

# **Network Layer Communication Performance in Network-on-Chips**

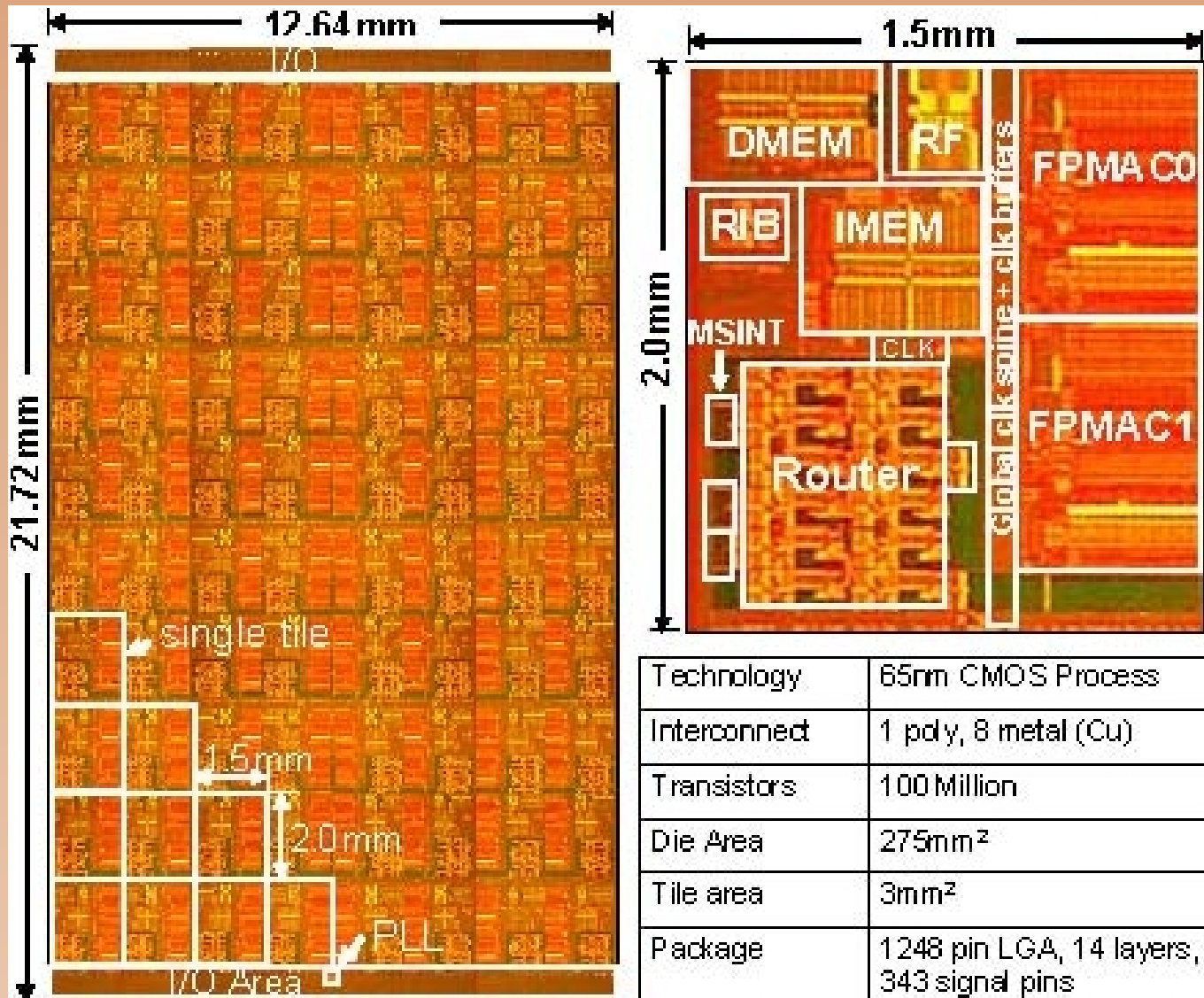
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# NoC Architecture Space



- 20 - 100 nodes (2D) / 1000 nodes (3D)
- Homogeneous - Heterogeneous
- Processors, memories, special processing units

# Network Layer Communication Performance in Network-on-Chips

Introduction

Communication Performance

Organizational Structure

Interconnection Topologies

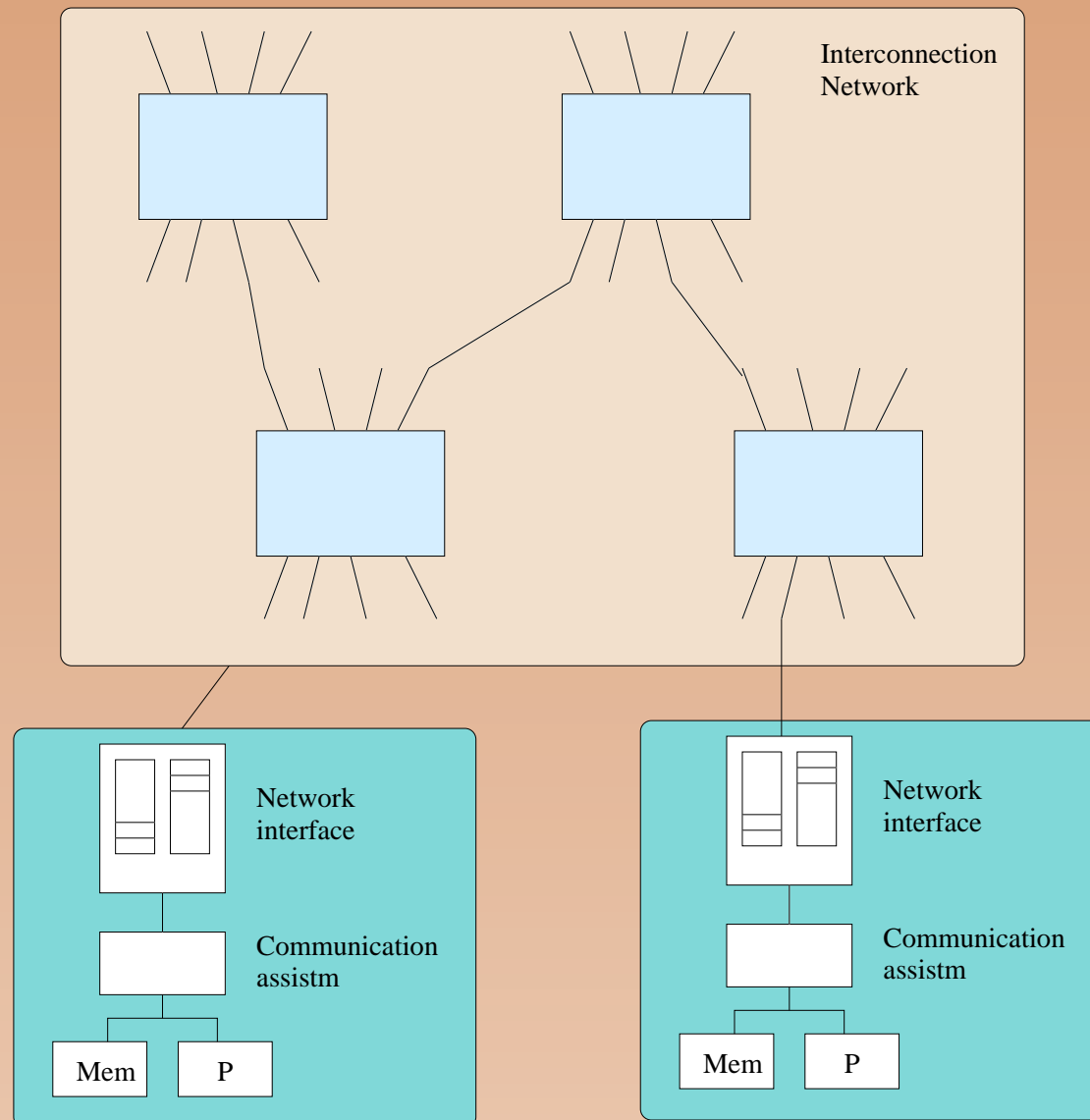
Trade-offs in Network Topology

Routing

Quality of Service



# Introduction



- **Topology:** How switches and nodes are connected
- **Routing algorithm:** determines the route from source to destination
- **Switching strategy:** how a message traverses the route
- **Flow control:** Schedules the traversal of the message over time

# Basic Definitions



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**Flit** is the basic flow control unit. A message consists of 1 or many flits.

**Phit** is the basic unit of the physical layer.



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**Indirect network** is a network with switches not connected to any node.

**Hop** is the basic communication action from node to switch or from switch to switch.

**Diameter** is the length of the maximum shortest path between any two nodes measured in hops.

**Routing distance** between two nodes is the number of hops on a route.

**Average distance** is the average of the routing distance over all pairs of nodes.



# Basic Switching Techniques

**Circuit Switching** A real or virtual circuit establishes a direct connection between source and destination.



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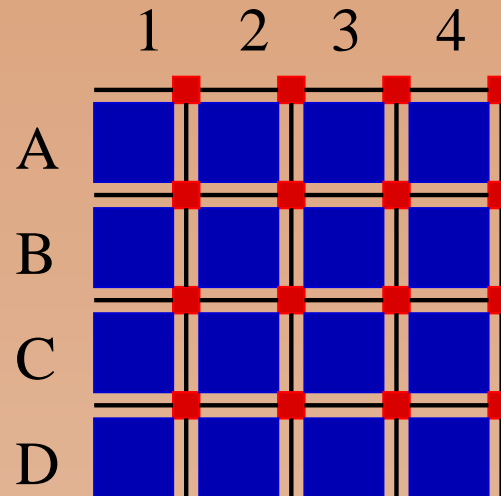
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**Wormhole Switching** is cut through switching and all flits are blocked on the spot when the header flit is blocked.



## Latency



$$\text{Time}(n) = \text{Admission} + \text{RoutingDelay} + \text{ContentionDelay}$$

**Admission** is the time it takes to emit the message into the network.

**RoutingDelay** is the delay for the route.

**ContentionDelay** is the delay of a message due to contention.



## Routing Delay

Store and Forward:

$$T_{sf}(n, h) = h\left(\frac{n}{b} + \Delta\right)$$

$n$  ... message size in bits

$n_p$  ... size of message fragments in bits

$h$  ... number of hops

$b$  ... raw bandwidth of the channel

$\Delta$  ... switching delay per hop



## Routing Delay

Store and Forward:

$$T_{sf}(n, h) = h\left(\frac{n}{b} + \Delta\right)$$

Circuit Switching:

$$T_{cs}(n, h) = \frac{n}{b} + h\Delta$$

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Cut Through:

$$T_{ct}(n, h) = \frac{n}{b} + h\Delta$$

Store and Forward with  
fragmented packets:

$$T_{sf}(n, h, n_p) = \frac{n - n_p}{b} + h\left(\frac{n_p}{b} + \Delta\right)$$

$n$  ... message size in bits

$n_p$  ... size of message fragments in bits

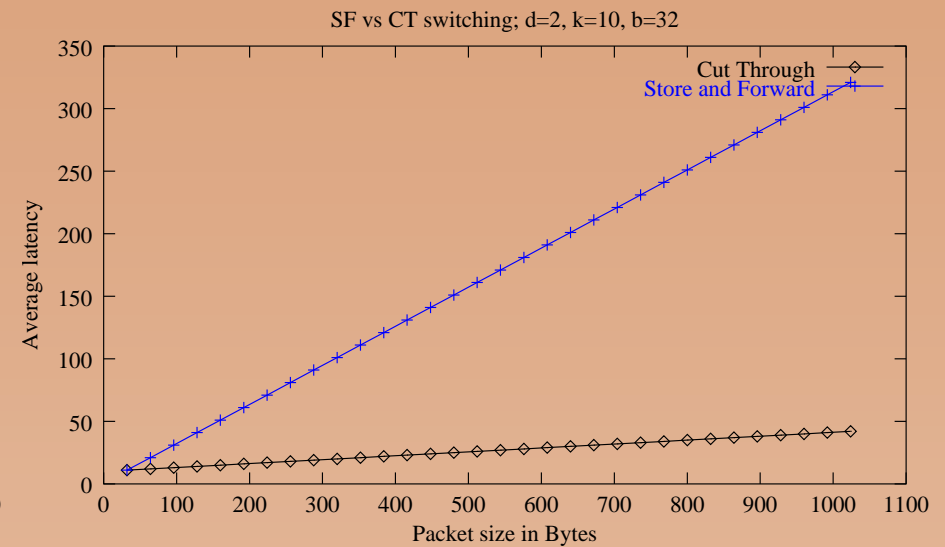
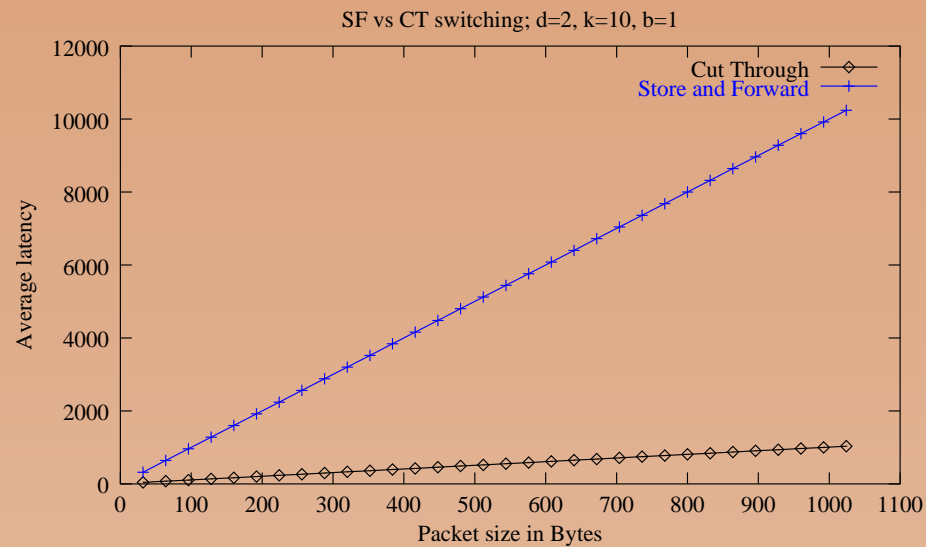
$h$  ... number of hops

$b$  ... raw bandwidth of the channel

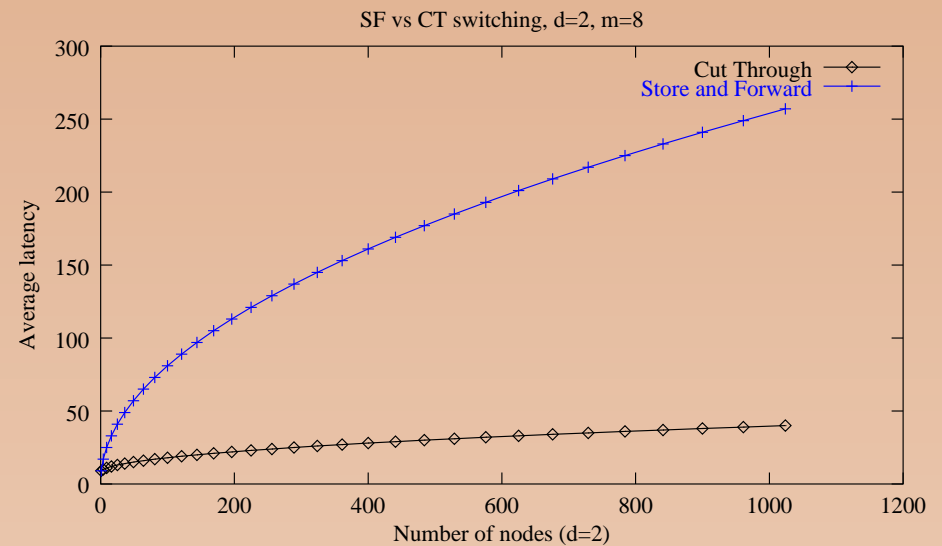
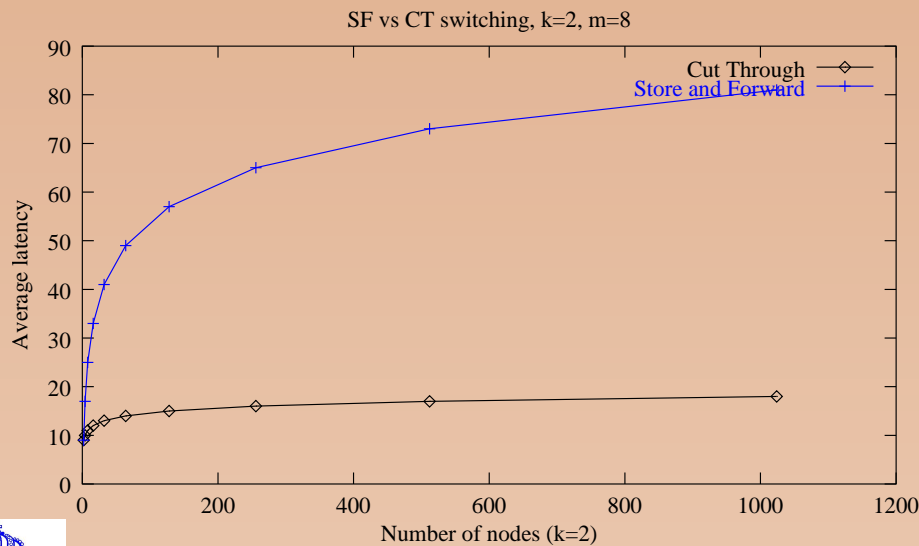
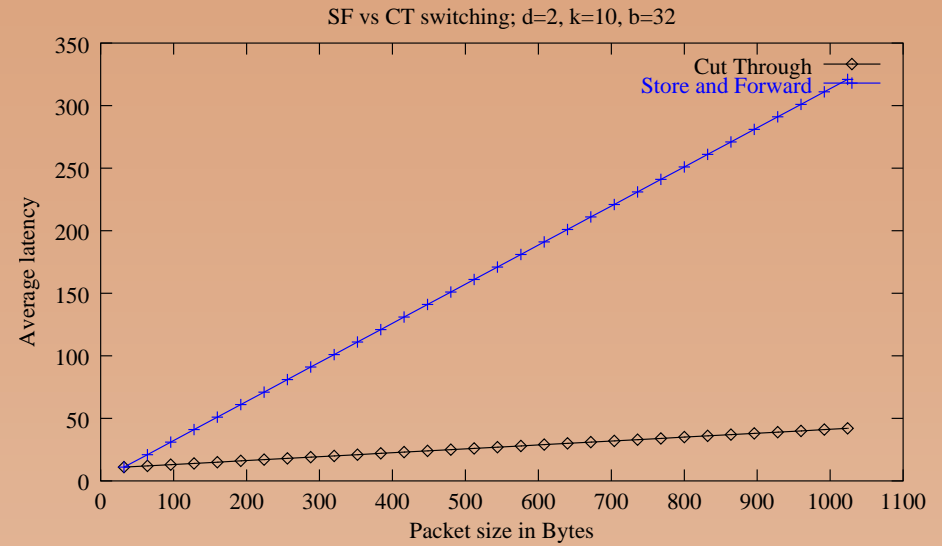
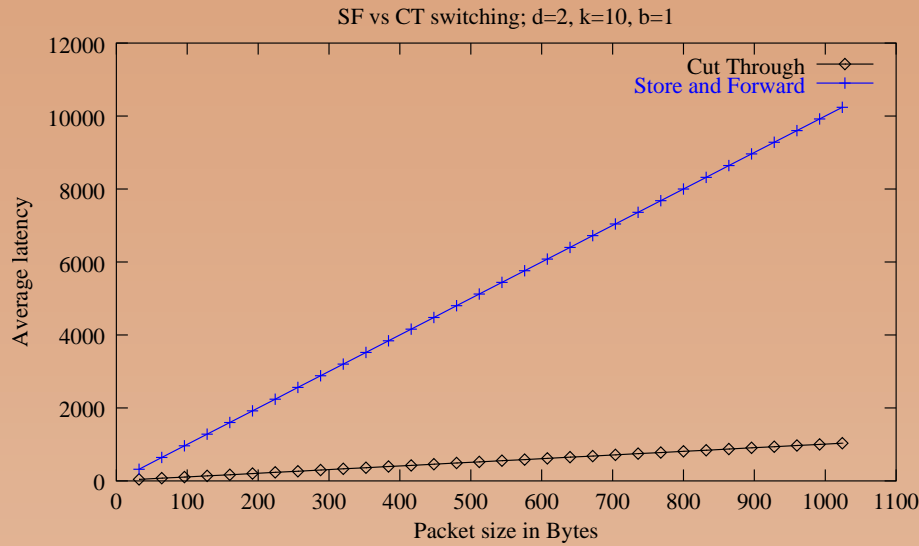
$\Delta$  ... switching delay per hop



# Routing Delay: Store and Forward vs Cut Through



# Routing Delay: Store and Forward vs Cut Through



## Local and Global Bandwidth

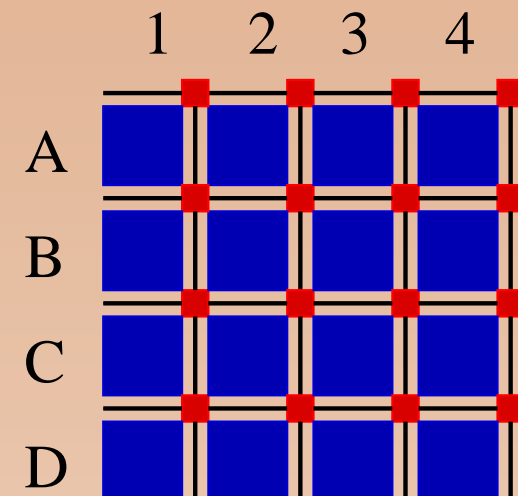
**Local bandwidth** =  $b$ [bits/second]  
**Total bandwidth** =  $Cb$ [bits/second] =  $Cw$ [bits/cycle] =  $C$ [phits/cycle]  
**Bisection bandwidth** ... minimum bandwidth to cut the net into two equal parts.

$b$  ... raw bandwidth of a link;  
 $n$  ... message size;  
 $n_E$  ... size of message envelope;  
 $w$  ... link bandwidth per cycle;

$\Delta$  ... switching time for each switch in cycles;  
 $w\Delta$  ... bandwidth lost during switching;  
 $C$  ... total number of channels;

For a  $k \times k$  mesh with bidirectional channels:

$$\begin{aligned} \text{Total bandwidth} &= (4k^2 - 4k)b \\ \text{Bisection bandwidth} &= 2kb \end{aligned}$$



## Link and Network Utilization

**total load on the network:**  $L = \frac{Nhl}{M}$  [phits/cycle]

**load per channel:**  $\rho = \frac{Nhl}{MC}$  [phits/cycle]  $\leq 1$

$M$  ... each host issues a packet every  $M$  cycles

$C$  ... number of channels

$N$  ... number of nodes

$h$  ... average routing distance

$l = n/w$  ... number of cycles a message occupies a channel

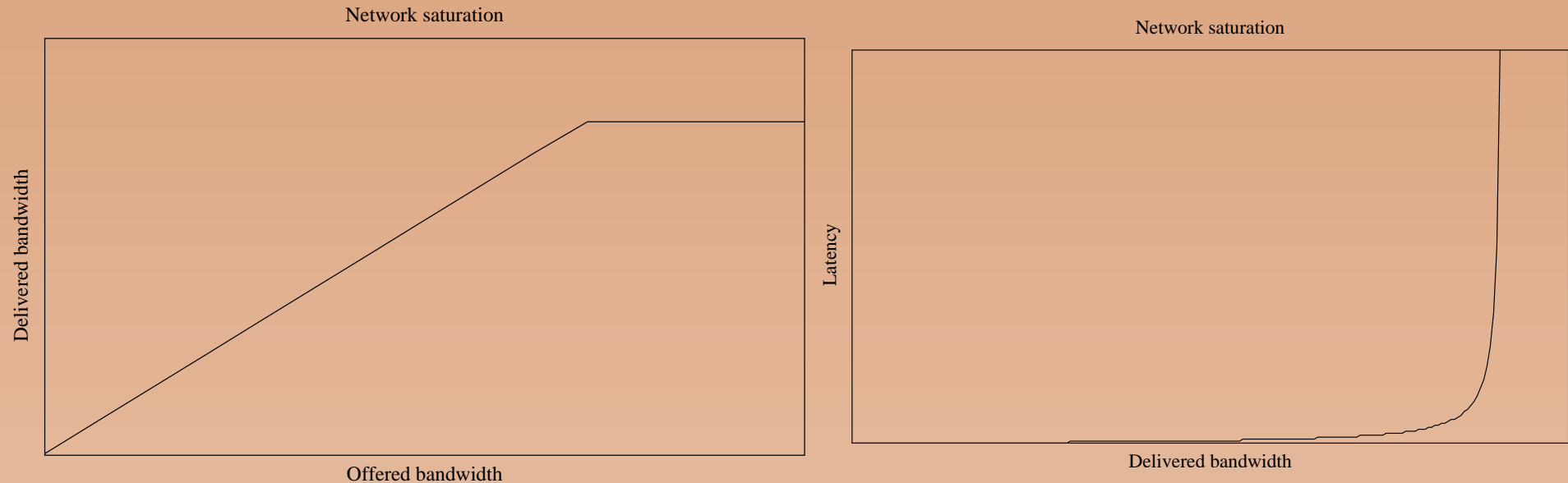
$n$  ... average message size

$w$  ... bandwidth per channel





# Network Saturation



Typical saturation points are between 40% and 70%.  
The saturation point depends on

- Traffic pattern
- Stochastic variations in traffic
- Routing algorithm



# Organizational Structure

- Link
- Switch
- Network Interface



# Link

**Short link** At any time there is only one data word on the link.

**Long link** Several data words can travel on the link simultaneously.

**Narrow link** Data and control information is multiplexed on the same wires.

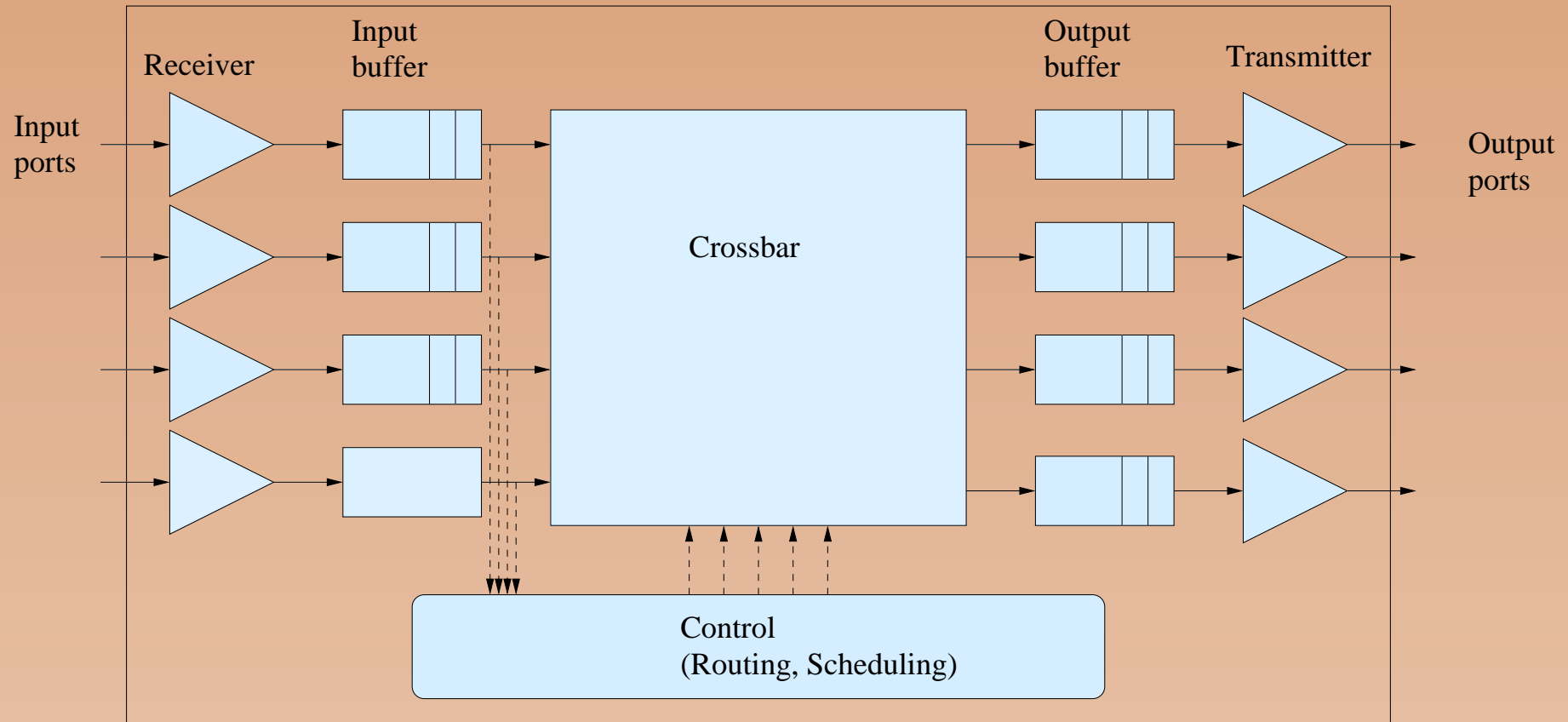
**Wide link** Data and control information is transmitted in parallel and simultaneously.

**Synchronous clocking** Both source and destination operate on the same clock.

**Asynchronous clocking** The clock is encoded in the transmitted data to allow the receiver to sample at the right time instance.



# Switch



# Switch Design Issues

**Degree:** number of inputs and outputs;

## Buffering

- Input buffers
- Output buffers
- Shared buffers

## Routing

- Source routing
- Deterministic routing
- Adaptive routing

## Output scheduling

## Deadlock handling

## Control flow



# Network Interface

- Admission protocol
- Reception obligations
- Buffering
- Assembling and disassembling of messages
- Routing
- Higher level services and protocols

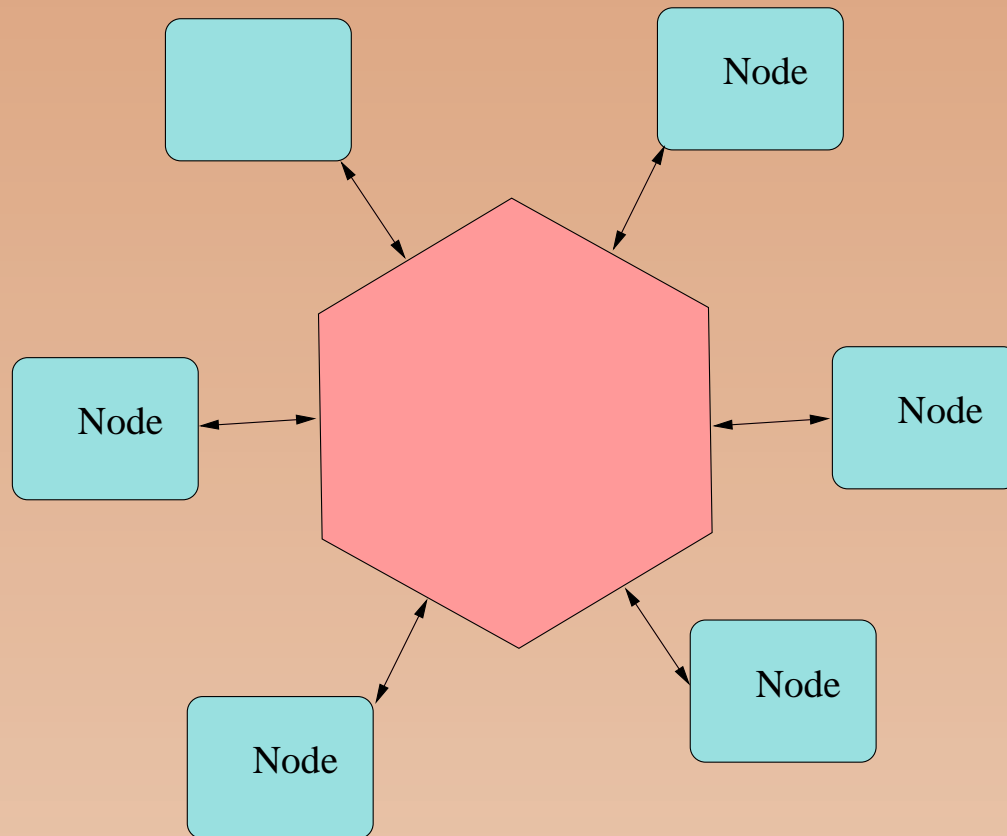


# Interconnection Topologies

- Fully connected networks
- Linear arrays and rings
- Multidimensional meshes and tori
- Trees
- Butterflies



# Fully Connected Networks

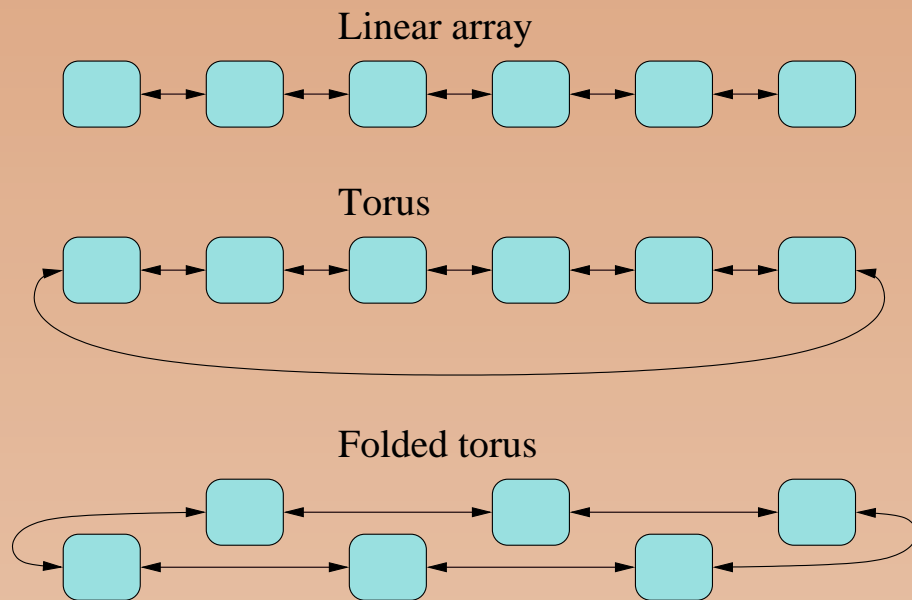


Bus: switch degree =  $N$   
 diameter = 1  
 distance = 1  
 network cost =  $O(N)$   
 total bandwidth =  $b$   
 bisection =  $b$   
 bandwidth

Crossbar: switch degree =  $N$   
 diameter = 1  
 distance = 1  
 network cost =  $O(N^2)$   
 total bandwidth =  $Nb$   
 bisection =  $Nb$   
 bandwidth



# Linear Arrays and Rings

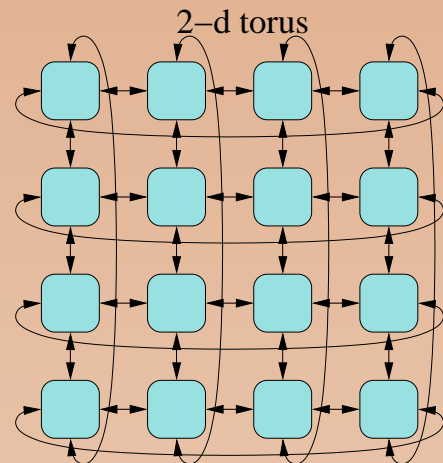
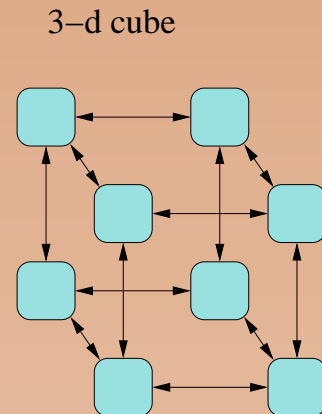
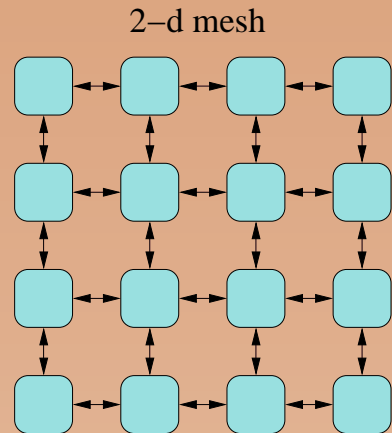


## Linear

|                      |        |             |
|----------------------|--------|-------------|
| array: switch degree | =      | 2           |
| diameter             | =      | $N - 1$     |
| distance             | $\sim$ | $2/3N$      |
| network cost         | =      | $O(N)$      |
| total bandwidth      | =      | $2(N - 1)b$ |
| bisection            | =      | $2b$        |
| bandwidth            |        |             |

|                      |        |        |
|----------------------|--------|--------|
| Torus: switch degree | =      | 2      |
| diameter             | =      | $N/2$  |
| distance             | $\sim$ | $1/3N$ |
| network cost         | =      | $O(N)$ |
| total bandwidth      | =      | $2Nb$  |
| bisection            | =      | $4b$   |
| bandwidth            |        |        |

## Multidimensional Meshes and Tori



**$k$ -ary  $d$ -cubes** are  $d$ -dimensional tori with unidirectional links and  $k$  nodes in each dimension:

$$\text{number of nodes } N = k^d$$

$$\text{switch degree} = d$$

$$\text{diameter} = d(k - 1)$$

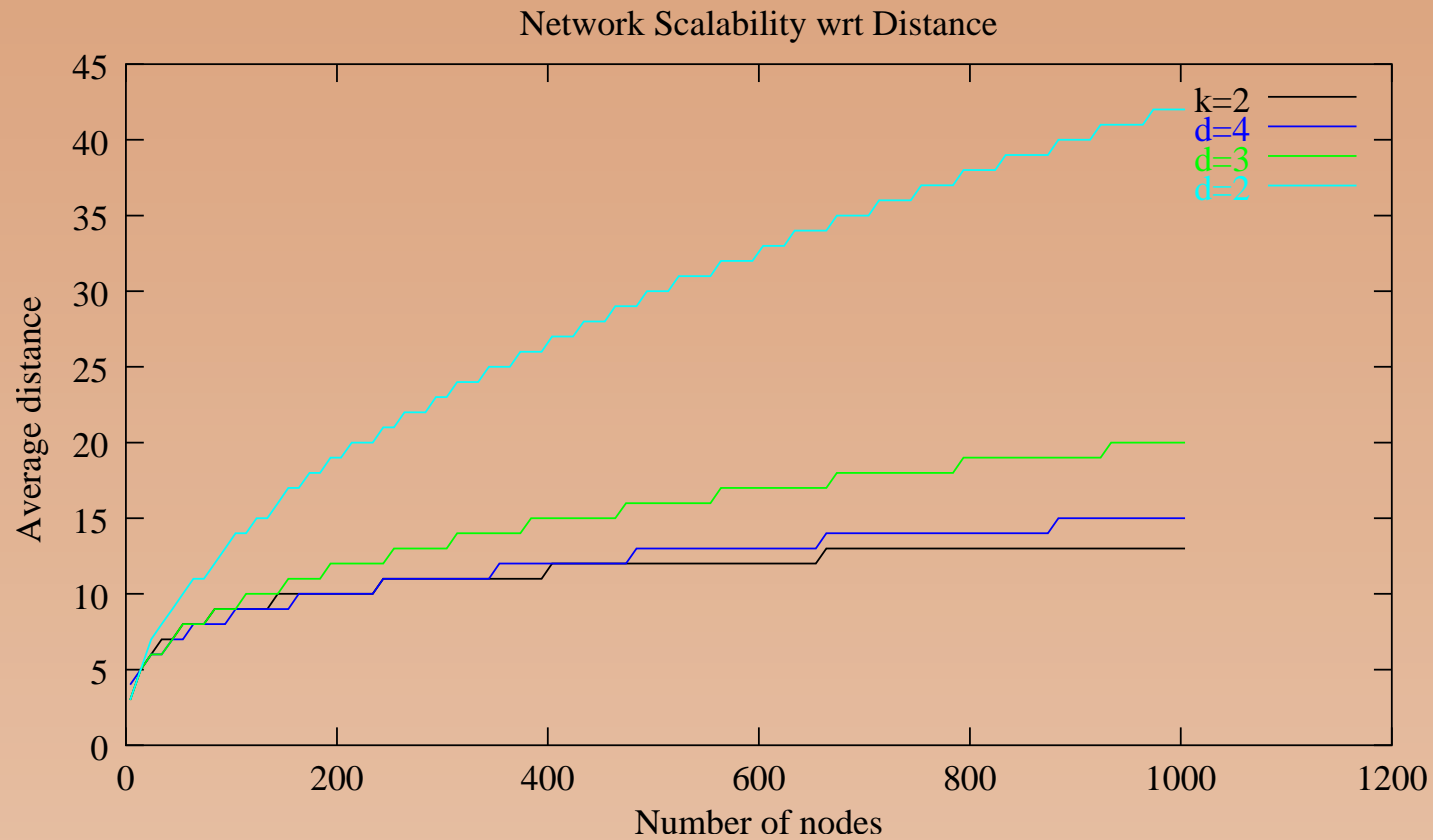
$$\text{distance} \sim d \frac{1}{2}(k - 1)$$

$$\text{network cost} = O(N)$$

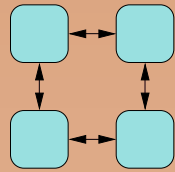
$$\text{total bandwidth} = 2Nb$$

$$\text{bisection bandwidth} = 2k^{(d-1)}b$$

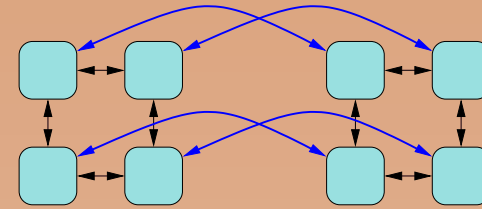
# Routing Distance in $k$ -ary $n$ -Cubes



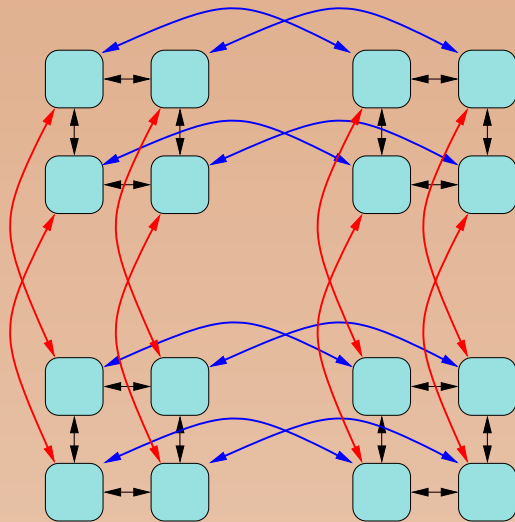
# Projecting High Dimensional Cubes



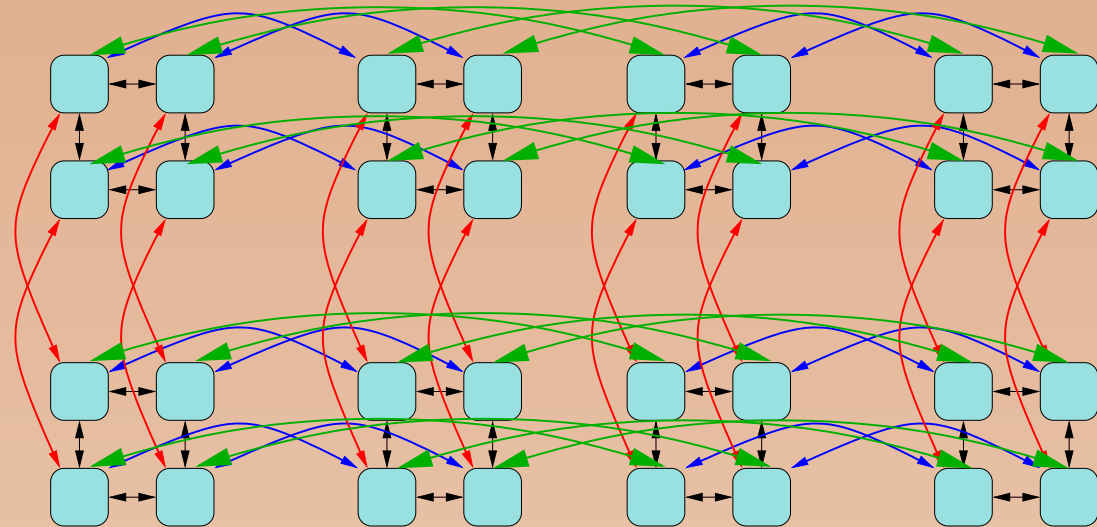
2-ary 2-cube



2-ary 3-cube



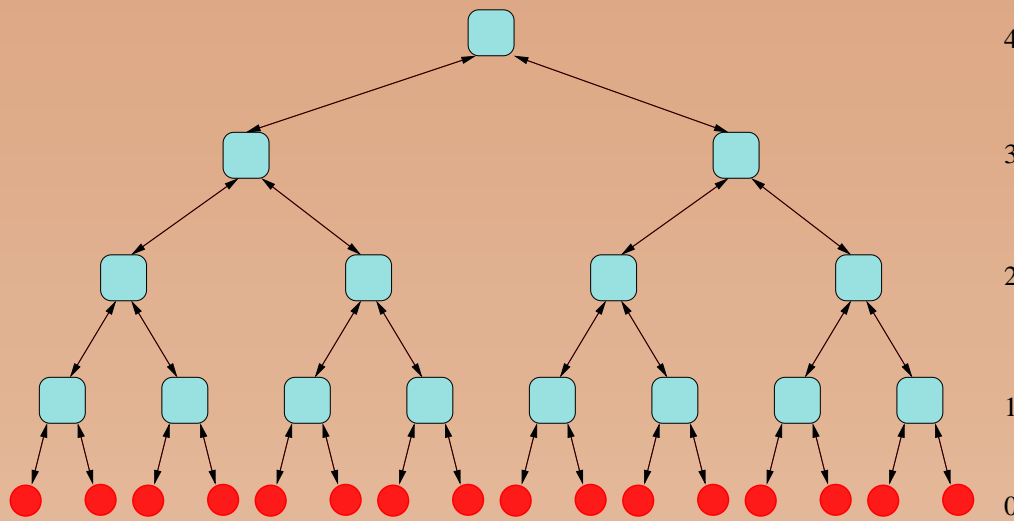
2-ary 4-cube



2-ary 5-cube

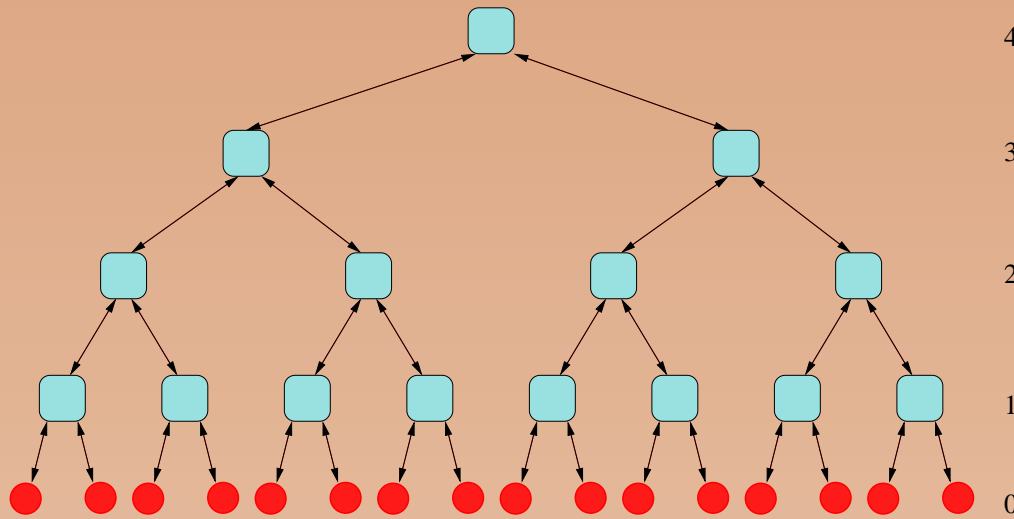


# Binary Trees



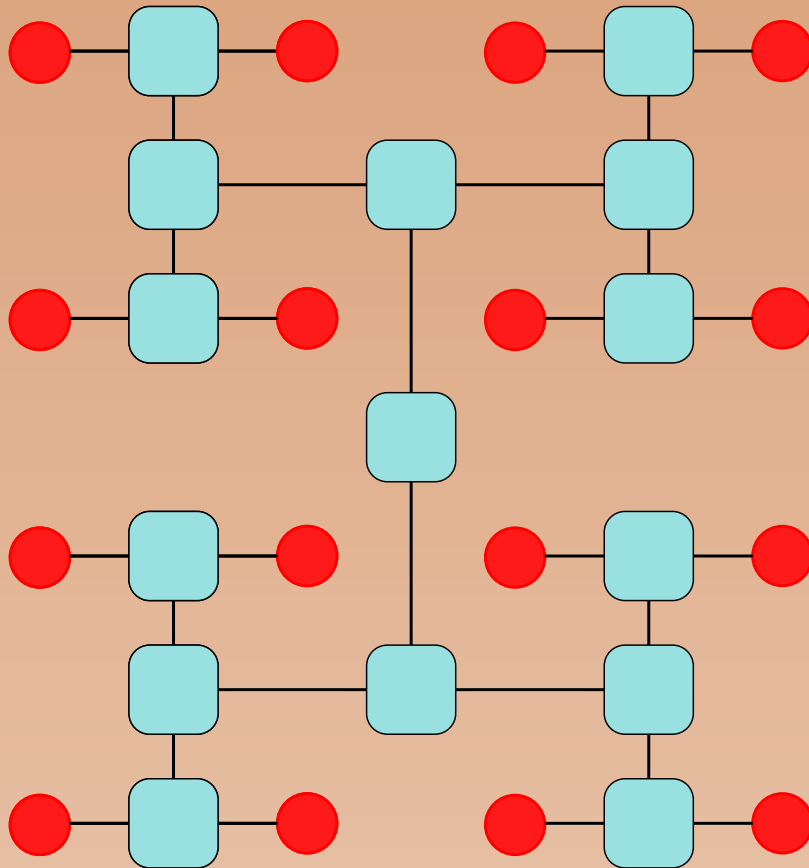
|   |                     |        |                     |
|---|---------------------|--------|---------------------|
| 4 | number of nodes $N$ | $=$    | $2^d$               |
| 3 | number of switches  | $=$    | $2^d - 1$           |
| 2 | switch degree       | $=$    | 3                   |
| 1 | diameter            | $=$    | $2d$                |
| 0 | distance            | $\sim$ | $d + 2$             |
|   | network cost        | $=$    | $O(N)$              |
|   | total bandwidth     | $=$    | $2 \cdot 2(N - 1)b$ |
|   | bisection bandwidth | $=$    | $2b$                |

# $k$ -ary Trees



|   |                     |        |                     |
|---|---------------------|--------|---------------------|
| 4 | number of nodes $N$ | $=$    | $k^d$               |
| 3 | number of switches  | $\sim$ | $k^d$               |
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|   | network cost        | $=$    | $O(N)$              |
|   | total bandwidth     | $=$    | $2 \cdot 2(N - 1)b$ |
|   | bisection bandwidth | $=$    | $kb$                |

## Binary Tree Projection



- Efficient and regular 2-layout;
- Longest wires in resource width:

$$lW = 2^{\lfloor \frac{d-1}{2} \rfloor} - 1$$

|      |   |   |    |    |    |     |     |     |      |
|------|---|---|----|----|----|-----|-----|-----|------|
| $d$  | 2 | 3 | 4  | 5  | 6  | 7   | 8   | 9   | 10   |
| $N$  | 4 | 8 | 16 | 32 | 64 | 128 | 256 | 512 | 1024 |
| $lW$ | 0 | 1 | 1  | 2  | 2  | 4   | 4   | 8   | 8    |

## $k$ -ary $n$ -Cubes versus $k$ -ary Trees

$k$ -ary  $n$ -cubes:

|                     |        |                       |
|---------------------|--------|-----------------------|
| number of nodes $N$ | =      | $k^d$                 |
| switch degree       | =      | $d + 2$               |
| diameter            | =      | $d(k - 1)$            |
| distance            | $\sim$ | $d\frac{1}{2}(k - 1)$ |
| network cost        | =      | $O(N)$                |
| total bandwidth     | =      | $2Nb$                 |
| bisection bandwidth | =      | $2k^{(d-1)}b$         |

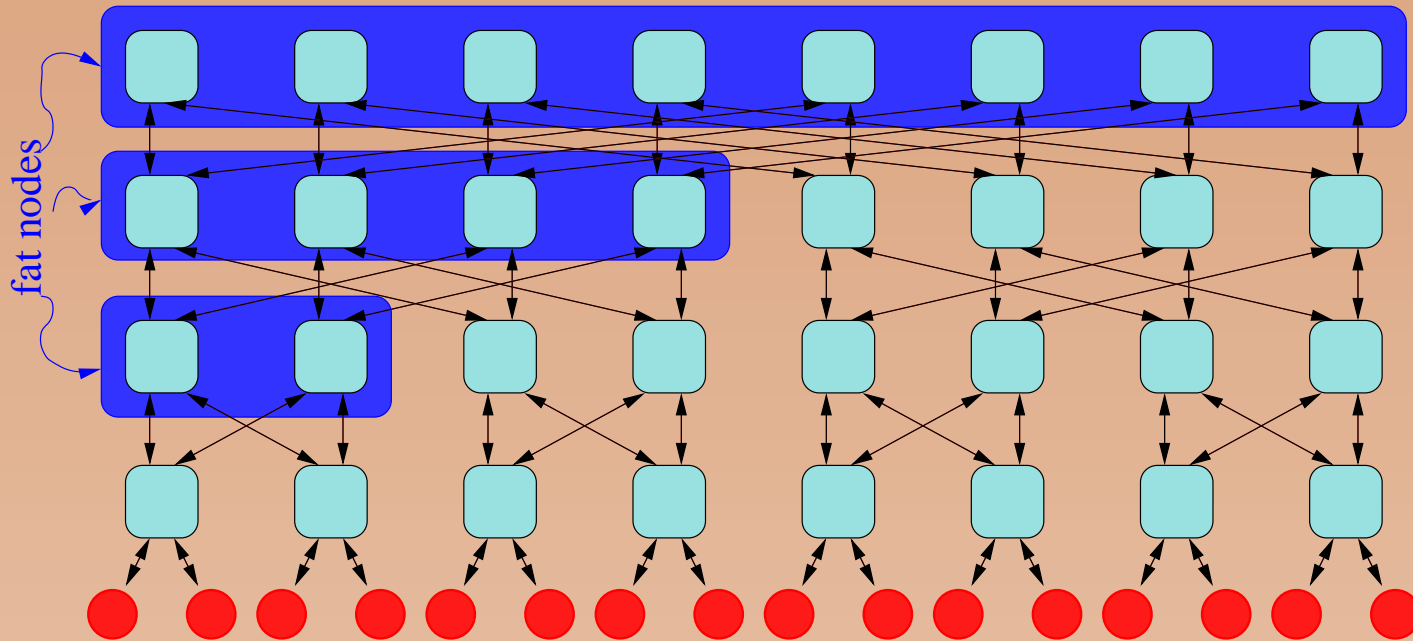
$k$ -ary trees:

|                     |        |                     |
|---------------------|--------|---------------------|
| number of nodes $N$ | =      | $k^d$               |
| number of switches  | $\sim$ | $k^d$               |
| switch degree       | =      | $k + 1$             |
| diameter            | =      | $2d$                |
| distance            | $\sim$ | $d + 2$             |
| network cost        | =      | $O(N)$              |
| total bandwidth     | =      | $2 \cdot 2(N - 1)b$ |
| bisection bandwidth | =      | $kb$                |





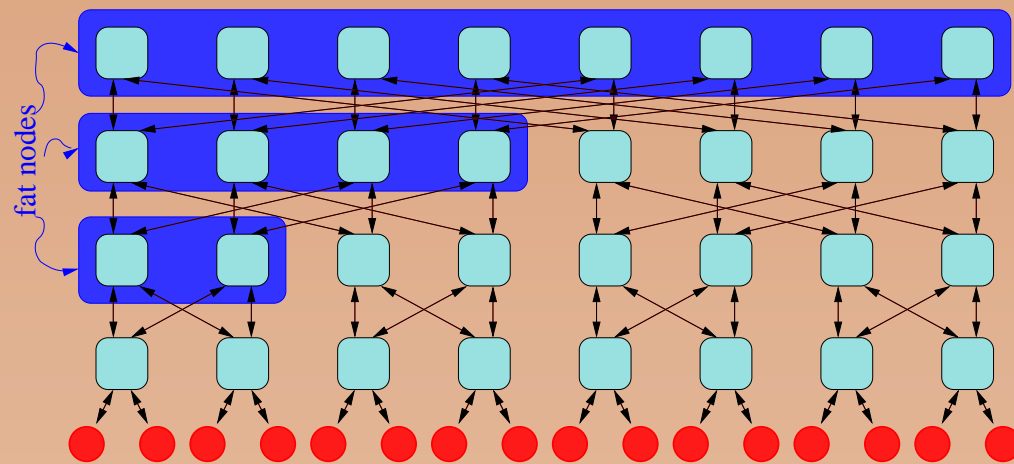
# Fat Trees



16-node 2-ary fat-tree



## $k$ -ary $n$ -dimensional Fat Tree Characteristics



16-node 2-ary fat-tree

|                     |        |             |
|---------------------|--------|-------------|
| number of nodes $N$ | $=$    | $k^d$       |
| number of switches  | $=$    | $k^{d-1}d$  |
| switch degree       | $=$    | $2k$        |
| diameter            | $=$    | $2d$        |
| distance            | $\sim$ | $d$         |
| network cost        | $=$    | $O(Nd)$     |
| total bandwidth     | $=$    | $2Ndb$      |
| bisection bandwidth | $=$    | $2k^{d-1}b$ |

## $k$ -ary $n$ -Cubes versus $k$ -ary $d$ -dimensional Fat Trees

$k$ -ary  $n$ -cubes:

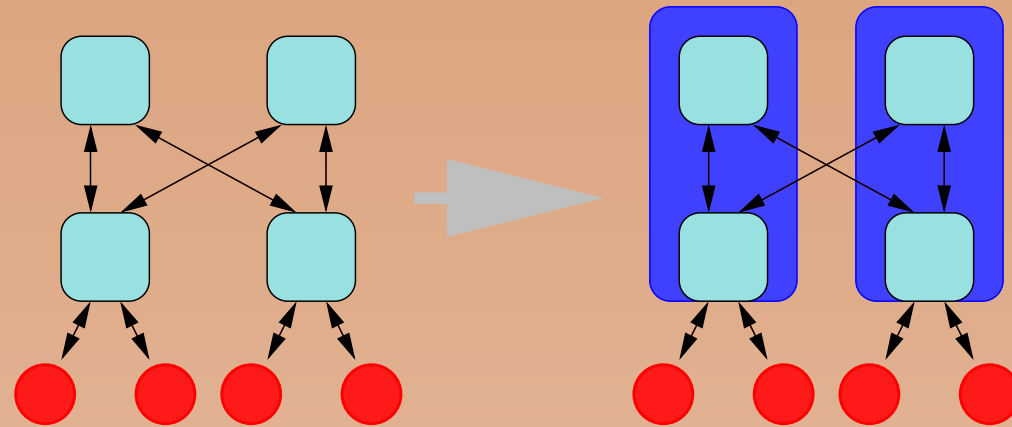
|                     |        |                       |
|---------------------|--------|-----------------------|
| number of nodes $N$ | =      | $k^d$                 |
| switch degree       | =      | $d$                   |
| diameter            | =      | $d(k - 1)$            |
| distance            | $\sim$ | $d\frac{1}{2}(k - 1)$ |
| network cost        | =      | $O(N)$                |
| total bandwidth     | =      | $2Nb$                 |
| bisection bandwidth | =      | $2k^{(d-1)}b$         |

$k$ -ary  $n$ -dimensional fat trees:

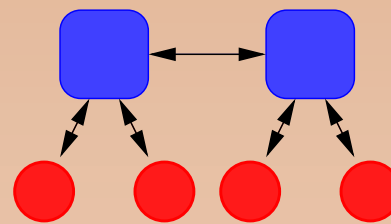
|                     |        |             |
|---------------------|--------|-------------|
| number of nodes $N$ | =      | $k^d$       |
| number of switches  | =      | $k^{d-1}d$  |
| switch degree       | =      | $2k$        |
| diameter            | =      | $2d$        |
| distance            | $\sim$ | $d$         |
| network cost        | =      | $O(Nd)$     |
| total bandwidth     | =      | $2Ndb$      |
| bisection bandwidth | =      | $2k^{d-1}b$ |



# Relation between Fat Tree and Hypercube



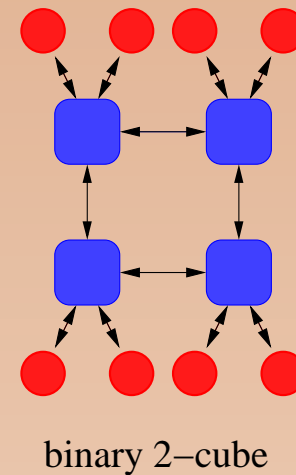
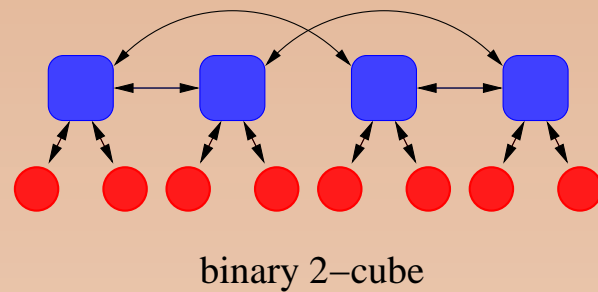
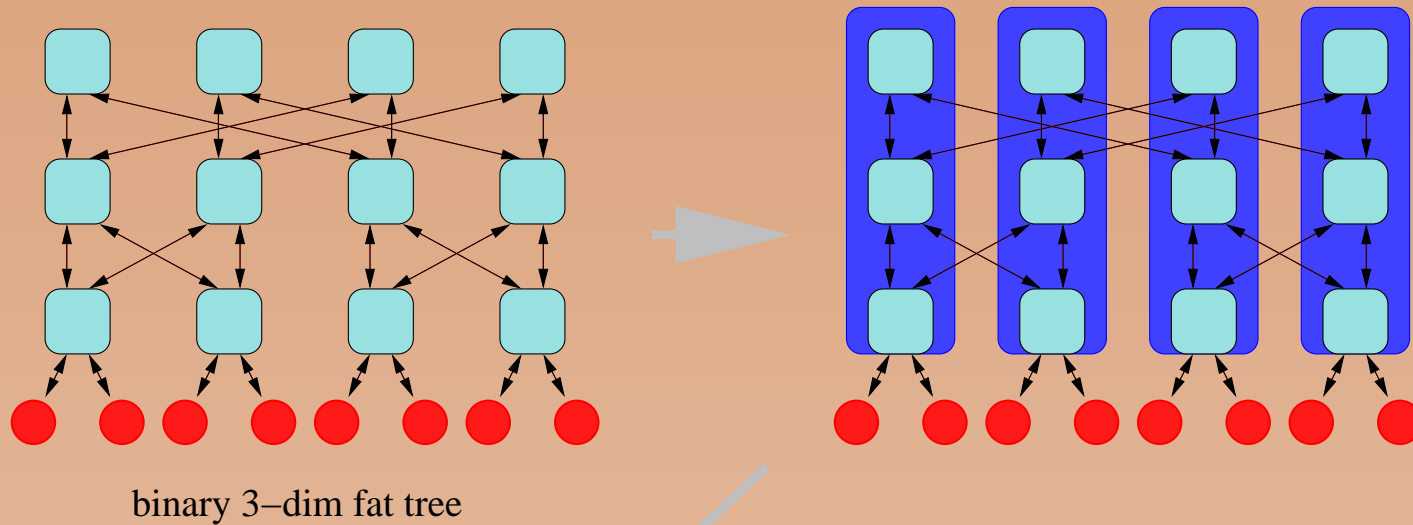
binary 2-dim fat tree



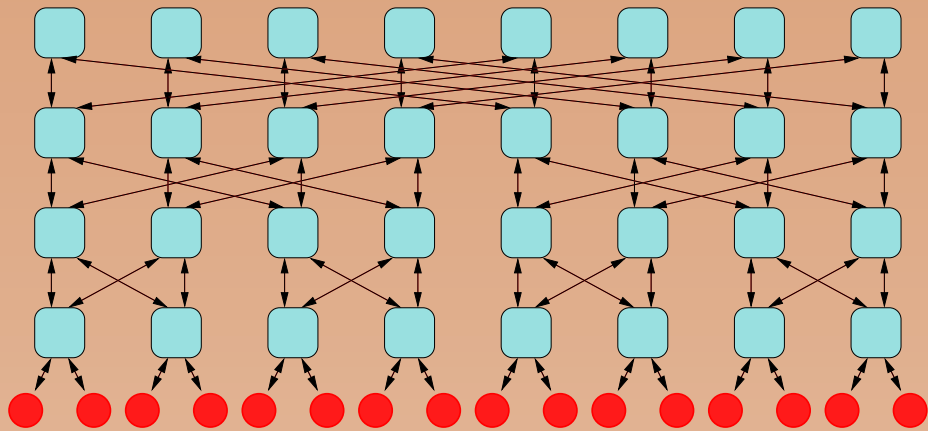
binary 1-cube



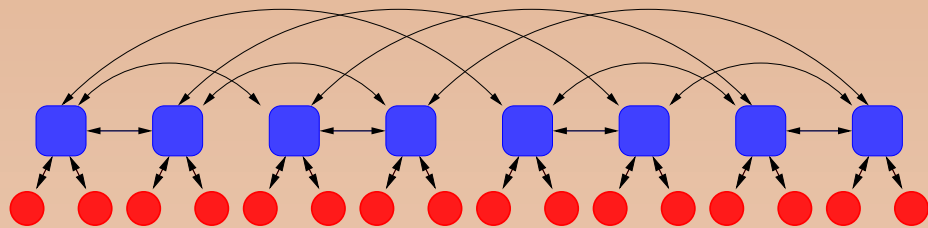
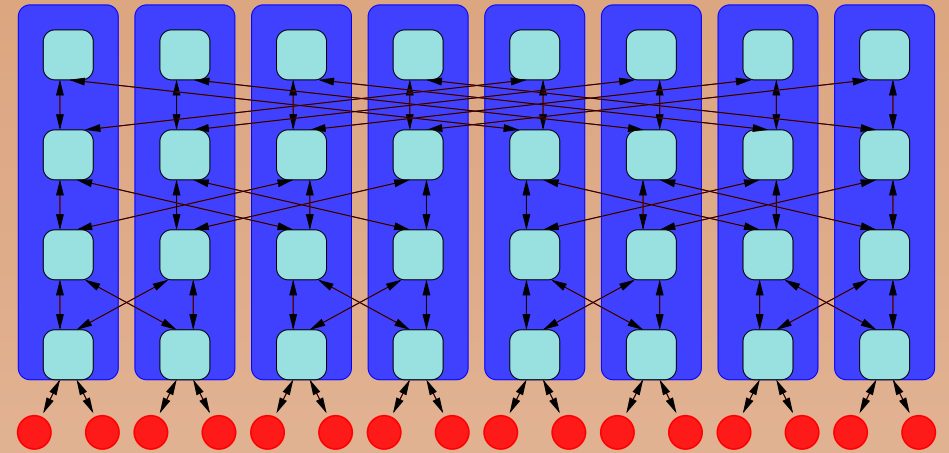
# Relation between Fat Tree and Hypercube - cont'd



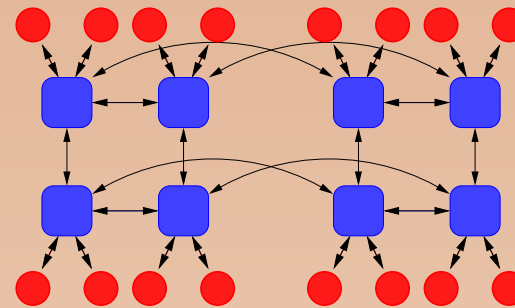
# Relation between Fat Tree and Hypercube - cont'd



binary 4-dim fat tree



binary 3-cube



binary 3-cube



# Trade-offs in Topology Design for the $k$ -ary $n$ -Cube

- Unloaded Latency
- Latency under Load

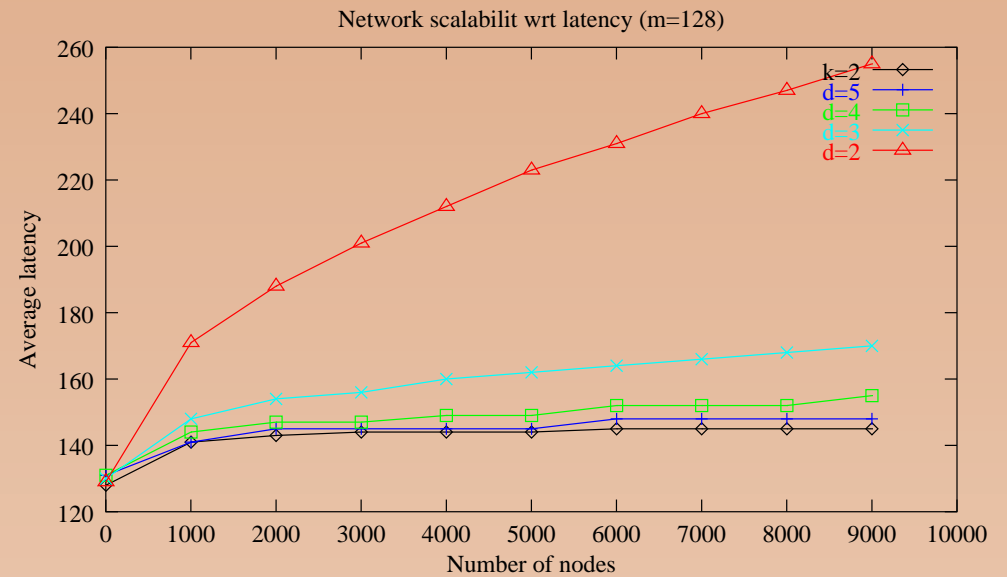
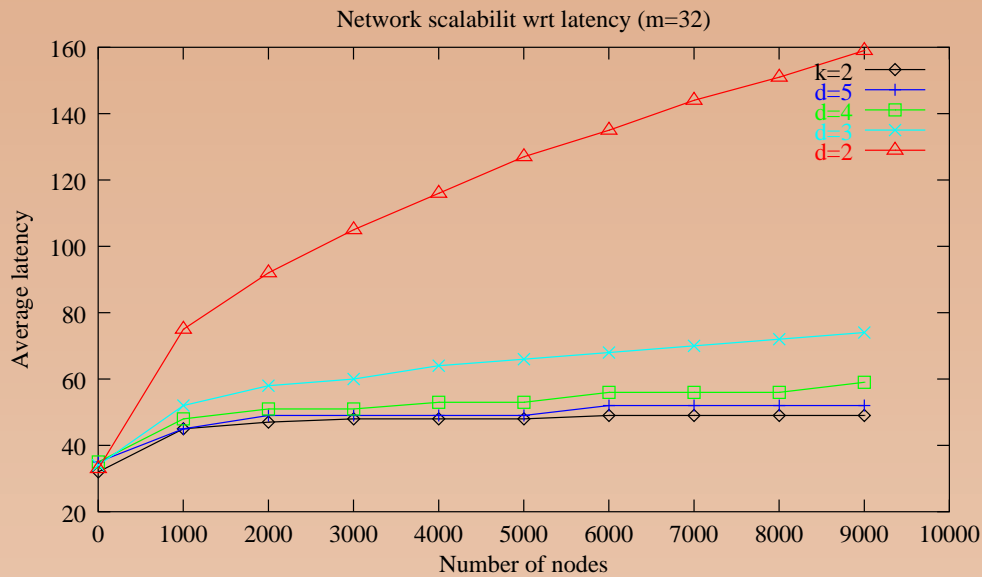


# Network Scaling for Unloaded Latency

$$\text{Latency}(n) = \text{Admission} + \text{RoutingDelay} + \text{ContentionDelay}$$

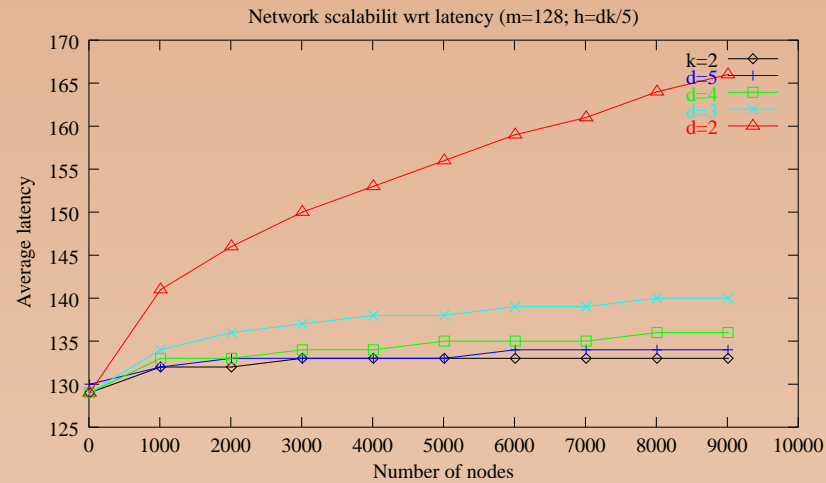
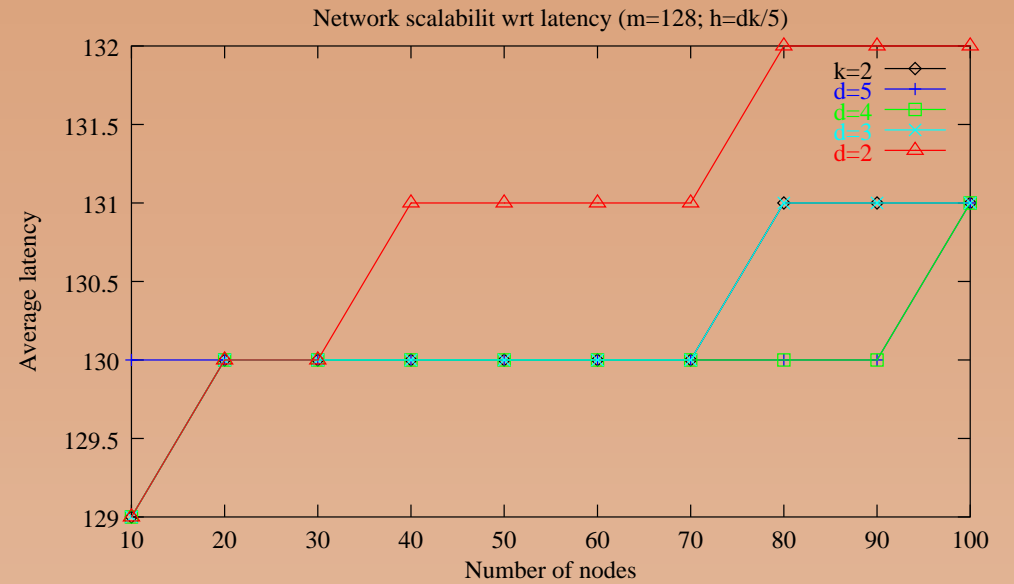
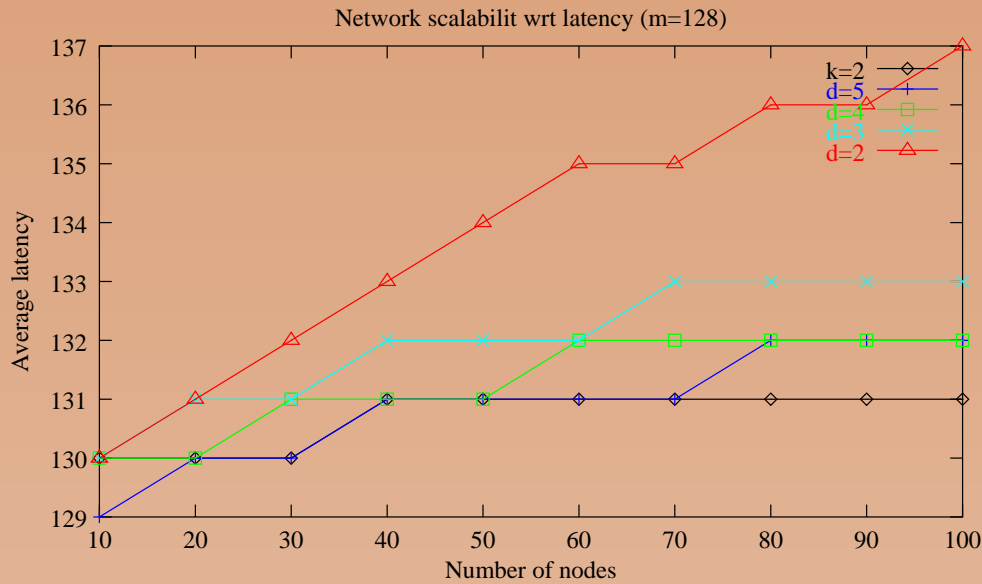
$$\text{RoutingDelay } T_{ct}(n, h) = \frac{n}{b} + h\Delta$$

$$\text{RoutingDistance } h = \frac{1}{2}d(k - 1)$$



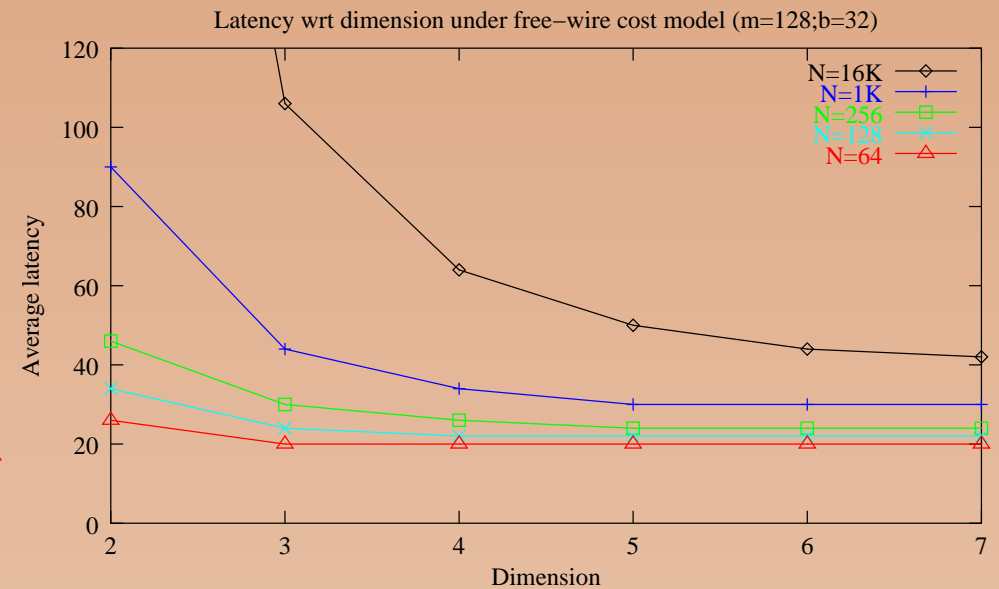
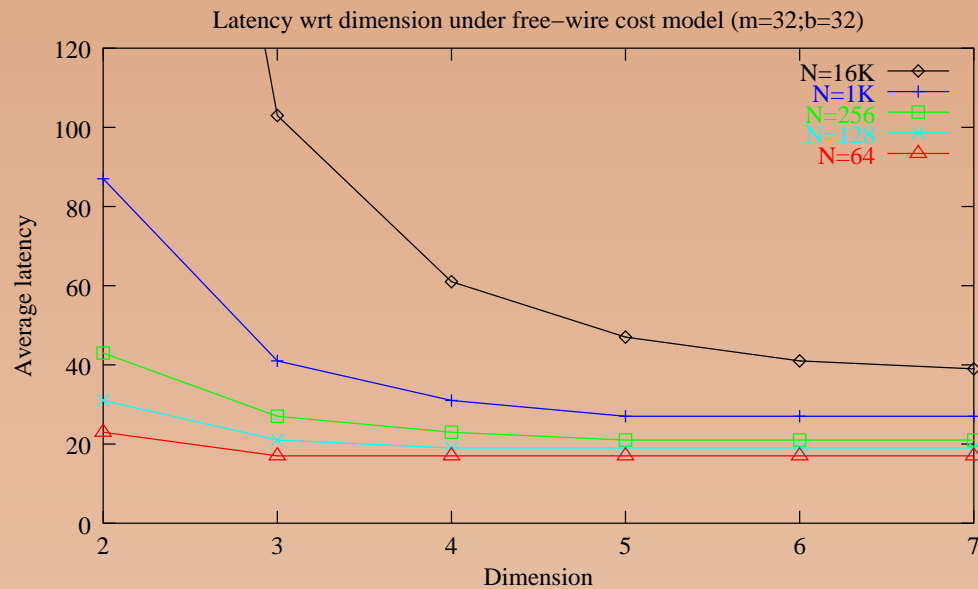


# Unloaded Latency for Small Networks and Local Traffic



# Unloaded Latency under a Free-Wire Cost Model

**Free-wire** cost model: Wires are free and can be added without penalty.

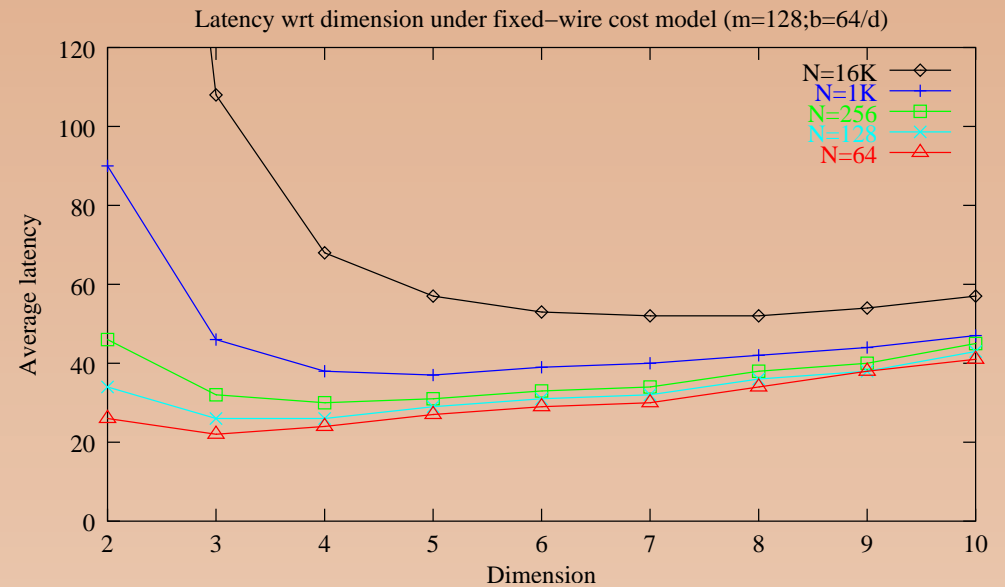
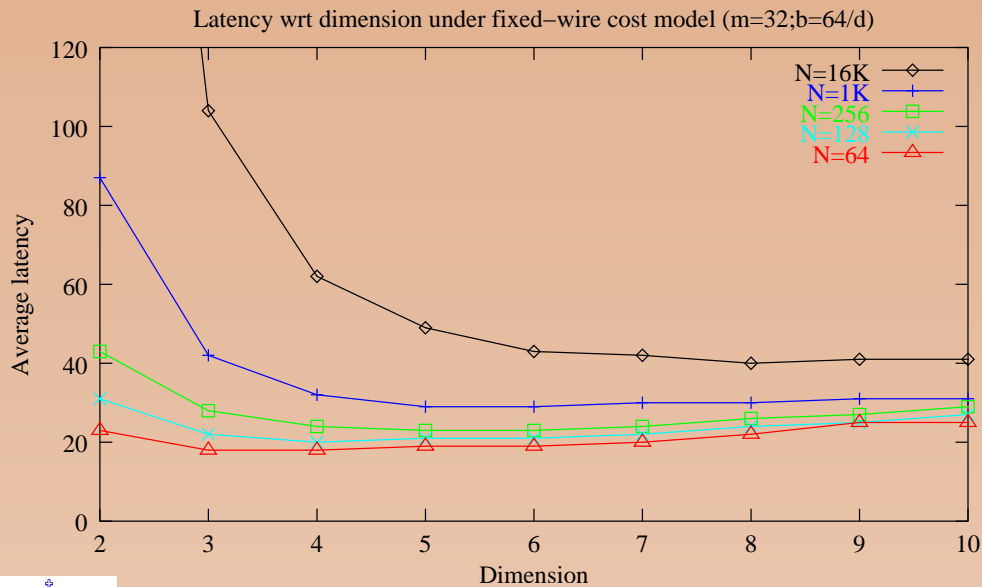


# Unloaded Latency under a Fixed-Wire Cost Models

**Fixed-wire** cost model: The number of wires is constant per node:

128 wires per node:  $w(d) = \lfloor \frac{64}{d} \rfloor$ .

|        |    |    |    |    |    |   |   |   |    |
|--------|----|----|----|----|----|---|---|---|----|
| $d$    | 2  | 3  | 4  | 5  | 6  | 7 | 8 | 9 | 10 |
| $w(d)$ | 32 | 21 | 16 | 12 | 10 | 9 | 8 | 7 | 6  |



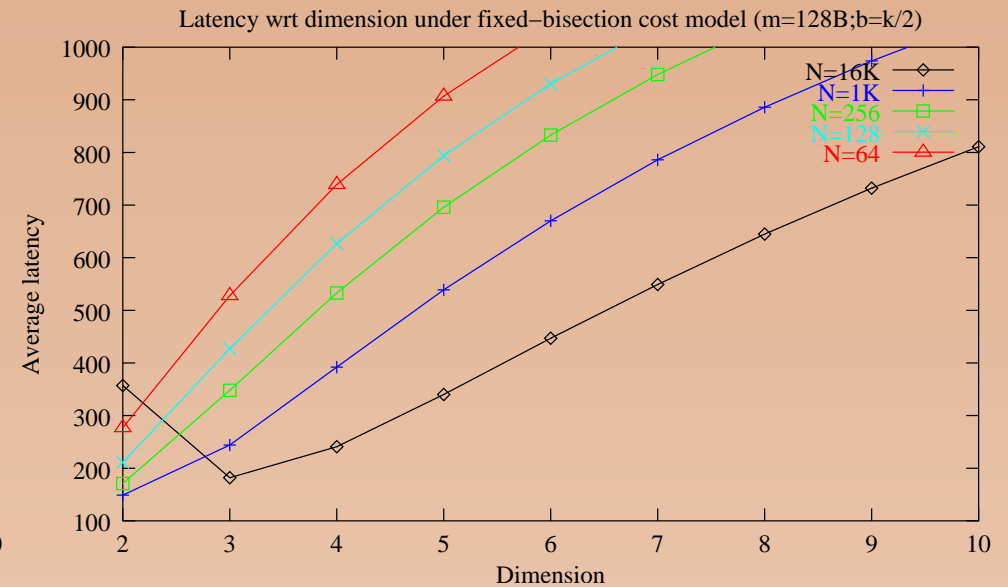
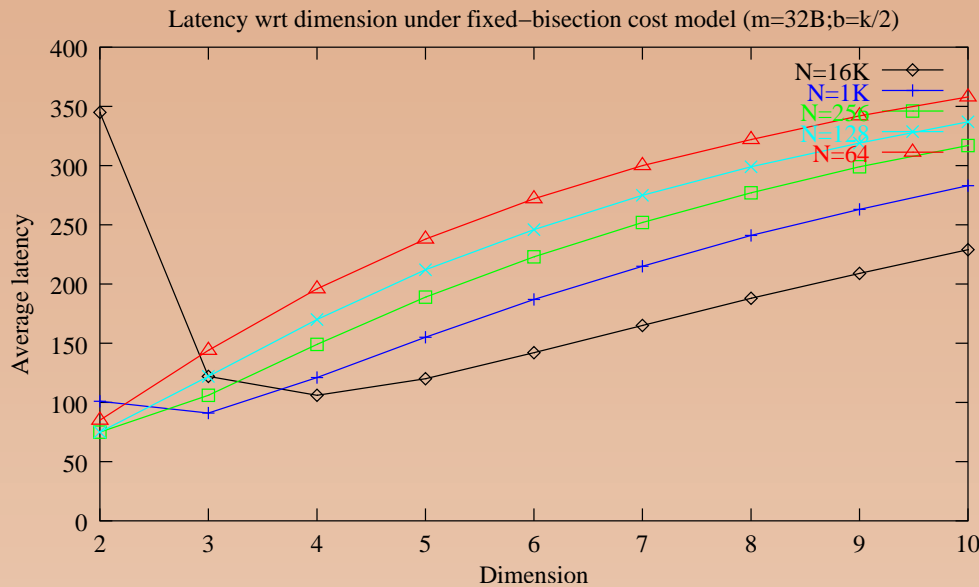
# Unloaded Latency under a Fixed-Bisection Cost Models

**Fixed-bisection** cost model: The number of wires across the bisection is constant:

bisection = 1024 wires:  $w(d) = \frac{k}{2} = \frac{d\sqrt{N}}{2}$ .

Example: N=1024:

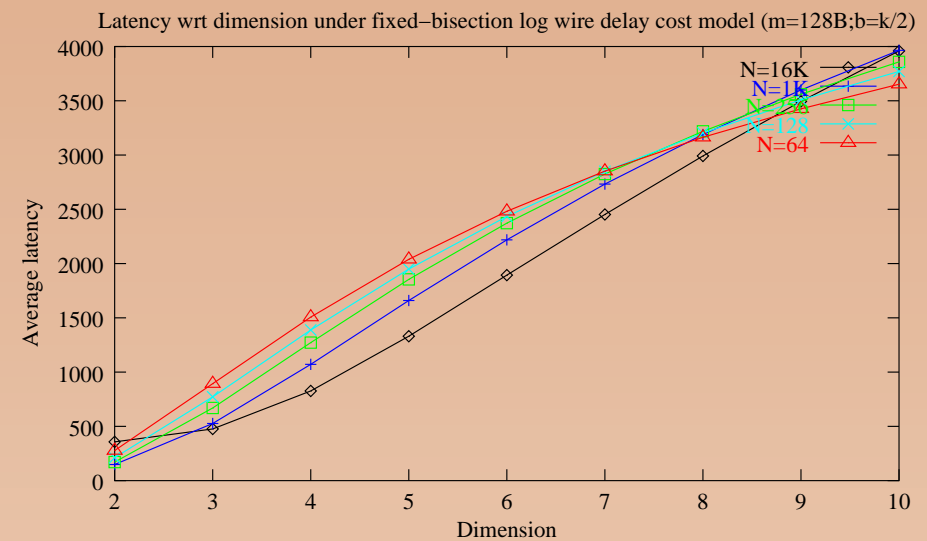
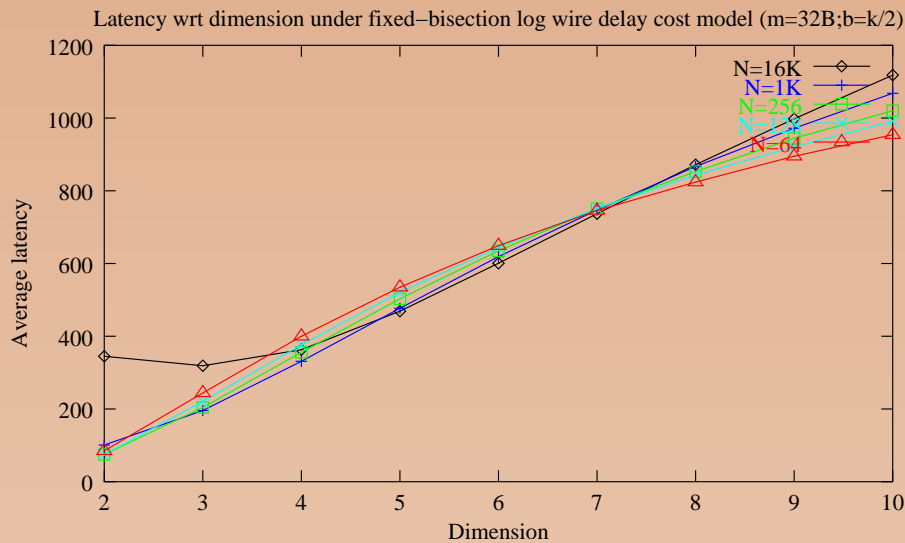
|        |     |    |   |   |   |   |   |   |    |
|--------|-----|----|---|---|---|---|---|---|----|
| $d$    | 2   | 3  | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| $w(d)$ | 512 | 16 | 5 | 3 | 2 | 2 | 1 | 1 | 1  |



# Unloaded Latency under a Logarithmic Wire Delay Cost Models

**Fixed-bisection Logarithmic Wire Delay** cost model: The number of wires across the bisection is constant and the delay on wires increases logarithmically with the length [Dally, 1990]:  
 Length of long wires:  $l = k^{\frac{n}{2}-1}$

$$T_c \propto 1 + \log l = 1 + \left(\frac{d}{2} - 1\right) \log k$$

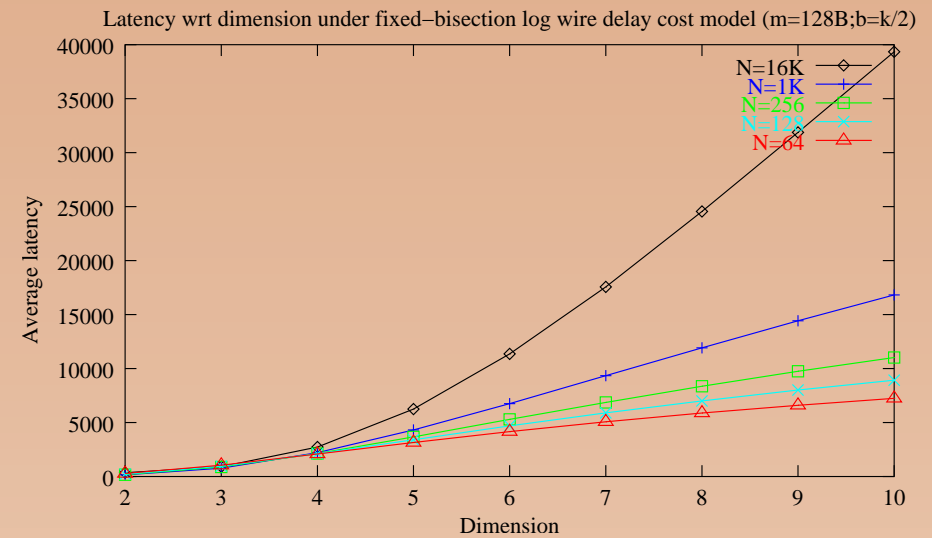
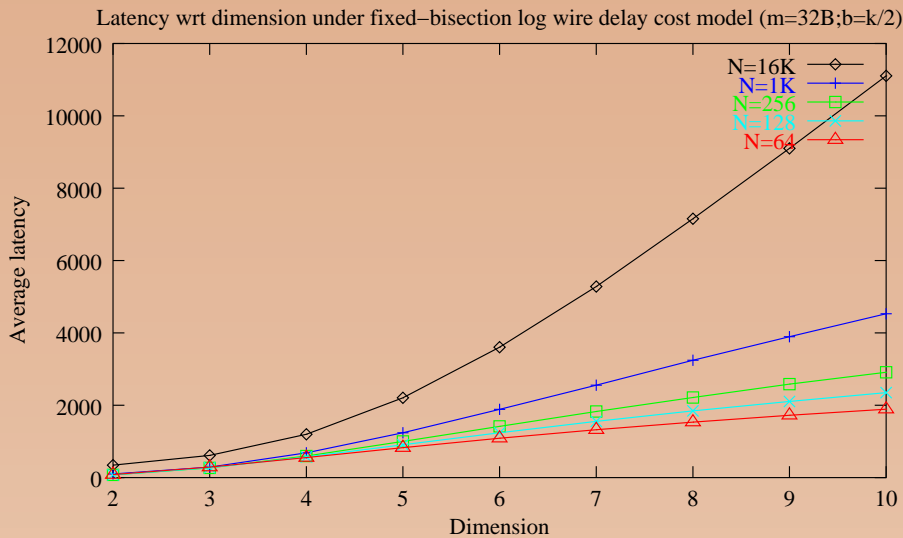


# Unloaded Latency under a Linear Wire Delay Cost Models

**Fixed-bisection Linear Wire Delay** cost model: The number of wires across the bisection is constant and the delay on wires increases linearly with the length [Dally, 1990]:

Length of long wires:  $l = k^{\frac{n}{2}-1}$

$$T_c \propto l = k^{\frac{d}{2}-1}$$



# Latency under Load

Assumptions [Agarwal, 1991]:

- $k$ -ary  $n$ -cubes
- random traffic
- dimension-order cut-through routing
- unbounded internal buffers (to ignore flow control and deadlock issues)



## Latency under Load - cont'd

$$\text{Latency}(n) = \text{Admission} + \text{RoutingDelay} + \text{ContentionDelay}$$

$$T(m, k, d, w, \rho) = \text{RoutingDelay} + \text{ContentionDelay}$$

$$T(m, k, d, w, \rho) = \frac{m}{w} + dh_k(\Delta + W(m, k, d, w, \rho))$$

$$W(m, k, d, w, \rho) = \frac{m}{w} \cdot \frac{\rho}{(1 - \rho)} \cdot \frac{h_k - 1}{h_k^2} \cdot \left(1 + \frac{1}{d}\right)$$

$$h = \frac{1}{2}d(k - 1)$$

$m$  ... message size

$w$  ... bitwidth of link

$\rho$  ... aggregate channel utilization

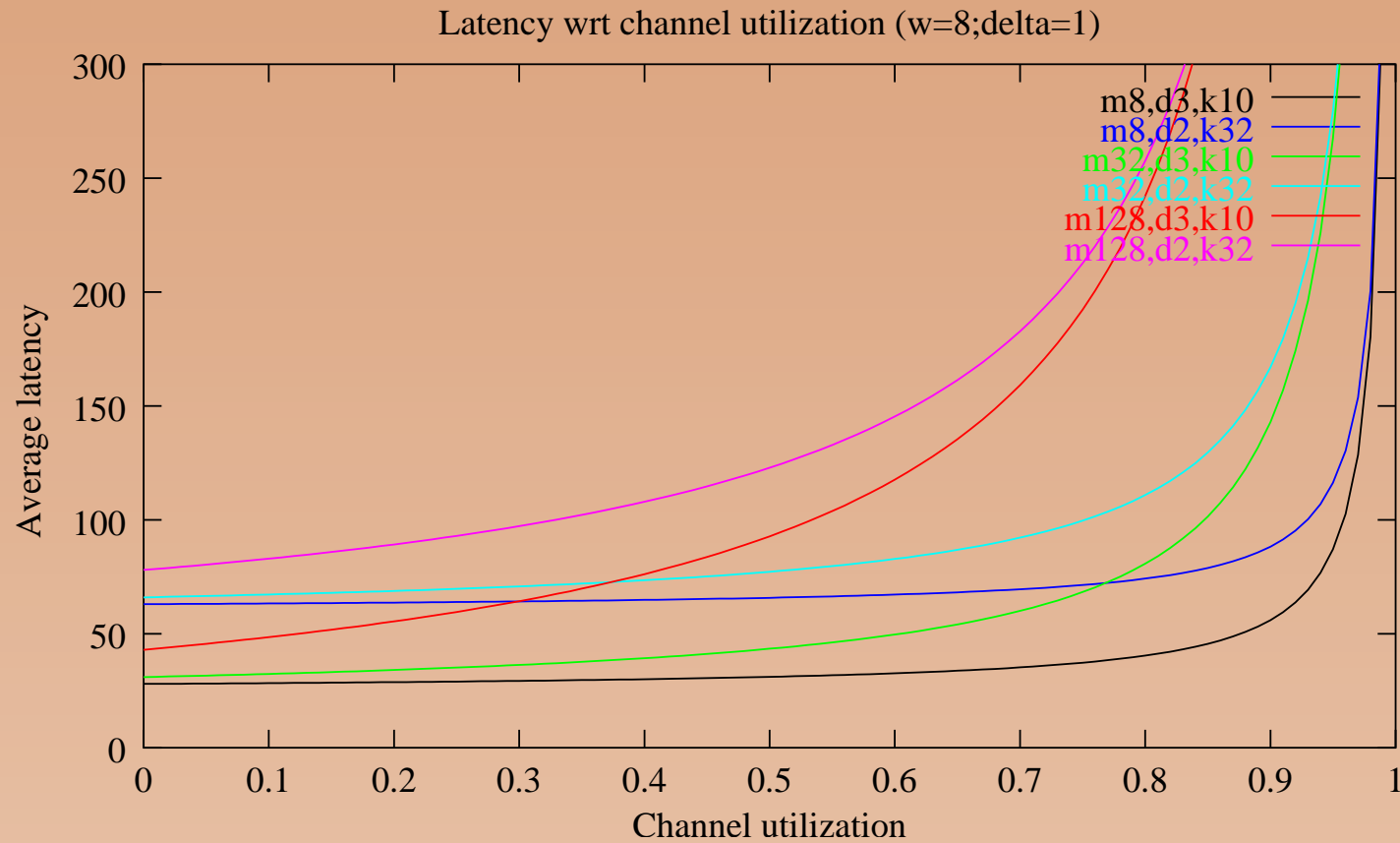
$h_k$  ... average distance in each dimension

$\Delta$  ... switching time in cycles





# Latency vs Channel Load



## Latency under Load for Hot Potato Routing

Assumptions [Jantsch 2006]:

- 2 dimensional mesh
- empirical model to be validated for each traffic pattern
- non-minimal deflection / hot potato routing
- no internal buffers
- single flit packets

$$\text{latency} = \frac{2}{3}k\Delta\delta \leq \frac{2}{3}k\Delta D_1(E)$$

- $\frac{2}{3}k$     ... average distance  
 $\Delta$     ... switching time in cycles  
 $\delta$     ... deflection factor  
 $E$     ... packet emission probability per node  
 $D_1(E)$  ... delay bound for 90% of packets under uniform traffic



# Quality of Service

- Best Effort (BE)
  - ★ Optimization of the average case
  - ★ Loose or non-existent worst case bounds
  - ★ Cost effective use of resources
- Guaranteed Service (GS)
  - ★ Maximum delay
  - ★ Minimum bandwidth
  - ★ Maximum Jitter
  - ★ Requires additional resources



## Regulated Flows

A Flow  $F$  is  $(\sigma, \rho)$  regulated if

$$F(b) - F(a) \leq \sigma + \rho(b - a)$$

for all time intervals  $[a, b]$ ,  $0 \leq a \leq b$  and where

$F(t) \dots$  the cumulative amount of traffic between 0 and  $t \geq 0$ .

$\sigma \geq 0$  is the burstiness constraint;

$\rho \geq 0$  is the maximum average rate;



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A Flow  $F$  is  $(\sigma, \rho)$  regulated if

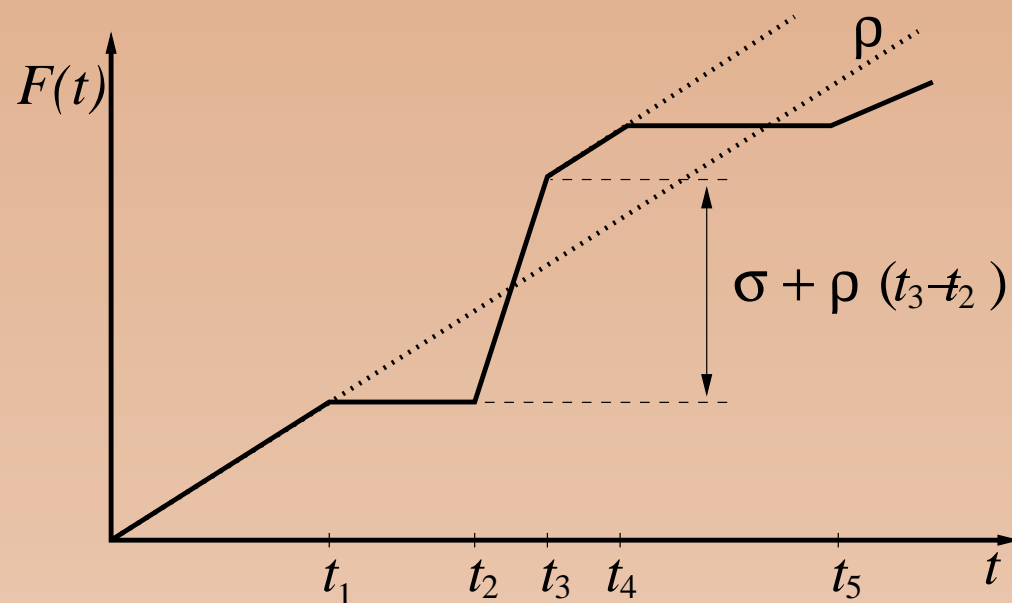
$$F(b) - F(a) \leq \sigma + \rho(b - a)$$

for all time intervals  $[a, b]$ ,  $0 \leq a \leq b$  and where

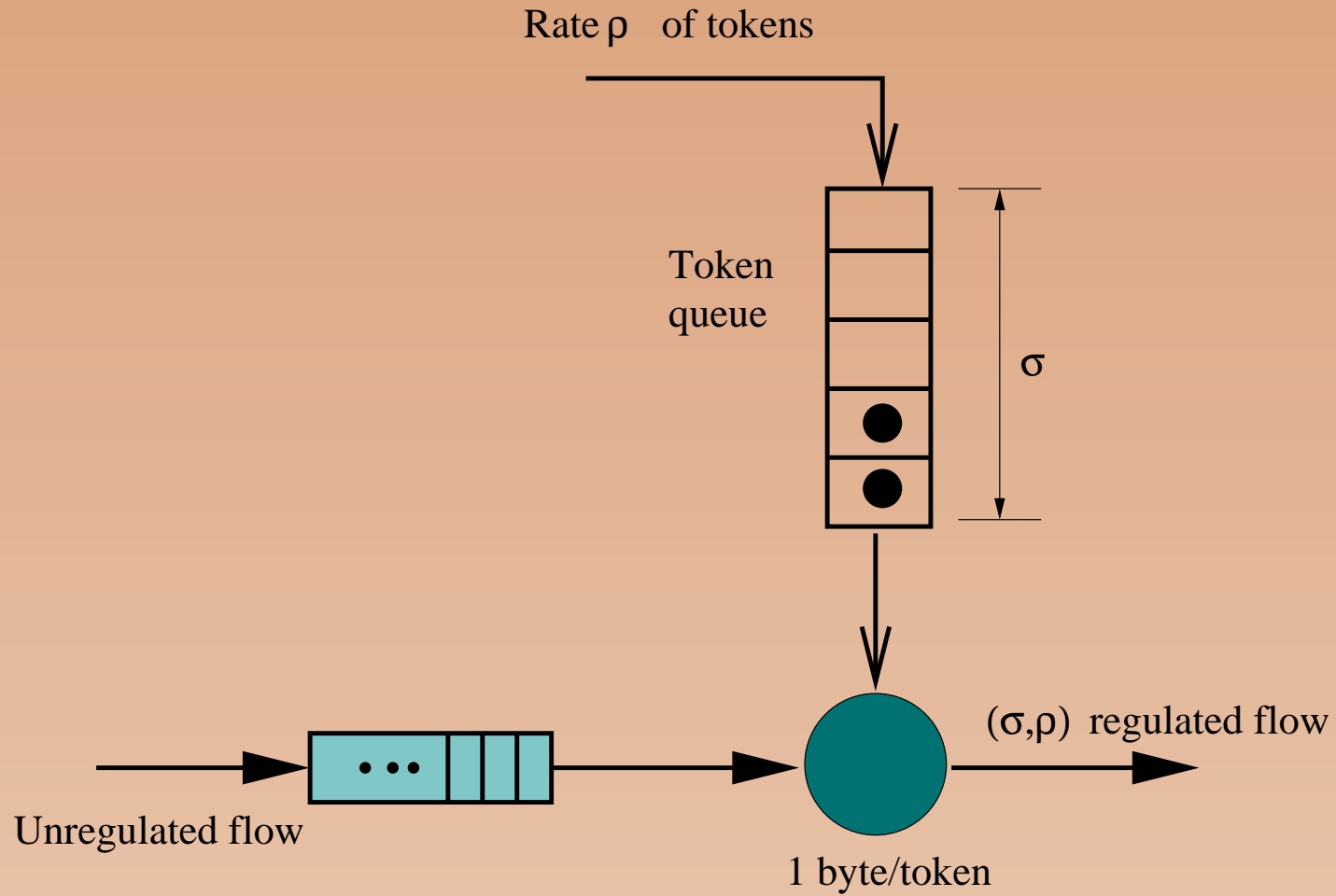
$F(t) \dots$  the cumulative amount of traffic between 0 and  $t \geq 0$ .

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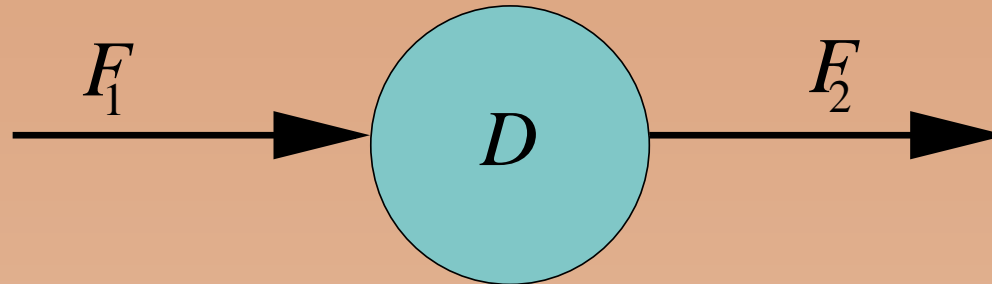
$\rho \geq 0$  is the maximum average rate;



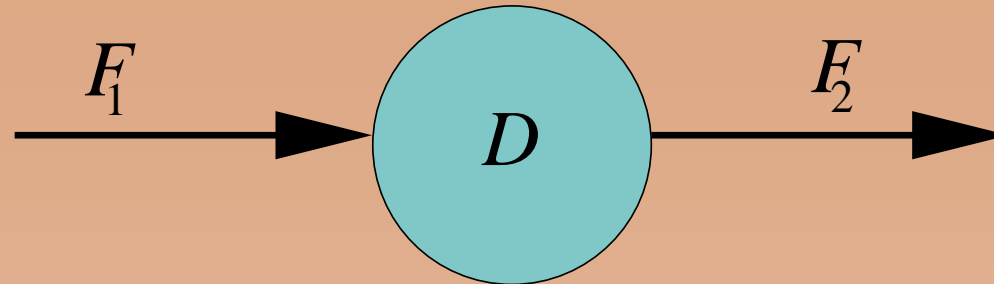
# $(\sigma, \rho)$ Regulator



## Regulated Flows - Delay Element



## Regulated Flows - Delay Element

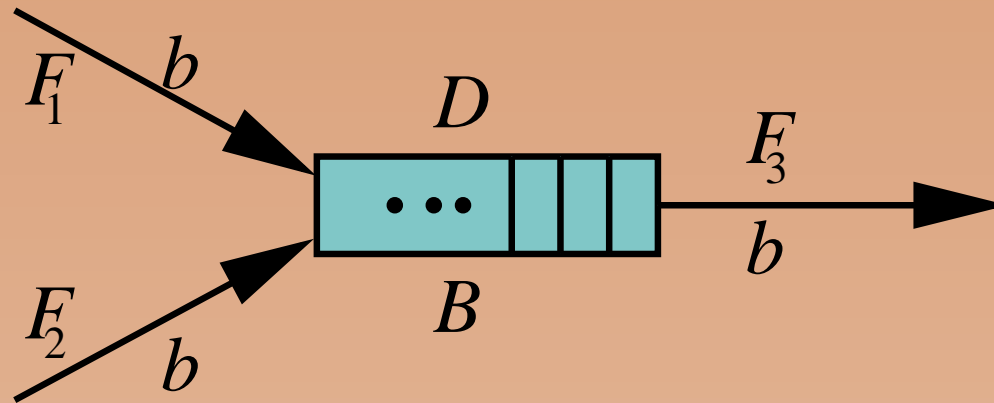


$$F_1 \sim (\sigma, \rho)$$

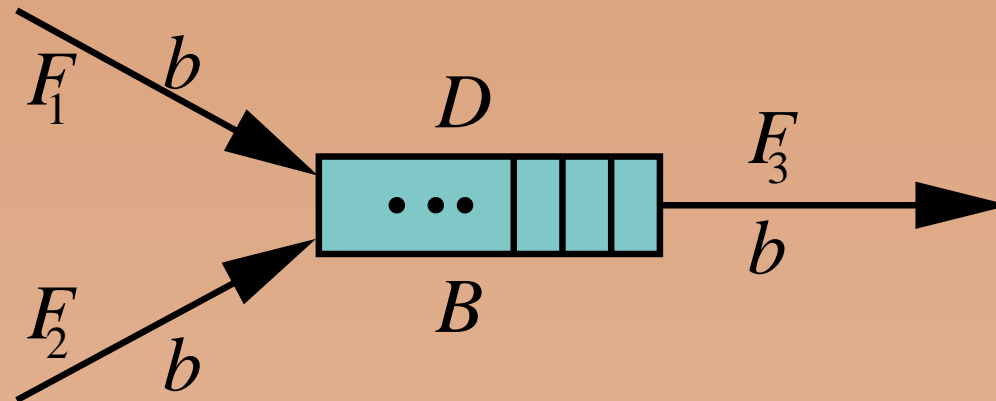
$$F_2 \sim (\sigma + \rho D, \rho)$$



## Regulated Flows - Work Conserving Multiplexer



## Regulated Flows - Work Conserving Multiplexer



$$F_1 \sim (\sigma_1, \rho_1)$$

$$F_2 \sim (\sigma_2, \rho_2)$$

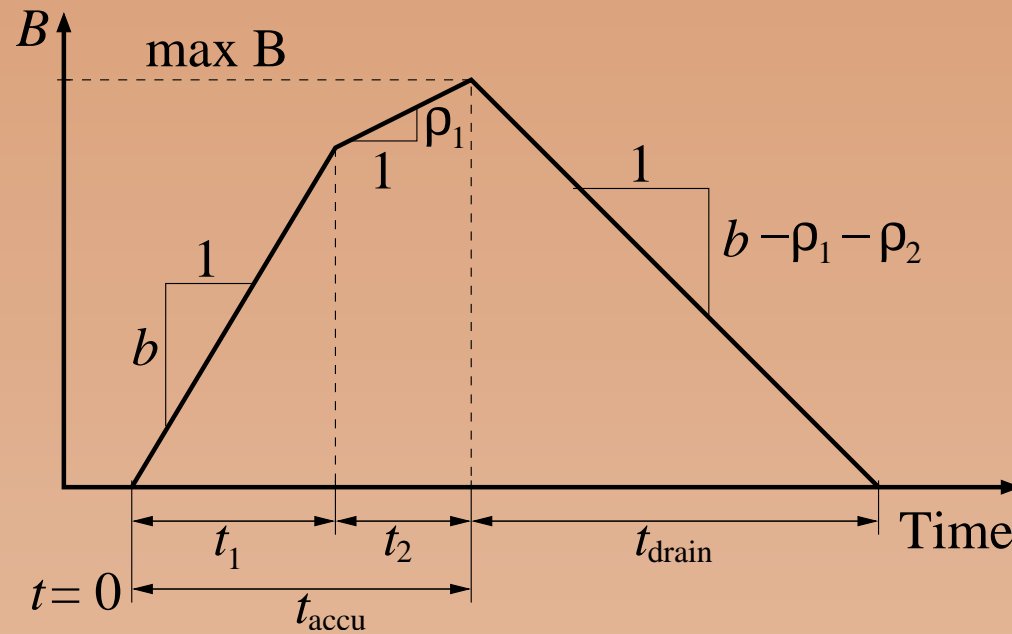
$$\text{link bandwidth } b > \rho_1 + \rho_2$$

$$F_3 \sim ?$$

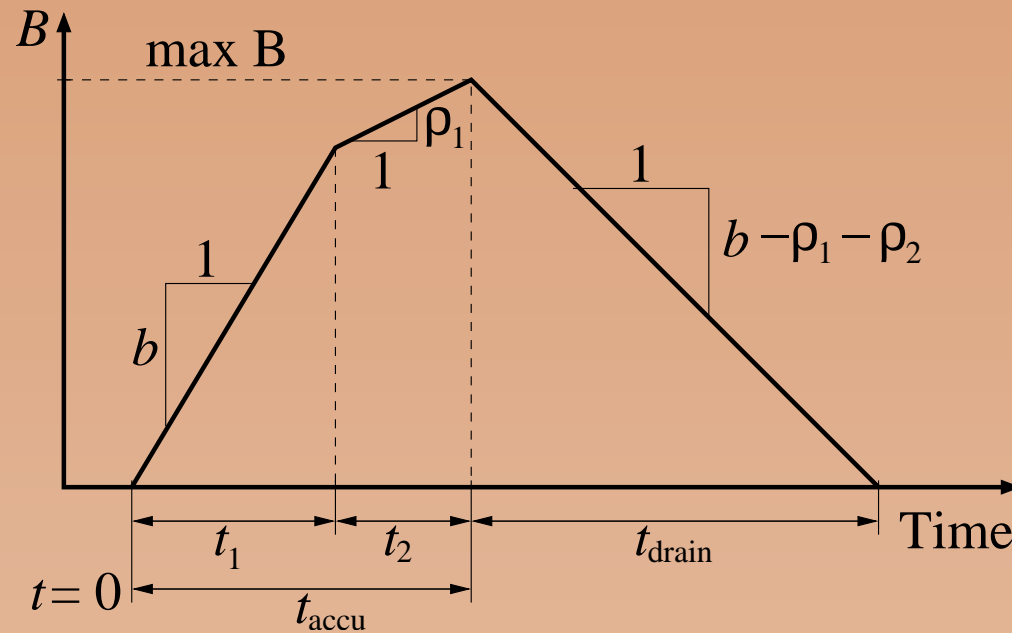
$$\text{maximum delay } D = ?$$

$$\text{maximum backlog } B = ?$$

# Work Conserving Multiplexer - 1

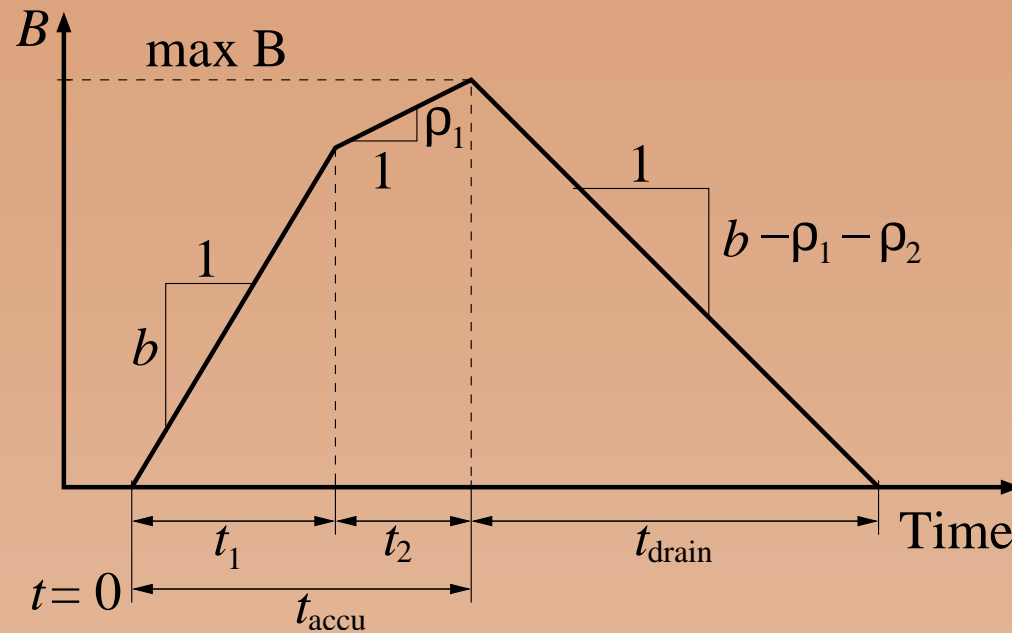


# Work Conserving Multiplexer - 1



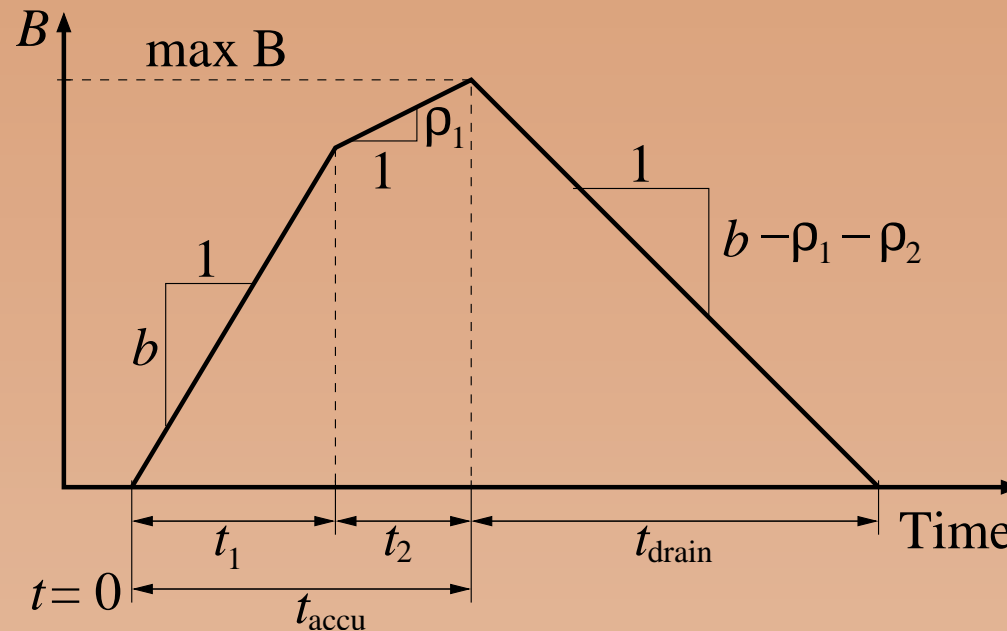
**Phase 1** ( $t_1$ ):  $F_1$  and  $F_2$  transmit at full speed;

## Work Conserving Multiplexer - 1



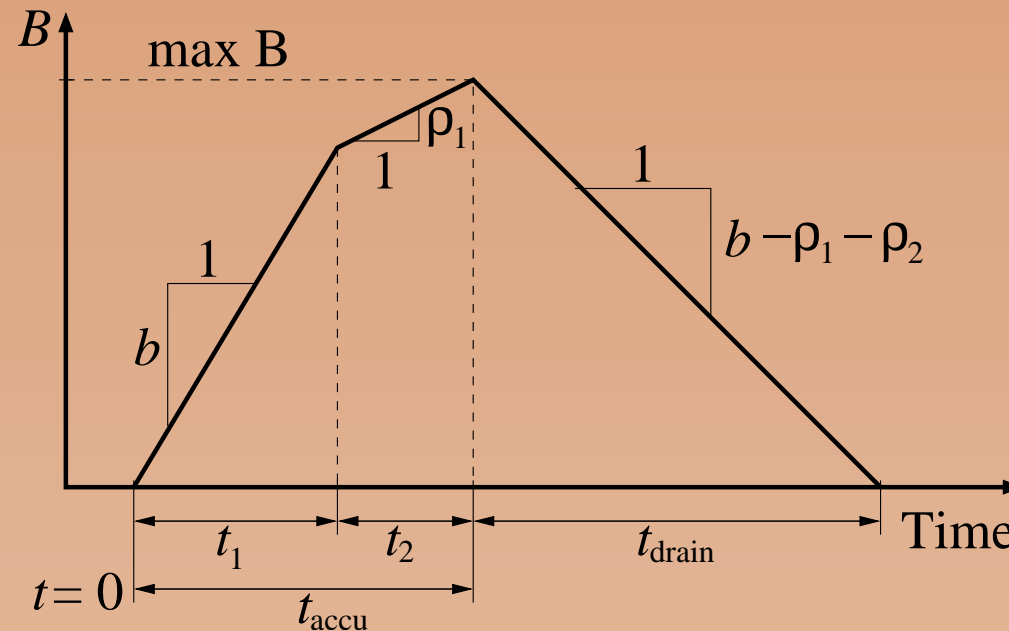
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 Assume: At  $t = 0$  the queue is empty;  $t_1 \leq t_{\text{accu}}$

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 Injection rate:  $2b$ ; Drain rate:  $b$

## Work Conserving Multiplexer - 1



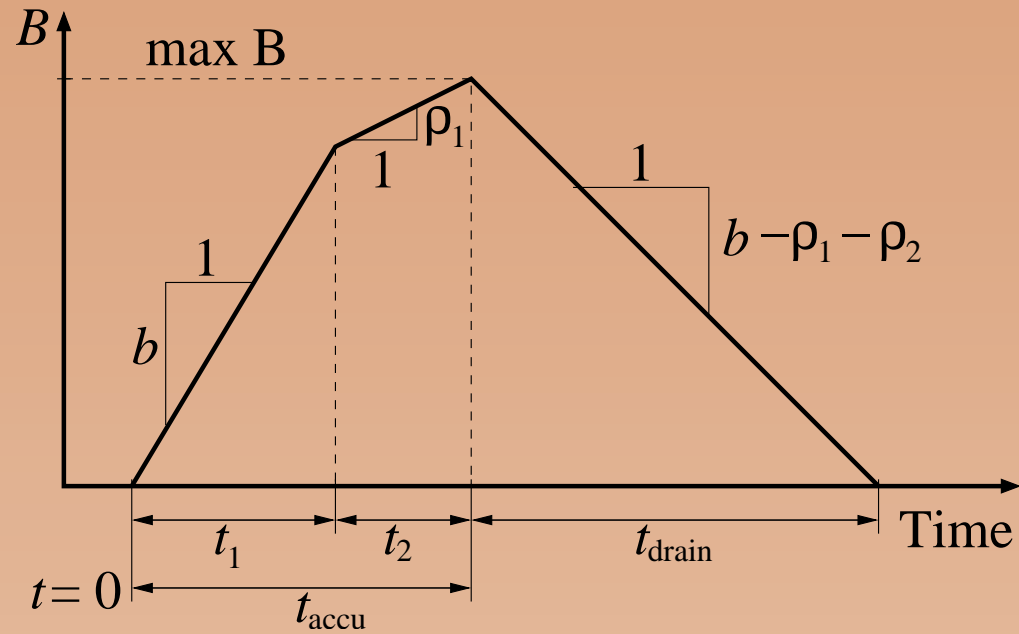
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 Assume: At  $t = 0$  the queue is empty;  $t_1 \leq t_{\text{accu}}$   
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$$bt_1 = \sigma_1 + \rho_1 t_1$$

$$t_1 = \frac{\sigma_1}{b - \rho_1}$$

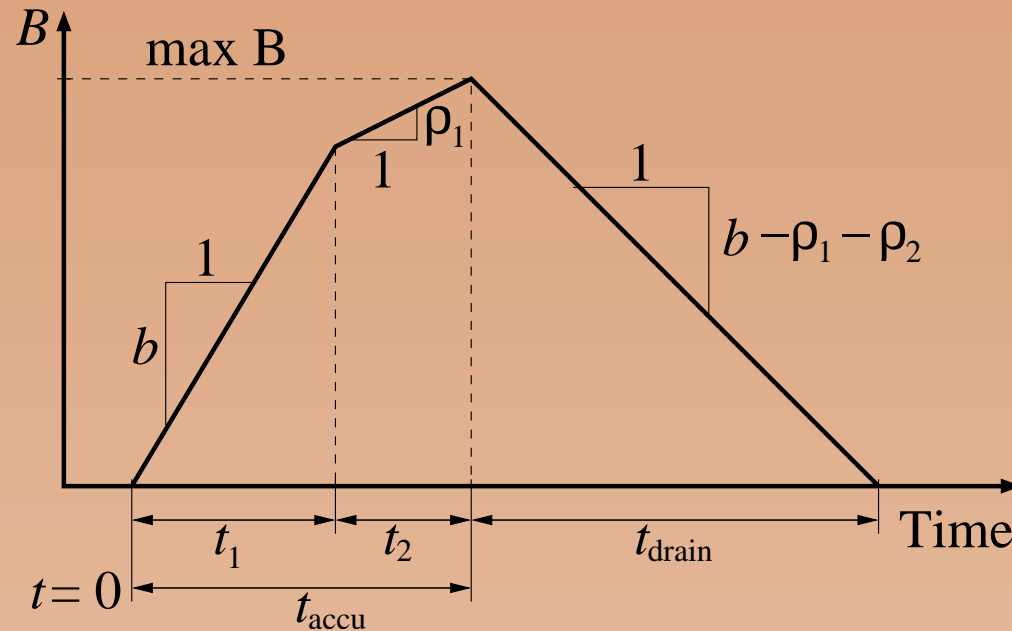


## Work Conserving Multiplexer - 2



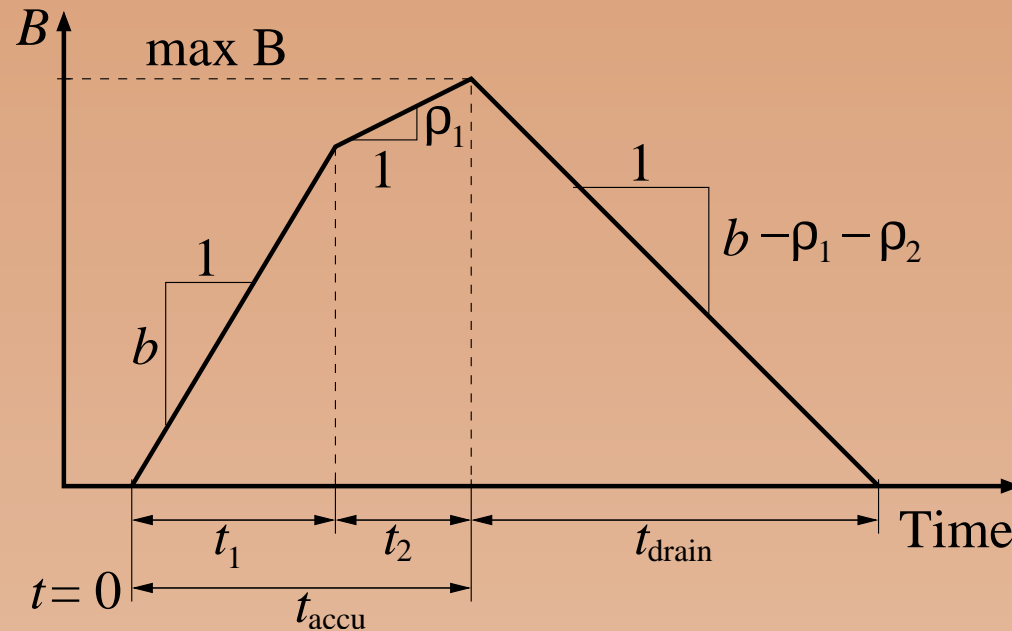


## Work Conserving Multiplexer - 2



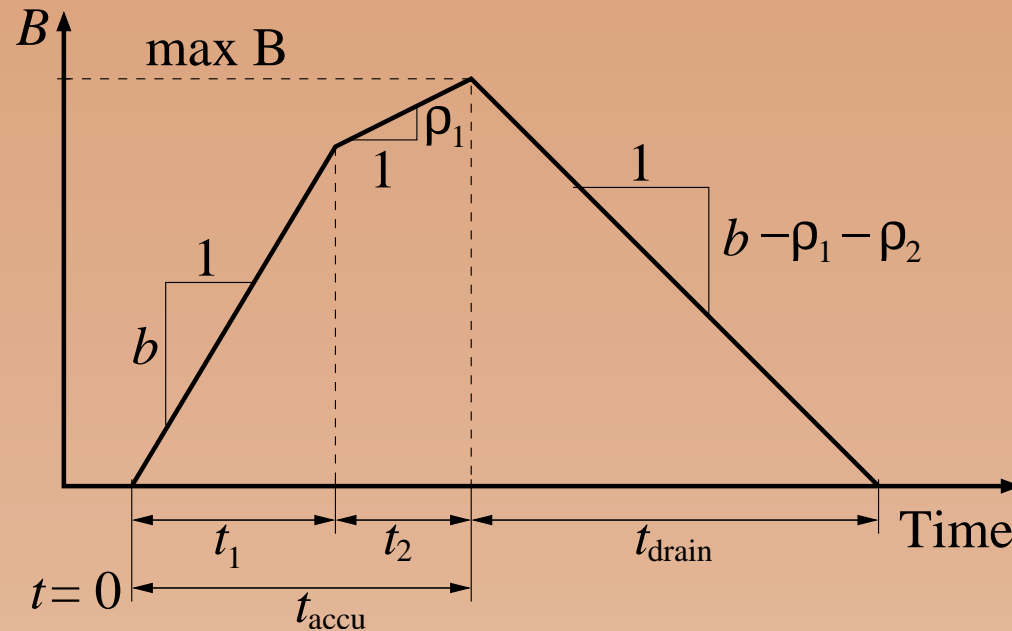
**Phase 2** ( $t_2$ ):  $F_1$  transmits at rate  $\rho_1$ ,  $F_2$  transmits at full speed;

## Work Conserving Multiplexer - 2



**Phase 2** ( $t_2$ ):  $F_1$  transmits at rate  $\rho_1$ ,  $F_2$  transmits at full speed;  
 Injection rate:  $b + \rho_1$ ; Drain rate:  $b$

## Work Conserving Multiplexer - 2



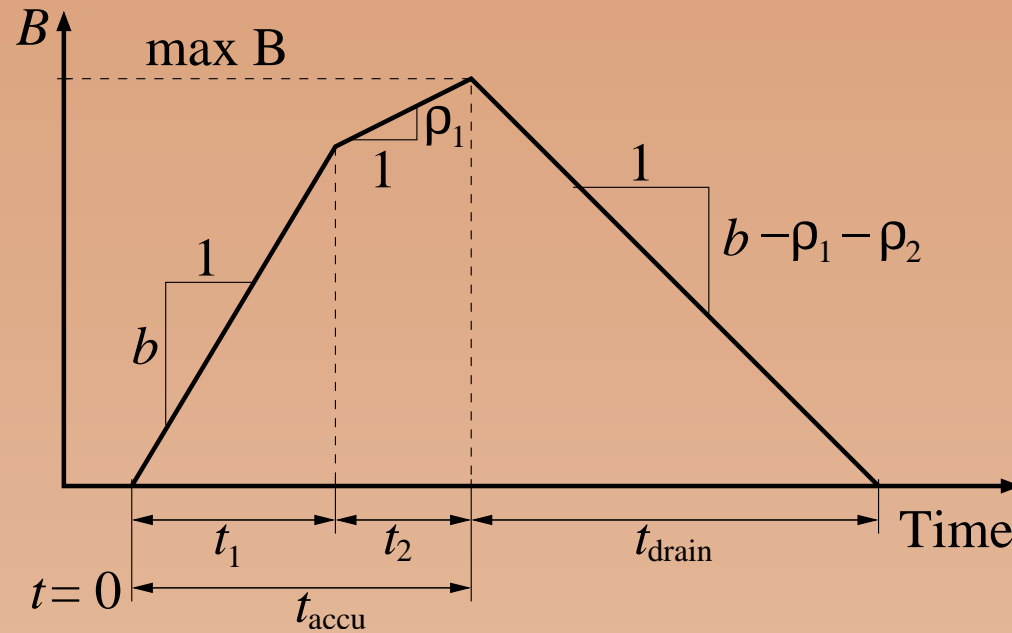
**Phase 2** ( $t_2$ ):  $F_1$  transmits at rate  $\rho_1$ ,  $F_2$  transmits at full speed;  
Injection rate:  $b + \rho_1$ ; Drain rate:  $b$

$$bt_{\text{accu}} = \sigma_2 + \rho_2 t_{\text{accu}}$$

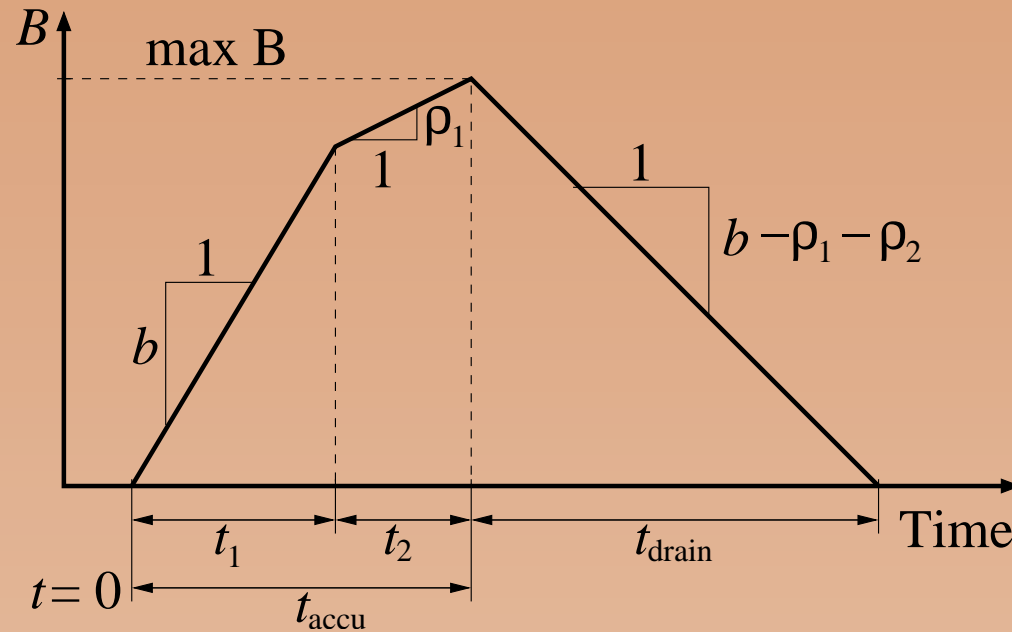
$$t_{\text{accu}} = \frac{\sigma_2}{b - \rho_2}$$



## Work Conserving Multiplexer - 3

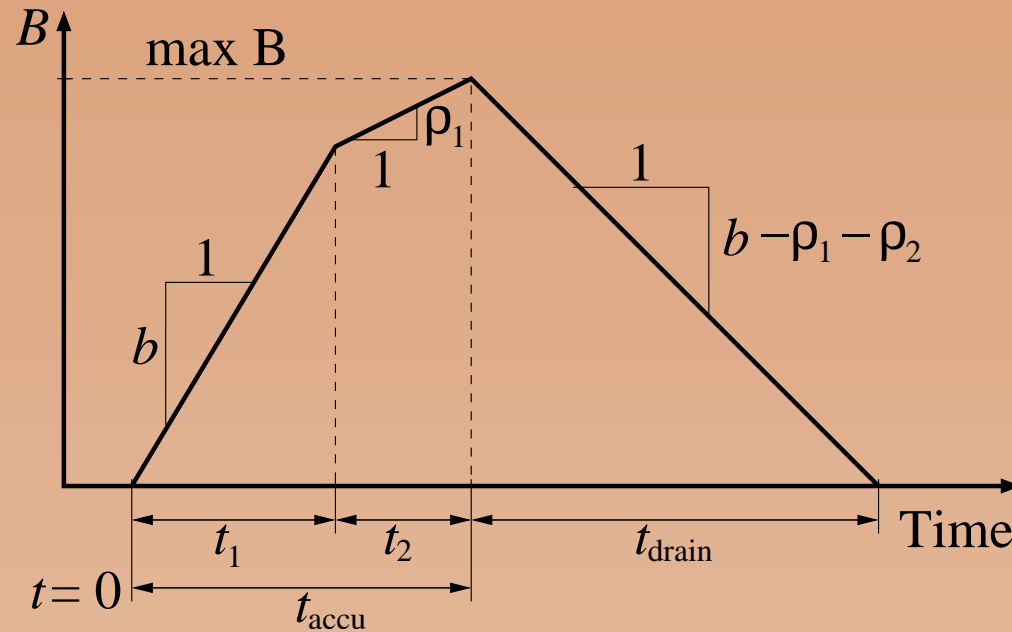


## Work Conserving Multiplexer - 3



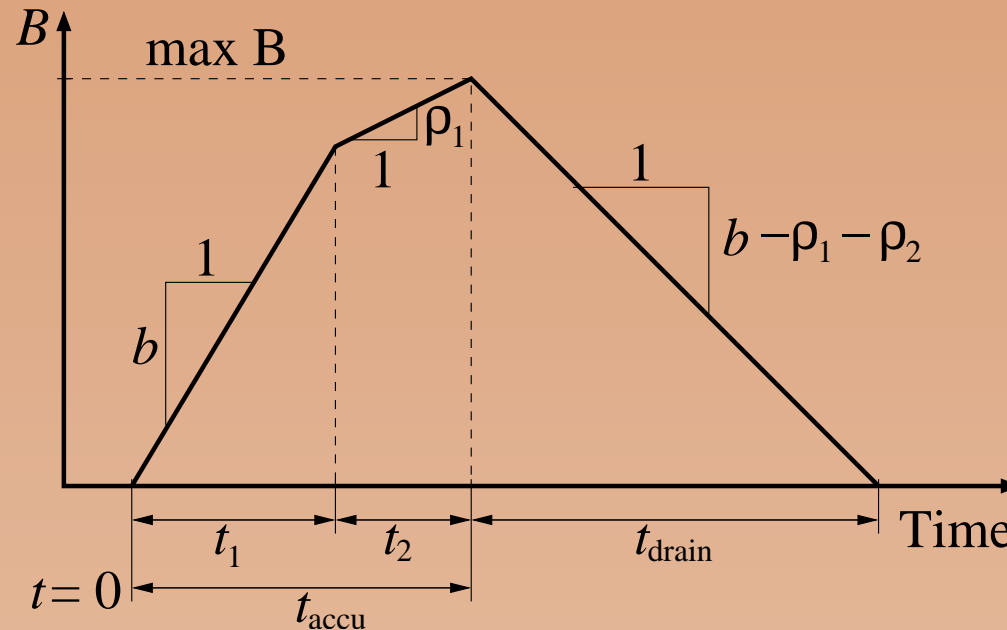
**Phase 3** ( $t_{\text{drain}}$ ):  $F_1$  transmits at rate  $\rho_1$ ,  $F_2$  transmits at rate  $\rho_2$ ;

## Work Conserving Multiplexer - 3



**Phase 3** ( $t_{\text{drain}}$ ):  $F_1$  transmits at rate  $\rho_1$ ,  $F_2$  transmits at rate  $\rho_2$ ;  
 Injection rate:  $\rho_1 + \rho_2$ ; Drain rate:  $b$

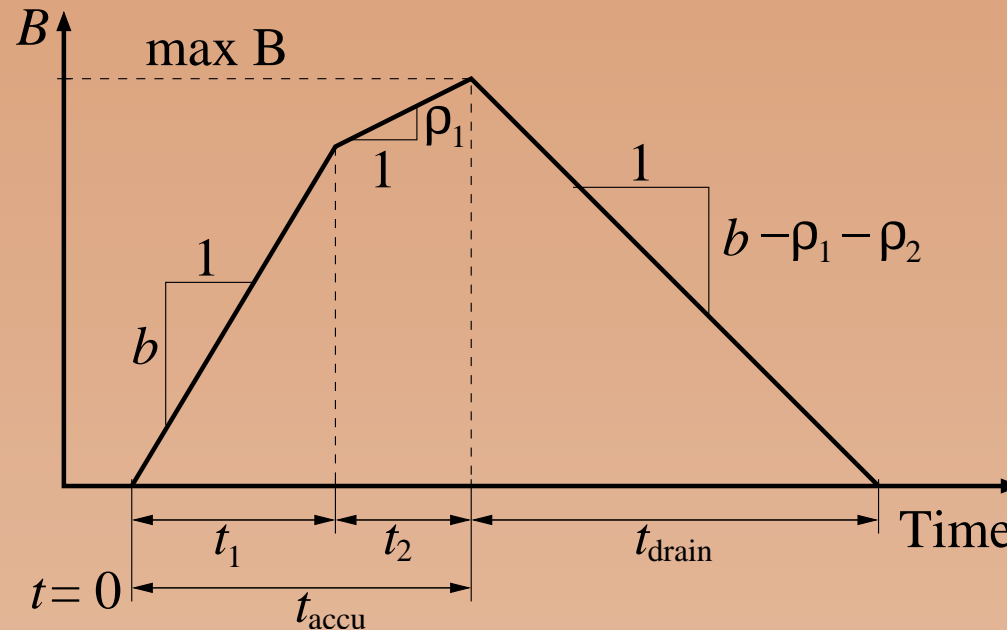
## Work Conserving Multiplexer - 3



**Phase 3** ( $t_{\text{drain}}$ ):  $F_1$  transmits at rate  $\rho_1$ ,  $F_2$  transmits at rate  $\rho_2$ ;  
 Injection rate:  $\rho_1 + \rho_2$ ; Drain rate:  $b$

$$t_{\text{drain}} = \frac{B_{\text{max}}}{b - \rho_1 - \rho_2}$$

## Work Conserving Multiplexer - 3



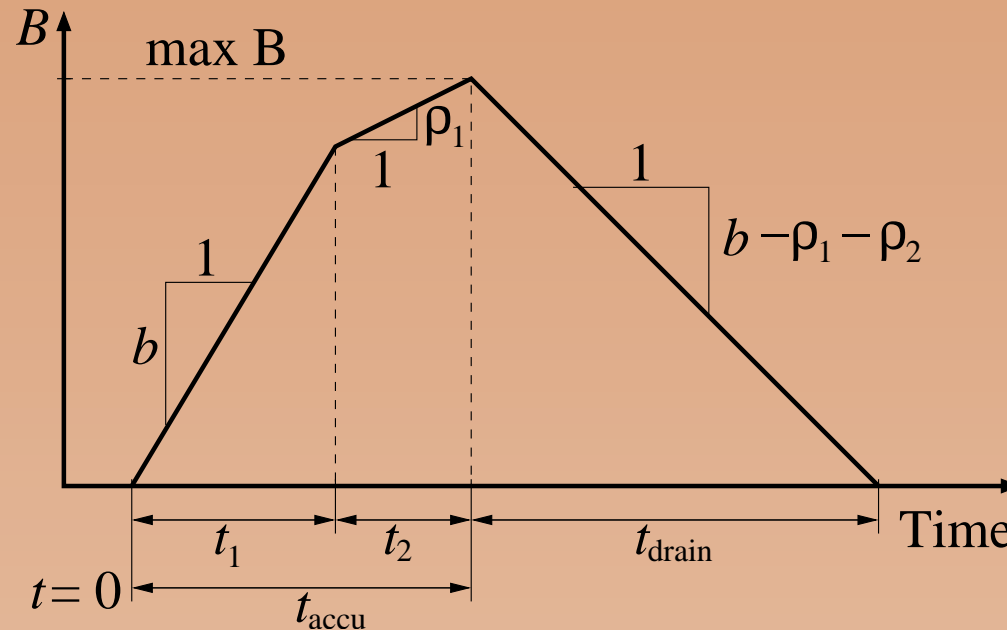
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$$t_{\text{drain}} = \frac{B_{\text{max}}}{b - \rho_1 - \rho_2}$$

$$B_{\text{max}} = bt_1 + \rho_1 t_2$$



## Work Conserving Multiplexer - 3



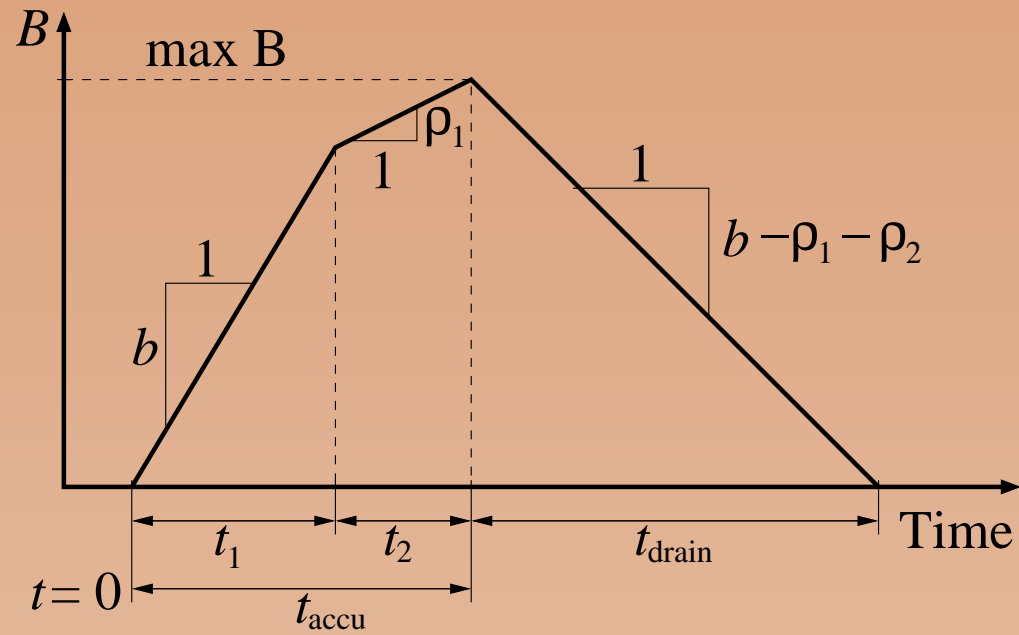
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Injection rate:  $\rho_1 + \rho_2$ ; Drain rate:  $b$

$$t_{\text{drain}} = \frac{B_{\text{max}}}{b - \rho_1 - \rho_2}$$

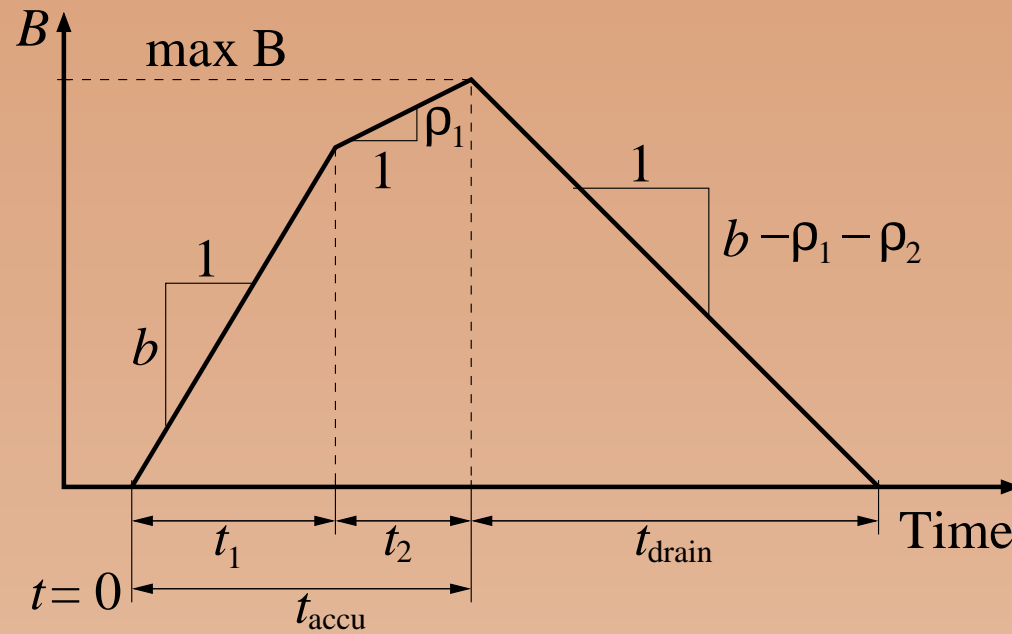
$$B_{\text{max}} = bt_1 + \rho_1 t_2 = \sigma_1 + \frac{\rho_1 \sigma_2}{b - \rho_2}$$



## Work Conserving Multiplexer - Summary

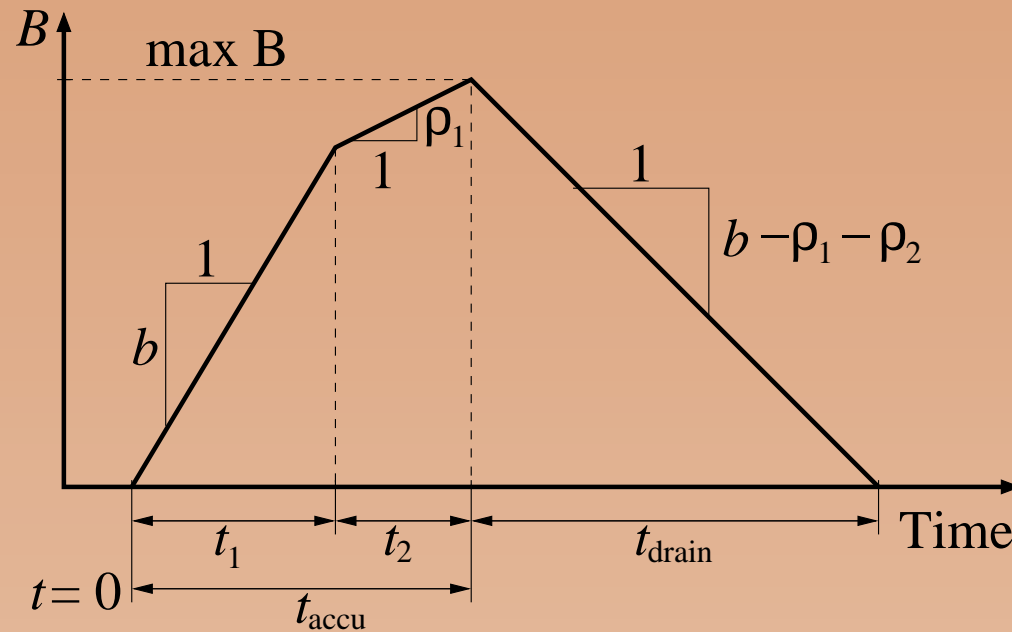


## Work Conserving Multiplexer - Summary



$$B_{\max} = \sigma_1 + \frac{\rho_1 \sigma_2}{b - \rho_2}$$

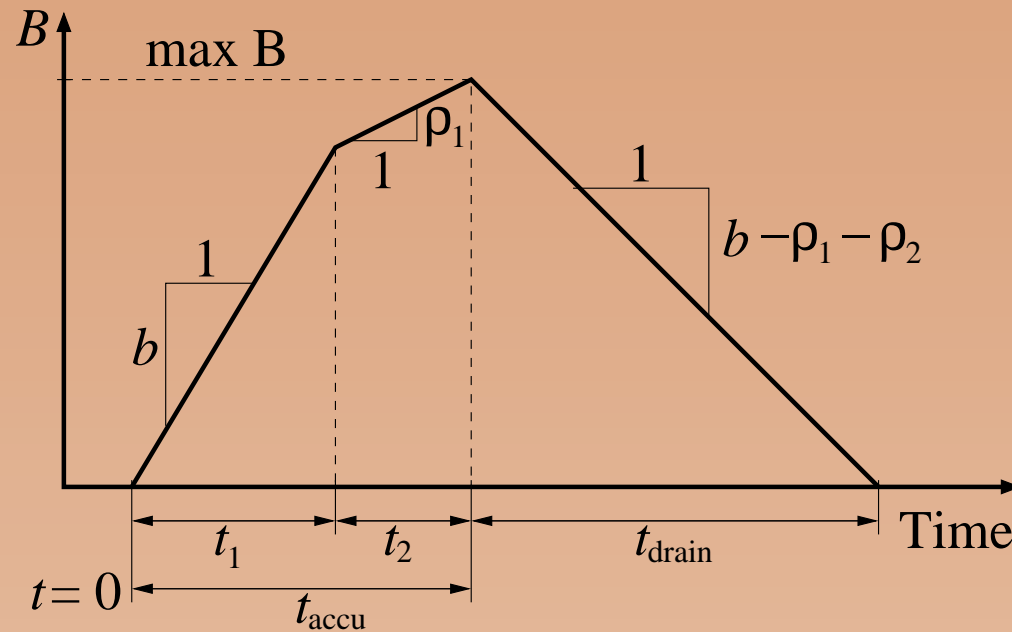
## Work Conserving Multiplexer - Summary



$$B_{\max} = \sigma_1 + \frac{\rho_1 \sigma_2}{b - \rho_2}$$

$$D_{\max} = t_{\text{accu}} + t_{\text{drain}} = \frac{\sigma_1 + \sigma_2}{b - \rho_1 - \rho_2}$$

## Work Conserving Multiplexer - Summary



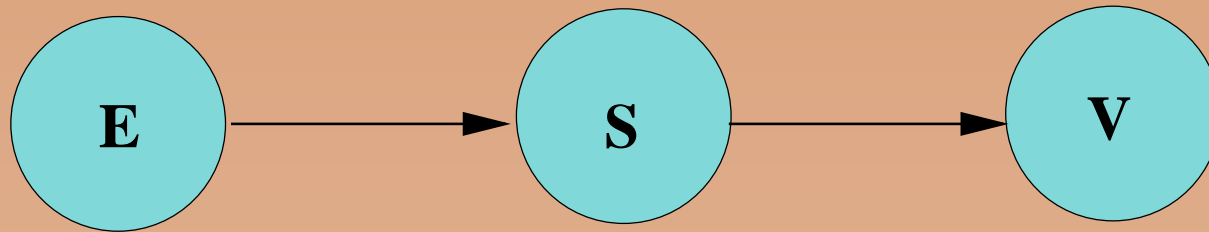
$$B_{\max} = \sigma_1 + \frac{\rho_1 \sigma_2}{b - \rho_2}$$

$$D_{\max} = t_{\text{accu}} + t_{\text{drain}} = \frac{\sigma_1 + \sigma_2}{b - \rho_1 - \rho_2}$$

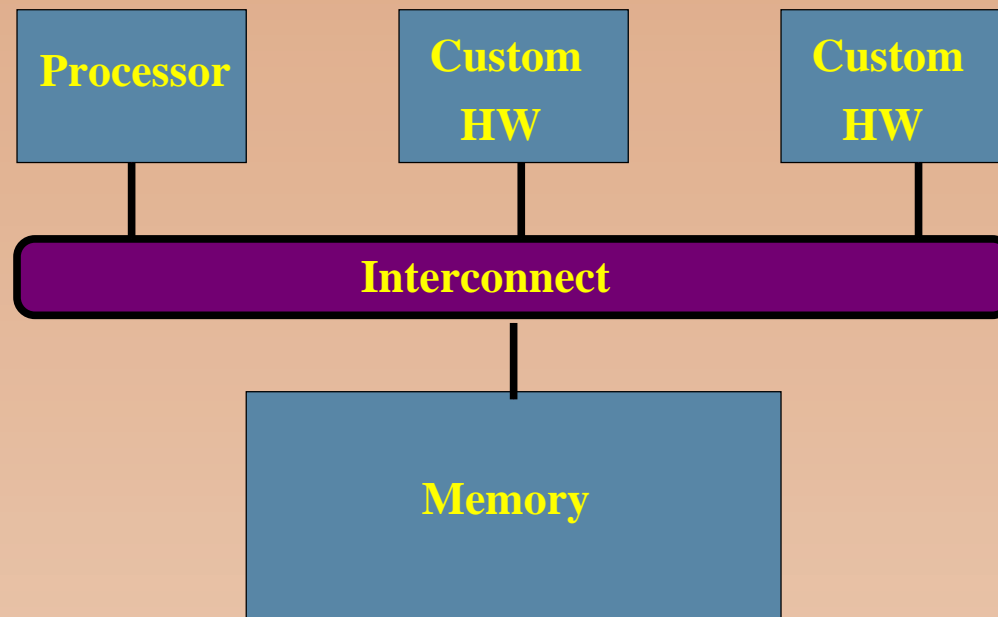
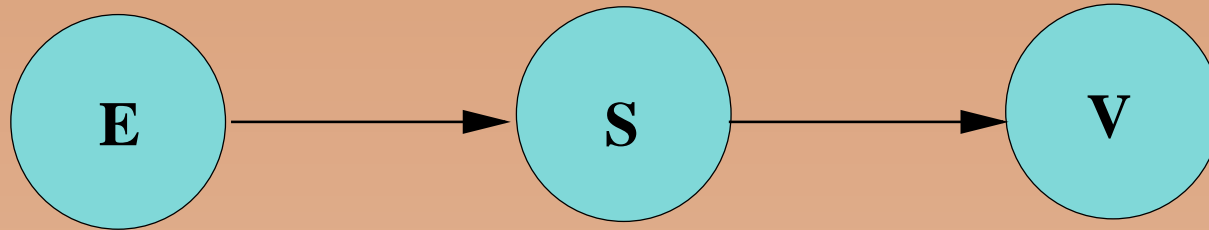
$$F_3 \sim (\sigma_1 + \sigma_2, \rho_1 + \rho_2)$$



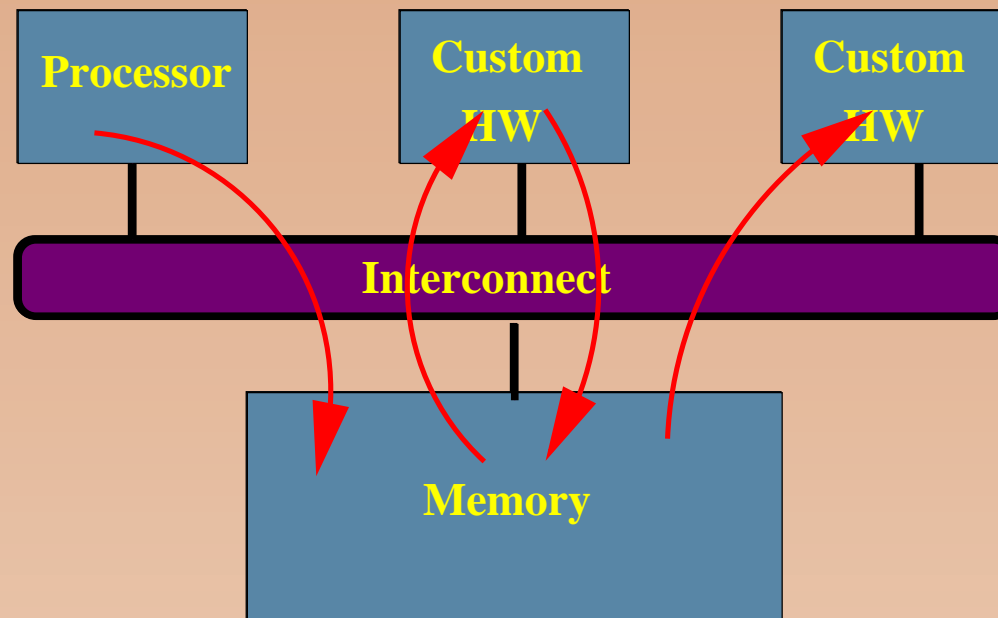
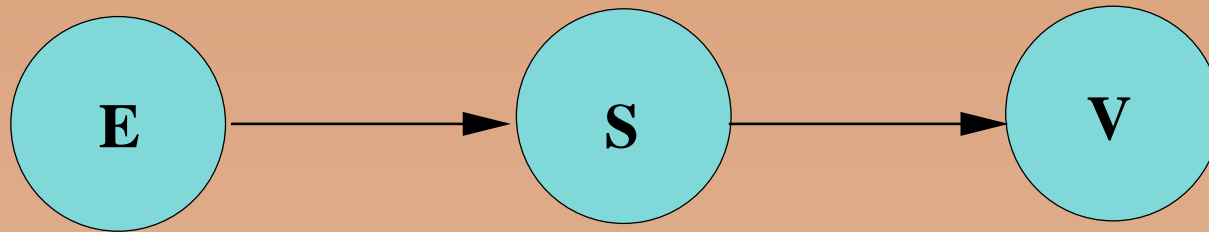
# MPEG Encoding Case Study



# MPEG Encoding Case Study

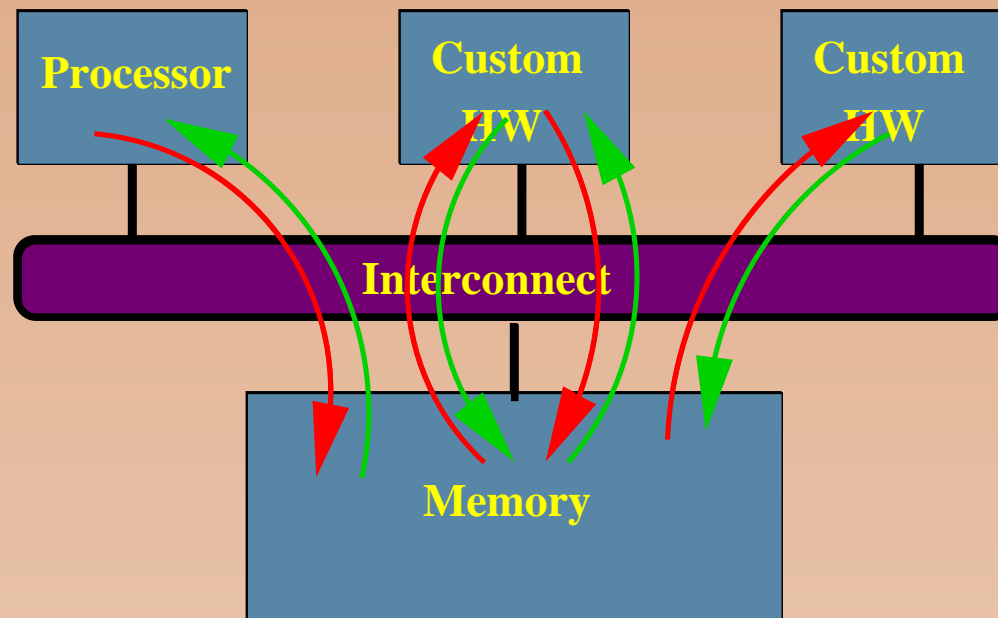
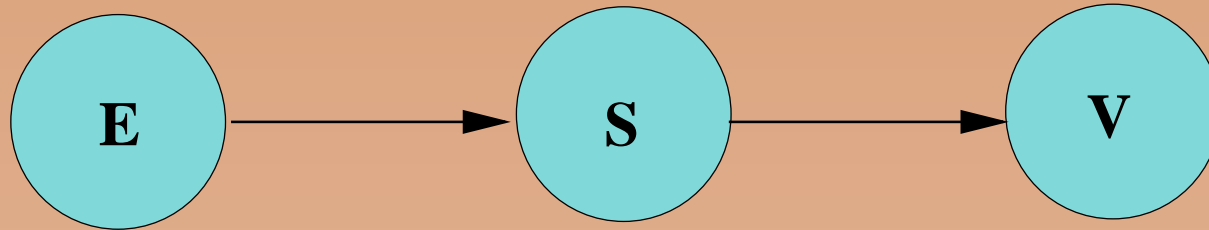


# MPEG Encoding Case Study

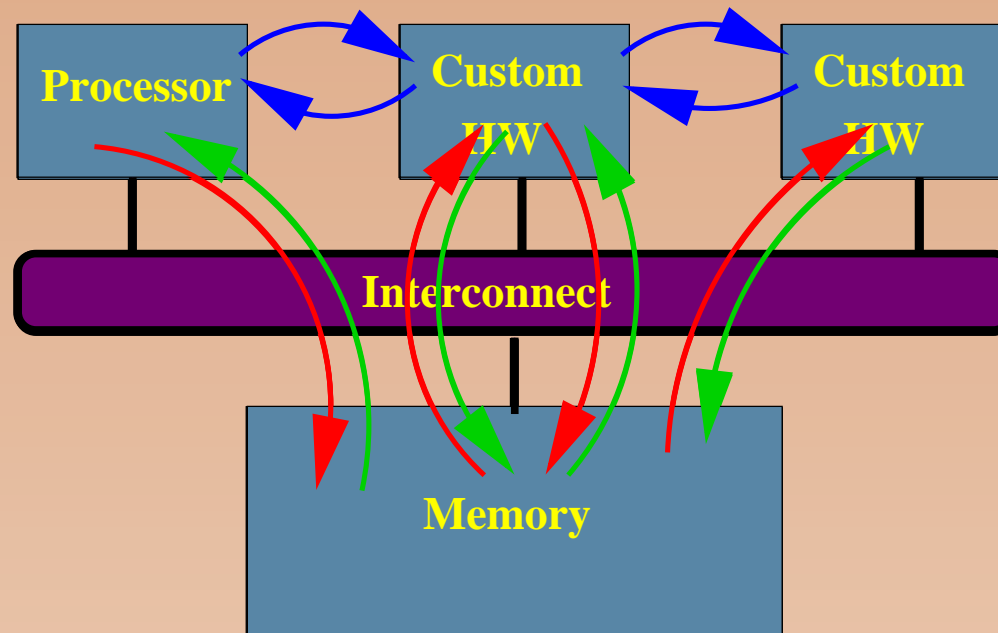
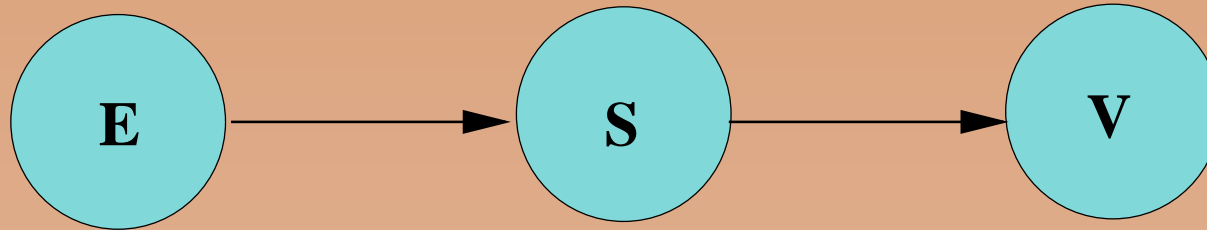




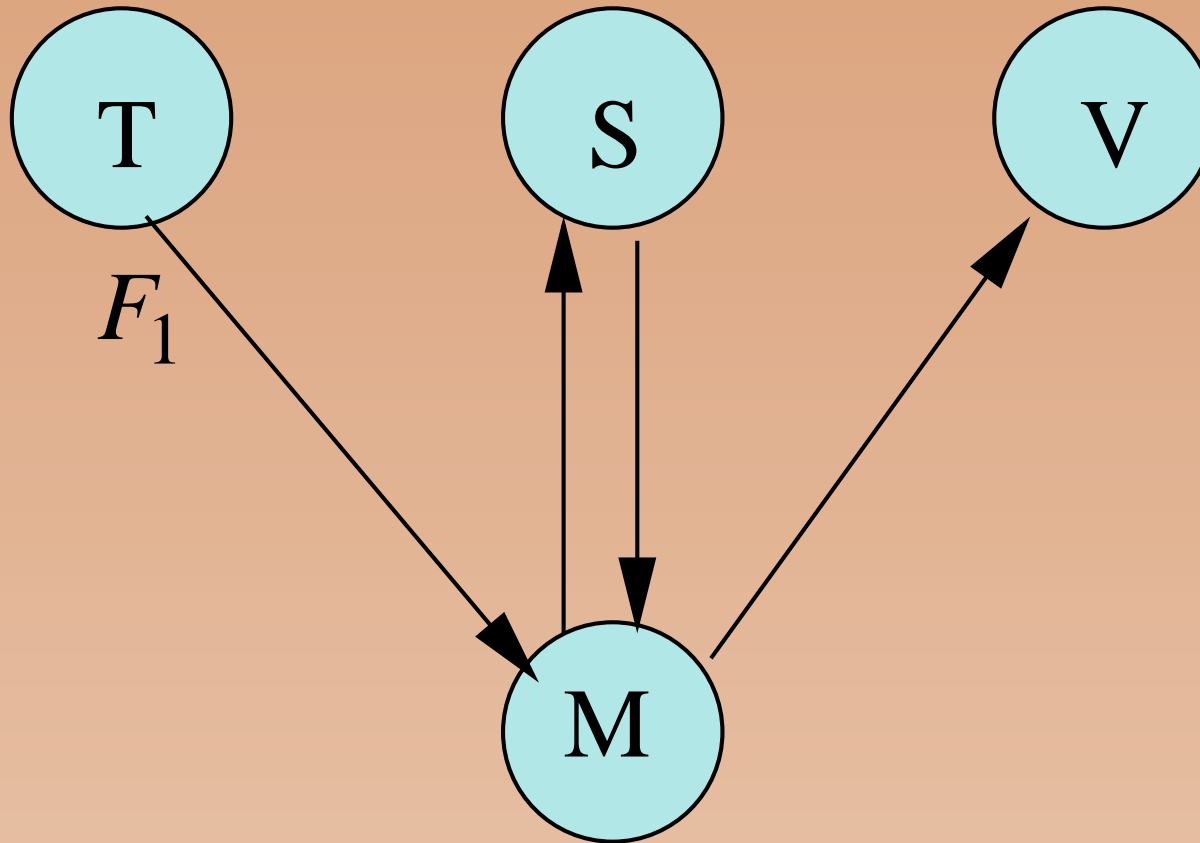
# MPEG Encoding Case Study



# MPEG Encoding Case Study

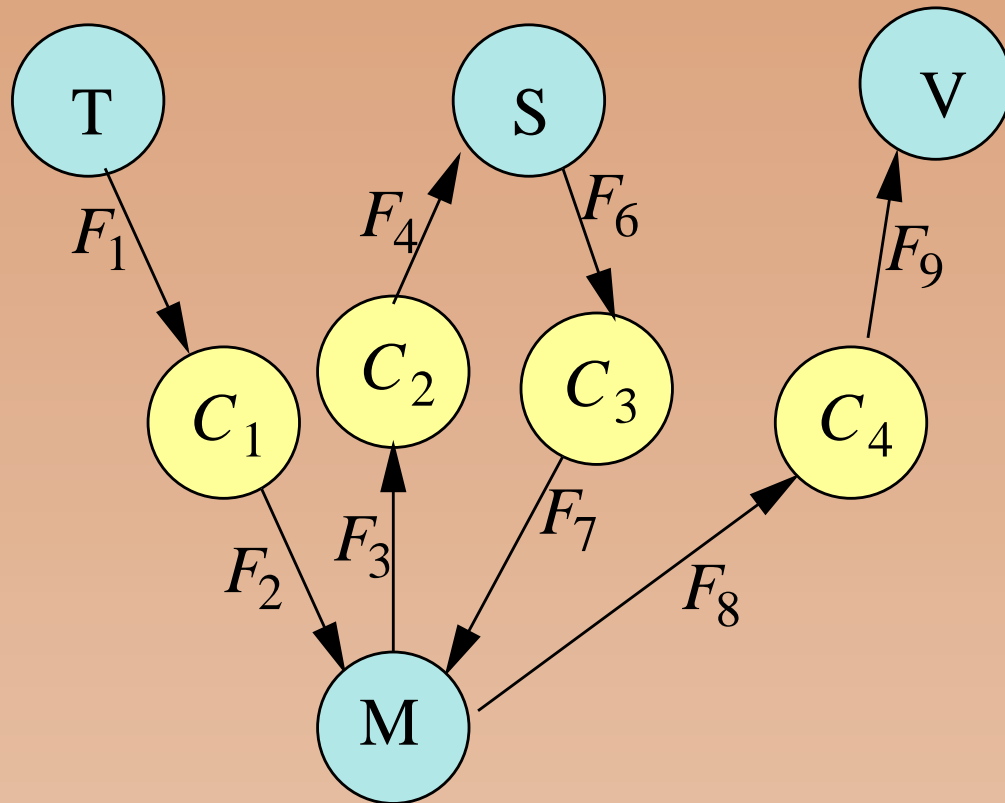


## MPEG Encoding Case Study - cont'd



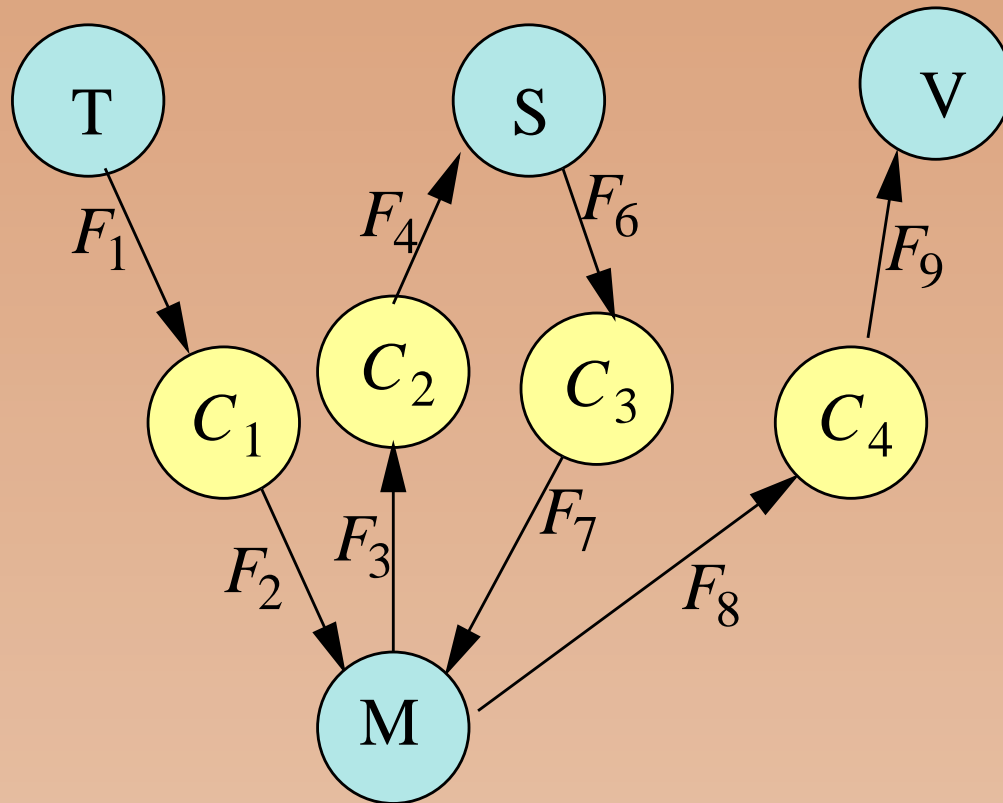
$$F_1 \sim (0, \rho_t)$$

## MPEG Encoding Case Study - cont'd



$$F_1 \sim (0, \rho_t)$$

## MPEG Encoding Case Study - cont'd



$$F_1 \sim (0, \rho_t)$$

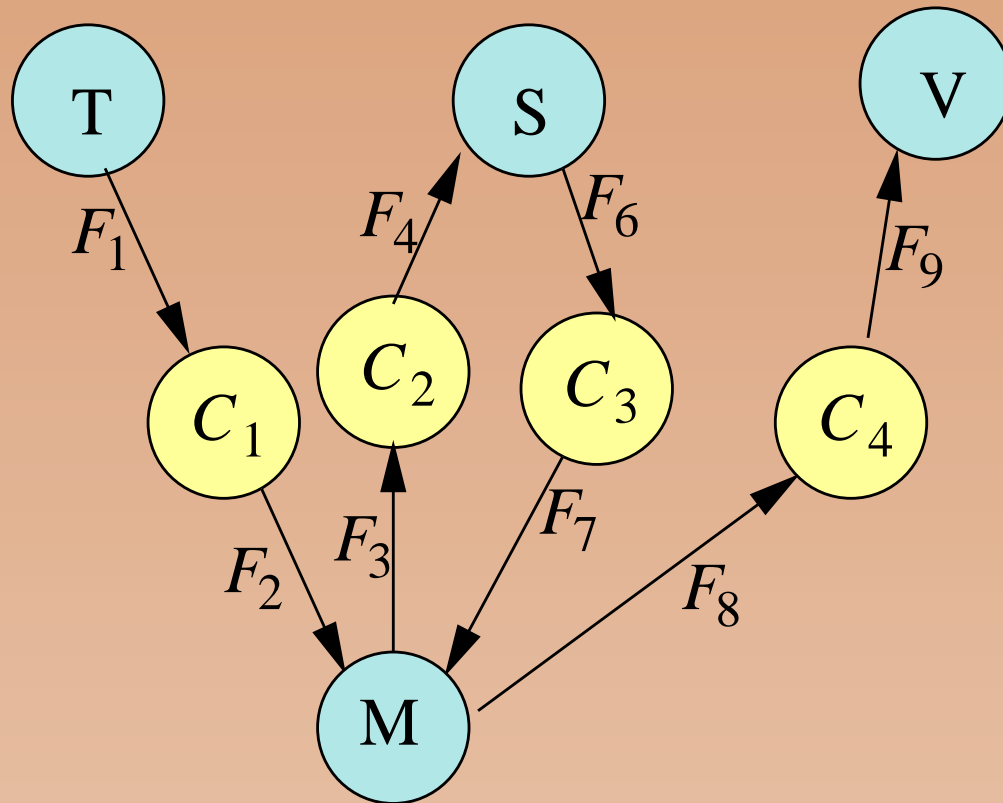
$$C_1 : (\rho_t, D_1)$$

$$C_2 : (\rho_t, D_2)$$

$$C_3 : (\rho_t, D_3)$$

$$C_4 : (\rho_t, D_4)$$

## MPEG Encoding Case Study - cont'd



$$F_1 \sim (0, \rho_t)$$

$$C_1 : (\rho_t, D_1)$$

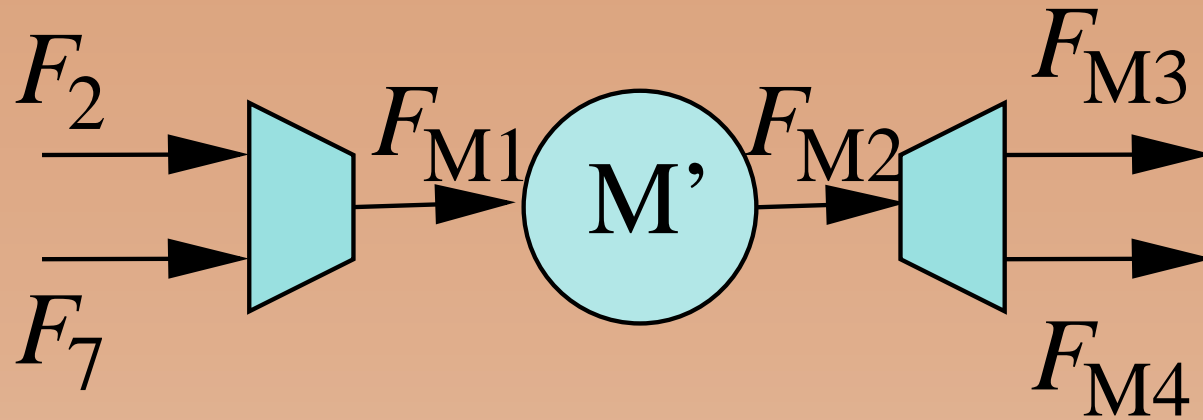
$$C_2 : (\rho_t, D_2)$$

$$C_3 : (\rho_t, D_3)$$

$$C_4 : (\rho_t, D_4)$$

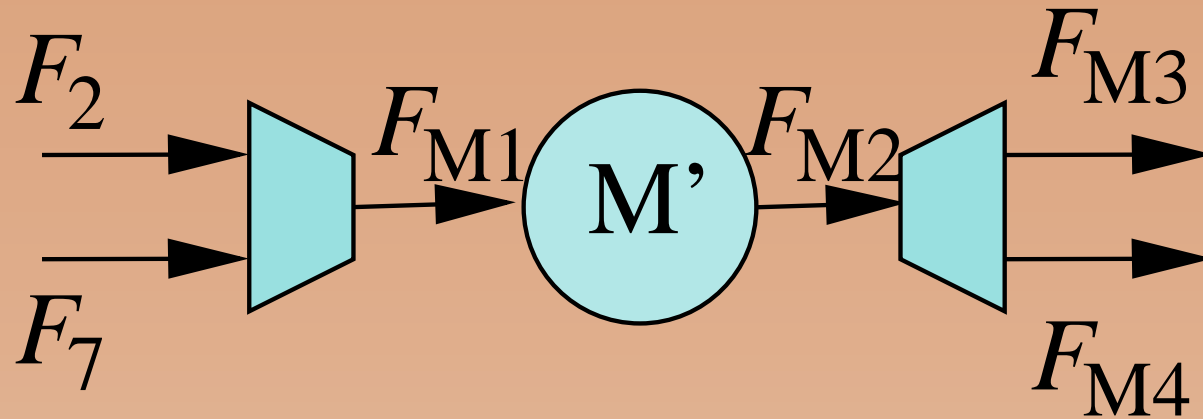
$$F_2 \sim (\rho_t D_1, \rho_t)$$

## MPEG Encoding Case Study - Memory



$$M' : (2\rho_t, D_{M'})$$

## MPEG Encoding Case Study - Memory



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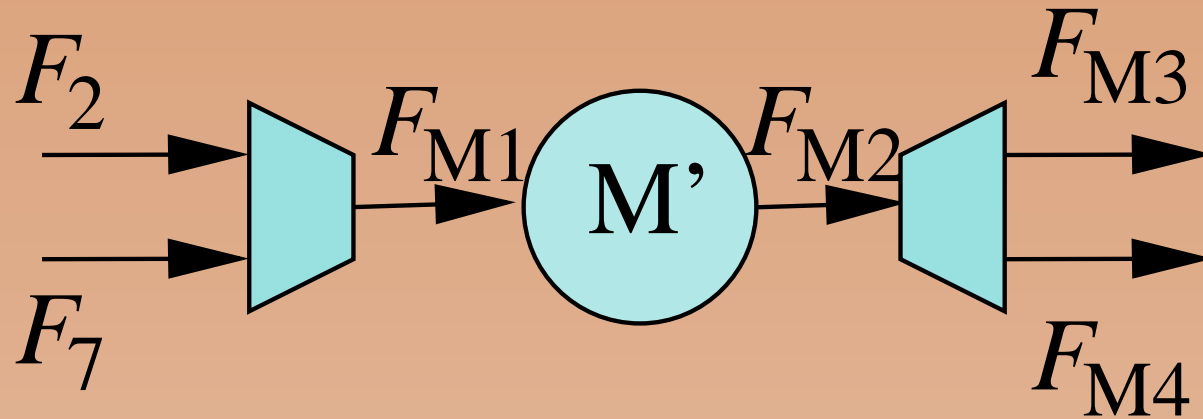
For a general multiplexer we have:

$$D_{\text{mux}} = \frac{\sigma_1 + \sigma_2}{C_{\text{out}} - \rho_1 - \rho_2}$$

$$F_{\text{muxout}} \sim (\sigma_1 + \sigma_2, \rho_1 + \rho_2)$$



## MPEG Encoding Case Study - Memory



$$M' : (2\rho_t, D_{M'})$$

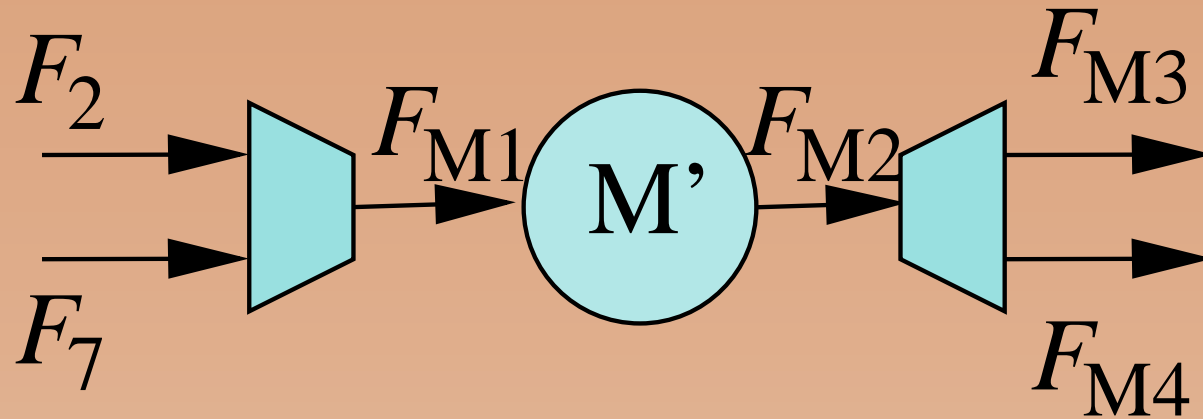
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$$F_{M3} \sim (\rho_t(D_1 + D_{\text{mux}} + D_{M'}), \rho_t)$$

## MPEG Encoding Case Study - Memory



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For a general multiplexer we have:

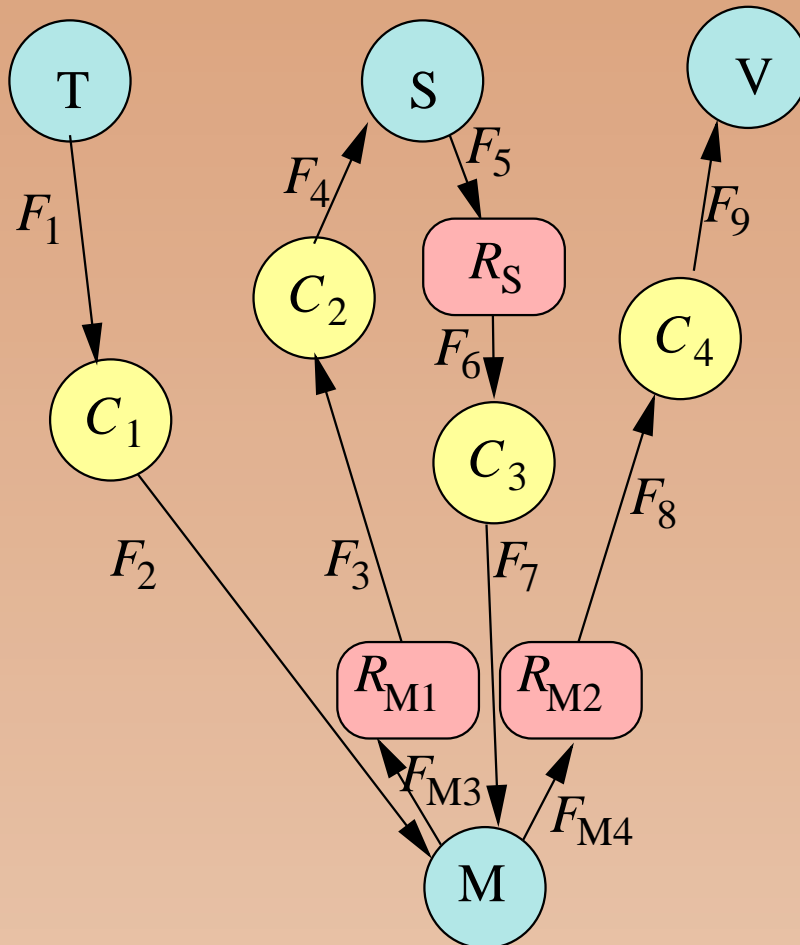
$$D_{\text{mux}} = \frac{\sigma_1 + \sigma_2}{C_{\text{out}} - \rho_1 - \rho_2}$$

$$F_{\text{muxout}} \sim (\sigma_1 + \sigma_2, \rho_1 + \rho_2)$$

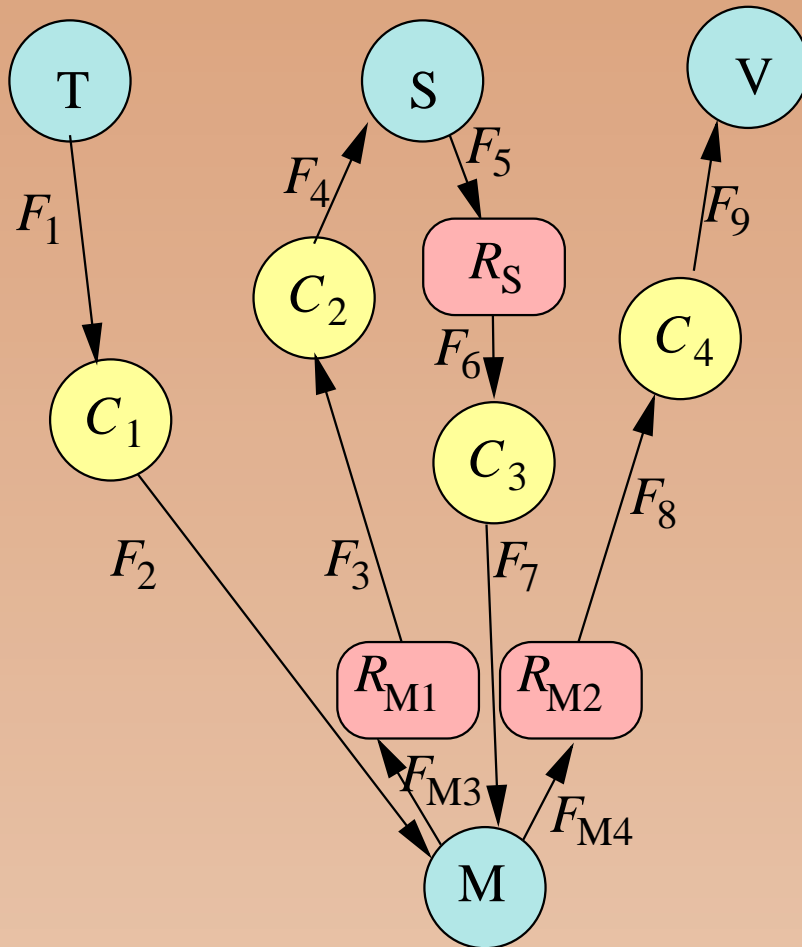
$$F_{M3} \sim (\rho_t(D_1 + D_{\text{mux}} + D_{M'}), \rho_t)$$

$$F_{M4} \sim ?$$

## MPEG Encoding Case Study - cont'd



## MPEG Encoding Case Study - cont'd



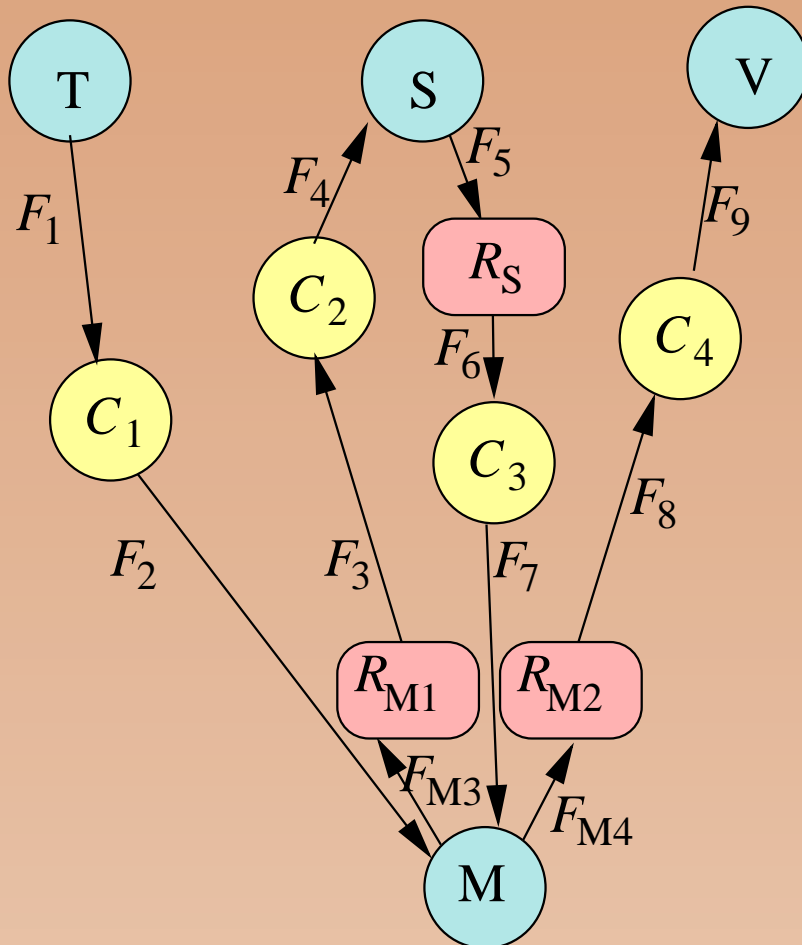
$$R_{M1} \sim (S_{\text{buffer}}, \rho_t);$$

$$R_{M2} \sim (S_{\text{buffer}}, \rho_t);$$

$$R_S \sim (S_{\text{buffer}}, \rho_t);$$

$S_{\text{buffer}}$  is the size of the input buffer in S.

## MPEG Encoding Case Study - cont'd



$$R_{M1} \sim (S_{\text{buffer}}, \rho_t);$$

$$R_{M2} \sim (S_{\text{buffer}}, \rho_t);$$

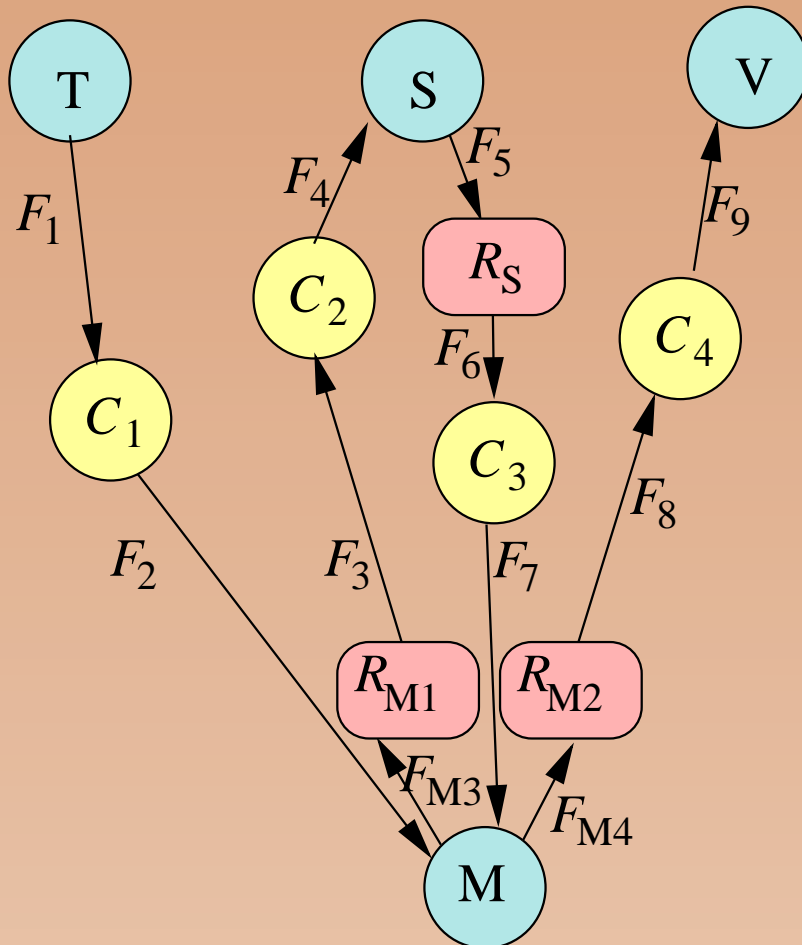
$$R_S \sim (S_{\text{buffer}}, \rho_t);$$

$S_{\text{buffer}}$  is the size of the input buffer in S.

$$D_{(\sigma, \rho)\text{-regulator}} = \frac{\max(0, \sigma' - \sigma)}{\rho}$$

$$B_{(\sigma, \rho)\text{-regulator}} = \max(0, \sigma' - \sigma)$$

## MPEG Encoding Case Study - cont'd



$$R_{M1} \sim (S_{\text{buffer}}, \rho_t);$$

$$R_{M2} \sim (S_{\text{buffer}}, \rho_t);$$

$$R_S \sim (S_{\text{buffer}}, \rho_t);$$

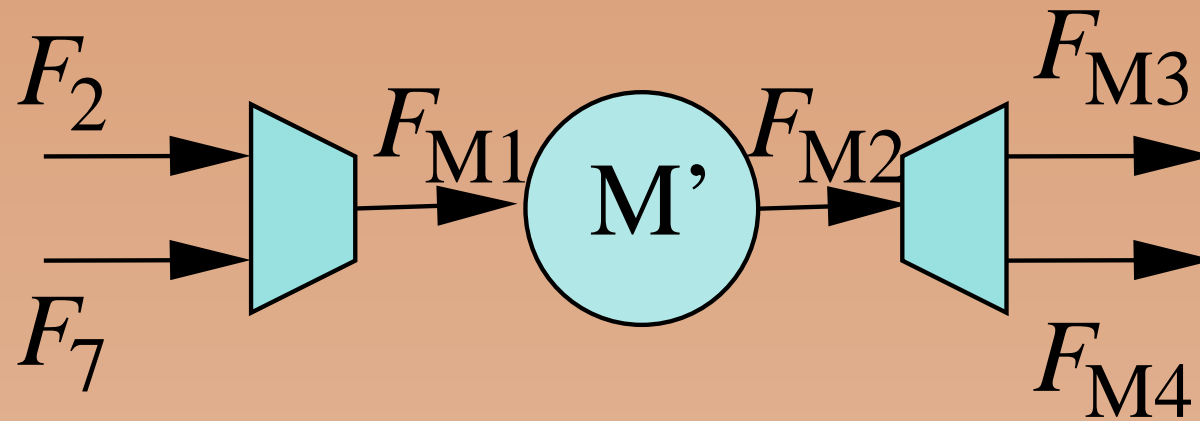
$S_{\text{buffer}}$  is the size of the input buffer in S.

$$F_6 \sim (S_{\text{buffer}}, \rho_t)$$

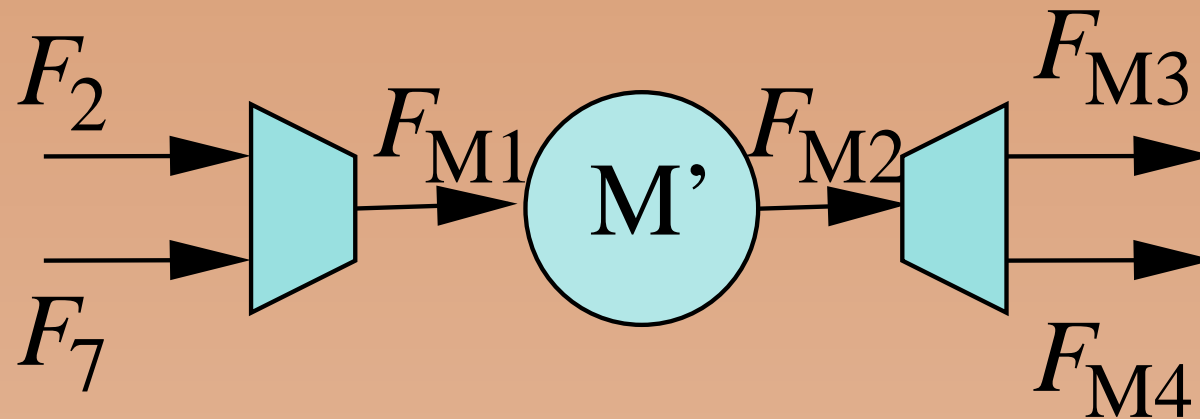
$$C_3 : (\rho_t, D_3)$$

$$F_7 \sim (S_{\text{buffer}} + \rho_t D_3, \rho_t)$$

## MPEG Encoding Case Study - Memory



## MPEG Encoding Case Study - Memory



$$M' : (2\rho_t, D_{M'})$$

$$D_{\text{mux}} = \frac{\sigma_1 + \sigma_2}{C_{\text{out}} - \rho_1 - \rho_2} = \frac{S_{\text{buffer}} + \rho_t(D_1 + D_3)}{C_{\text{out}} - 2\rho_t}$$

$$F_{M1} \sim (S_{\text{buffer}} + \rho_t(D_1 + D_3), 2\rho_t)$$

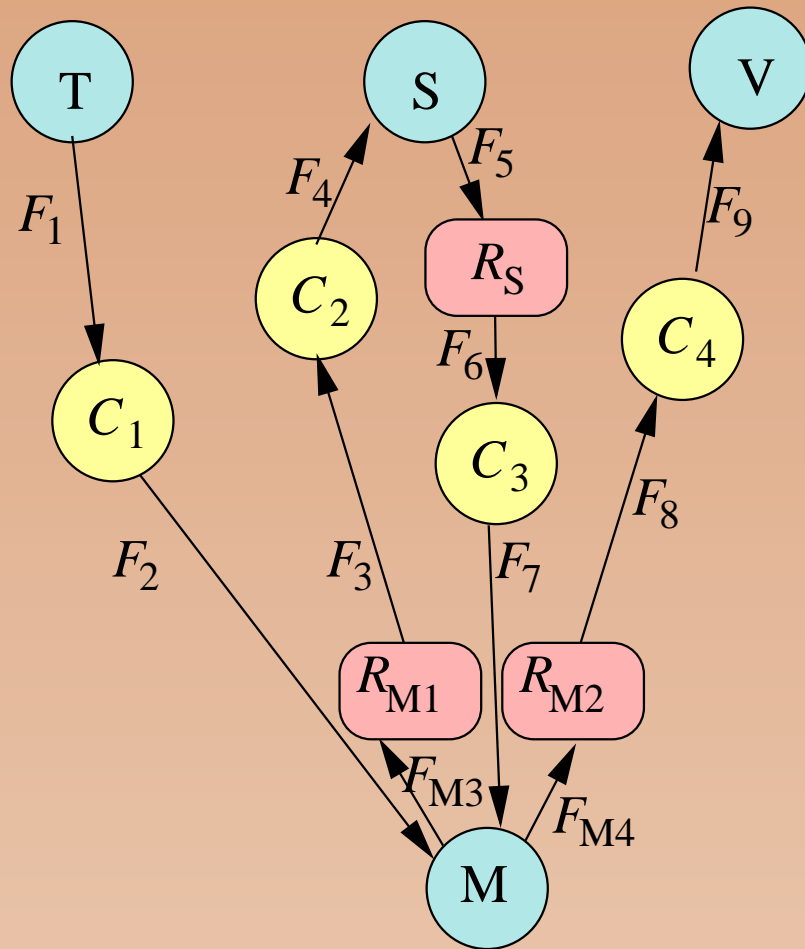
$$F_{M2} \sim (S_{\text{buffer}} + \rho_t(D_1 + D_3 + 2D_{M'}), 2\rho_t)$$

$$F_{M3} \sim (\rho_t(D_1 + D_{\text{mux}} + D_{M'}), \rho_t)$$

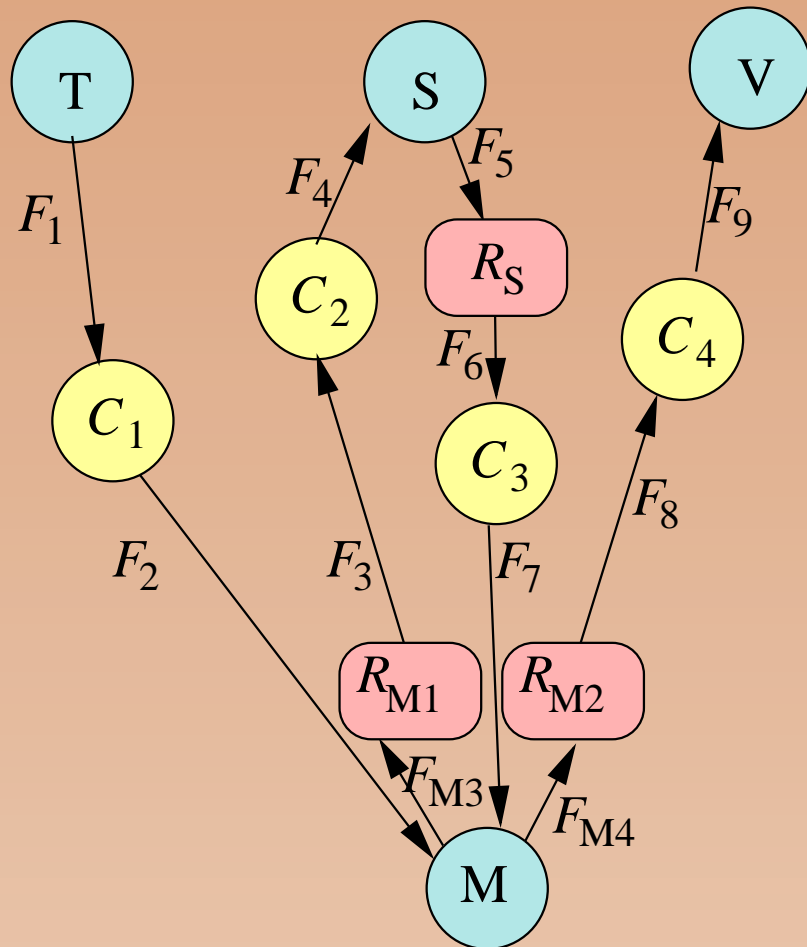
$$F_{M4} \sim (S_{\text{buffer}} + \rho_t(D_3 + D_{\text{mux}} + D_{M'}), \rho_t)$$



# MPEG Encoding Case Study - cont'd



## MPEG Encoding Case Study - cont'd



Backlog of the regulators:

$$B_{RM1} = \max(0, \rho_t(D_1 + D_{\text{mux}} + D_{M'}) - S_{\text{buffer}})$$

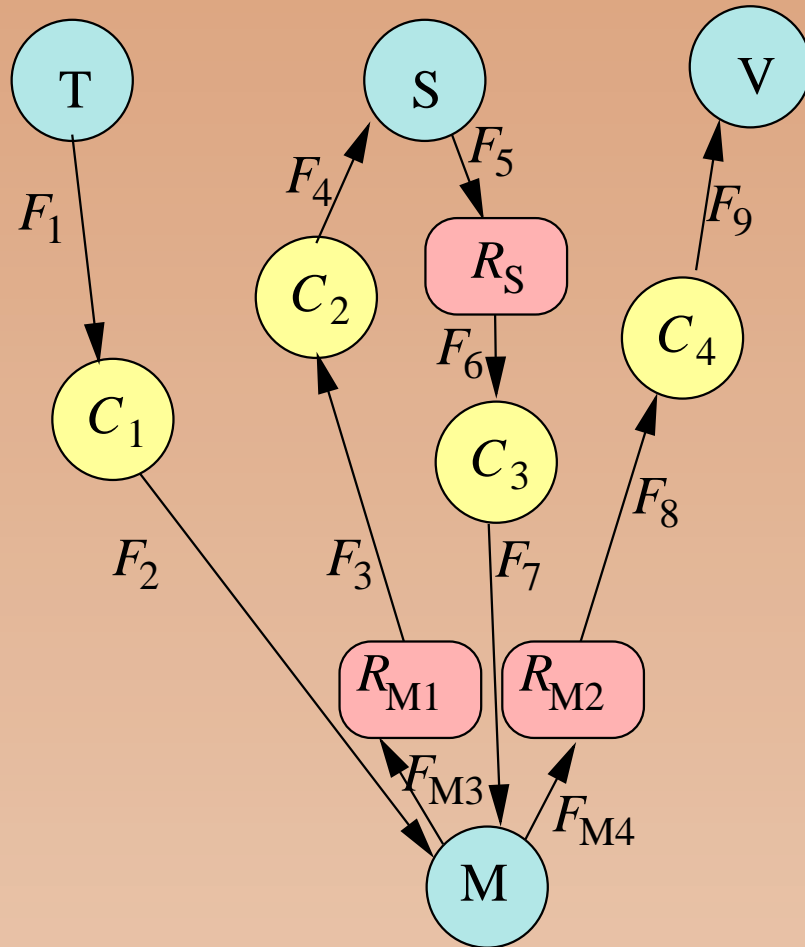
$$B_{RM2} = \max(0, 128B + \rho_t(D_3 + D_{\text{mux}} + D_{M'}) - S_{\text{buffer}})$$

Delay of the regulators:

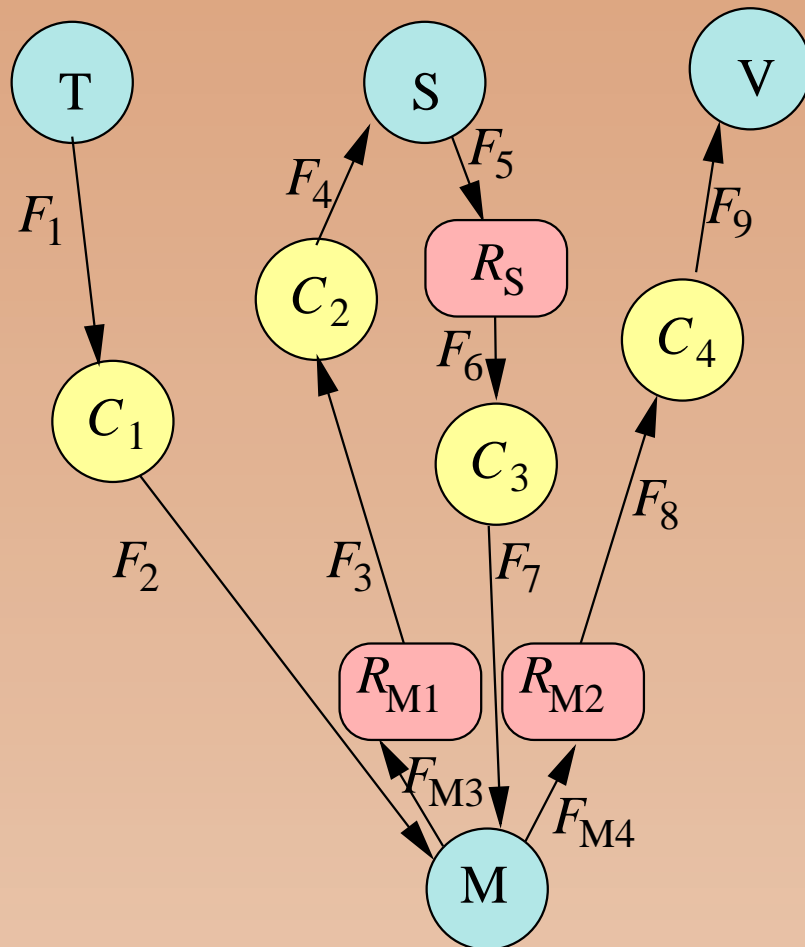
$$D_{RM1} = \frac{B_{RM1}}{\rho_t}$$

$$D_{RM2} = \frac{B_{RM2}}{\rho_t}$$

# MPEG Encoding Case Study - cont'd



## MPEG Encoding Case Study - cont'd



The flow from the memory to S:

$$F_3 \sim (S_{\text{buffer}}, \rho_t)$$

$$C_2 : (\rho_t, D_2)$$

$$F_4 \sim (S_{\text{buffer}} + \rho D_2, \rho_t),$$

A characterization of S and its output:

$$S : \left( \rho_t, \frac{S_{\text{buffer}}}{\rho_t} \right)$$

$$F_5 \sim (2S_{\text{buffer}} + \rho_t D_2, \rho_t)$$

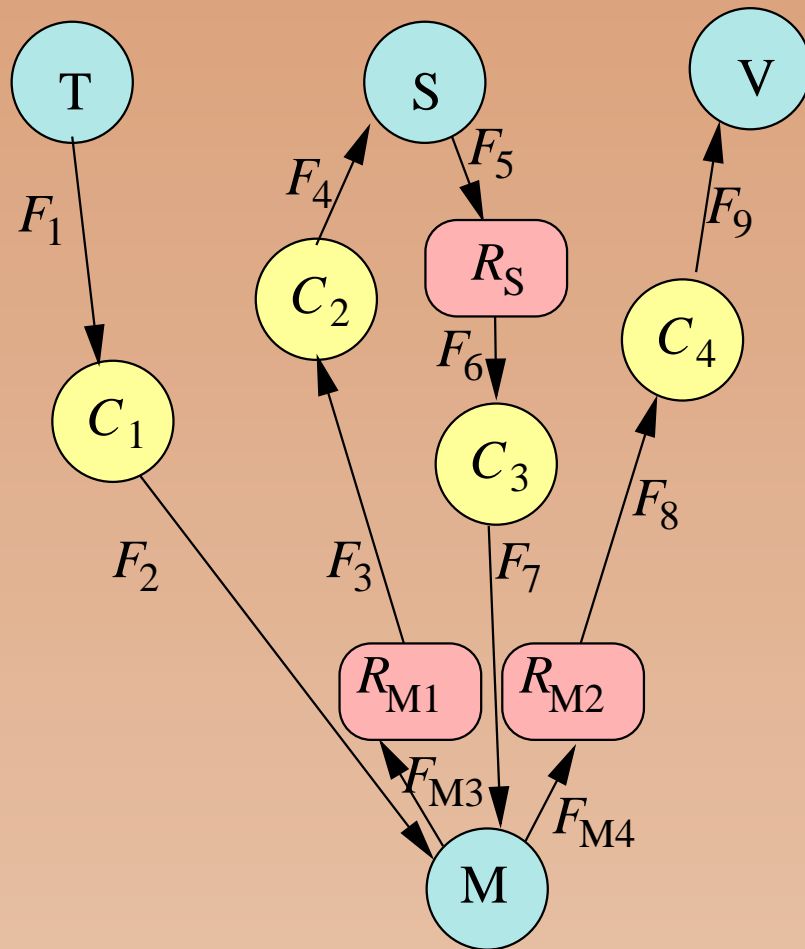
The flows between memory and V:

$$F_8 \sim (S_{\text{buffer}}, \rho_t)$$

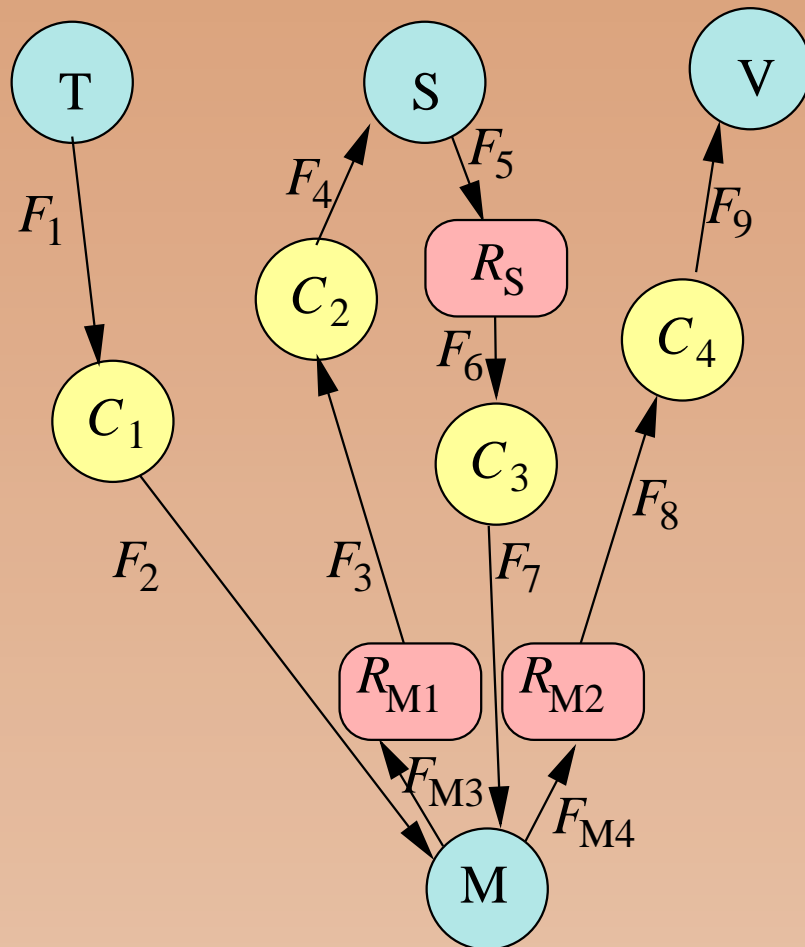
$$C_4 : (\rho, D_4)$$

$$F_9 \sim (S_{\text{buffer}} + \rho_t D_4, \rho_t)$$

## MPEG Encoding Case Study - cont'd



## MPEG Encoding Case Study - cont'd



End to end delay:

$$\begin{aligned}
 D_{\text{total}} = & D_1 + D_{\text{mux}} + D_{M'} \\
 & + D_{RM1} + D_2 + D_S + D_{RS} + D_3 \\
 & + D_{\text{mux}} + D_{M'} + D_{RM2} + D_4
 \end{aligned}$$

The flow at V:

$$F_{T \rightarrow V} \sim (0 + \rho_t D_{\text{total}}, \rho_t)$$

## Modeling with Regulated Flows

- Interconnect:
  - ★ Model each channel by available bandwidth and maximum delay variation;
  - ★ Model each node in the interconnect as an arbiter;
- Model read request, write acknowledge as separate flows;
- Model synchronization as separate flows;
- A simple generalization of  $(\sigma, \rho)$  flows is

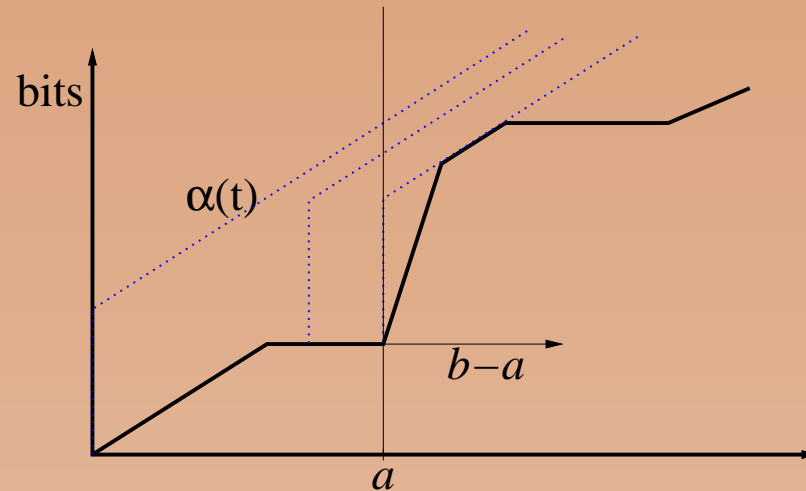
$$F \sim \min(\sigma_i, \rho_i), i > 0$$

$$F(b) - F(a) \leq \min_i(\sigma_i + \rho_i(b - a))$$

- Good analysis depends on good element models;



## Network Calculus - Arrival Curves



Given a monotonically increasing function  $\alpha$ , defined for  $t \geq 0$ ,  $\alpha$  is an arrival curve for flow  $F$  if for all  $0 \leq a \leq b$ :

$$F(b) - F(a) \leq \alpha(b - a)$$



## Network Calculus - Min-Plus Convolution

Given two monotonically increasing functions  $f$  and  $g$ . The min-plus convolution of  $f$  and  $g$  is the function

$$(f \otimes g)(t) = \inf_{0 \leq s \leq t} (f(t - s) + g(s))$$



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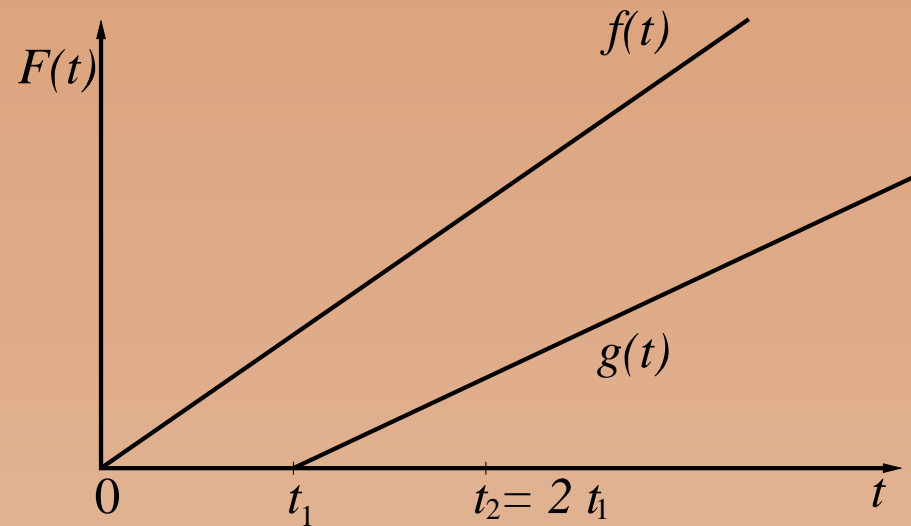
and

$$F \leq \alpha \otimes \alpha$$

with  $\alpha \otimes \alpha$  being the best bound that we can find based on information of  $\alpha$ .



# Convolution Example 1



$$f(t) = c_1 t$$

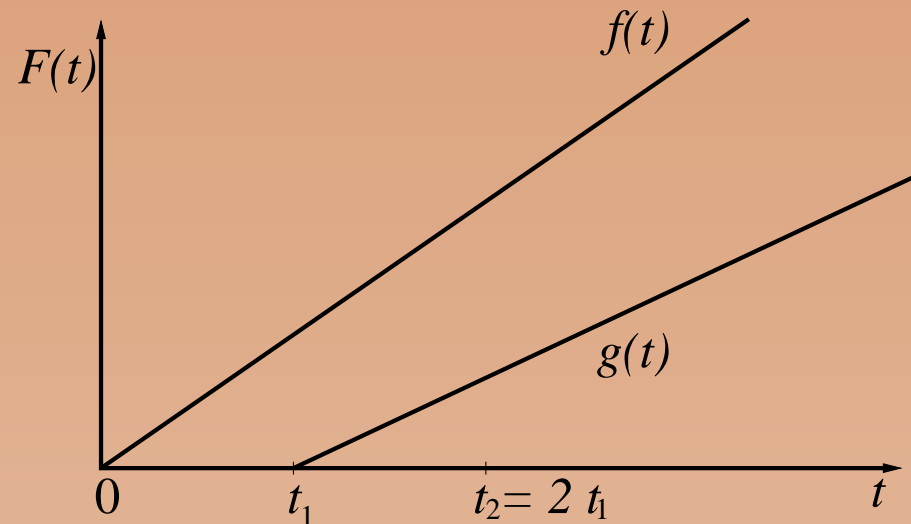
$$g(t) = \begin{cases} c_2(t - c_3) & \text{for } t > c_3 \\ 0 & \text{otherwise} \end{cases}$$

$$h = f \otimes g$$

$$c_2 < c_1$$

$$t_2 = 2t_1 = 2c_3$$

## Convolution Example 1



$$h(0) = \min(f(0) + g(0)) = 0$$

$$f(t) = c_1 t$$

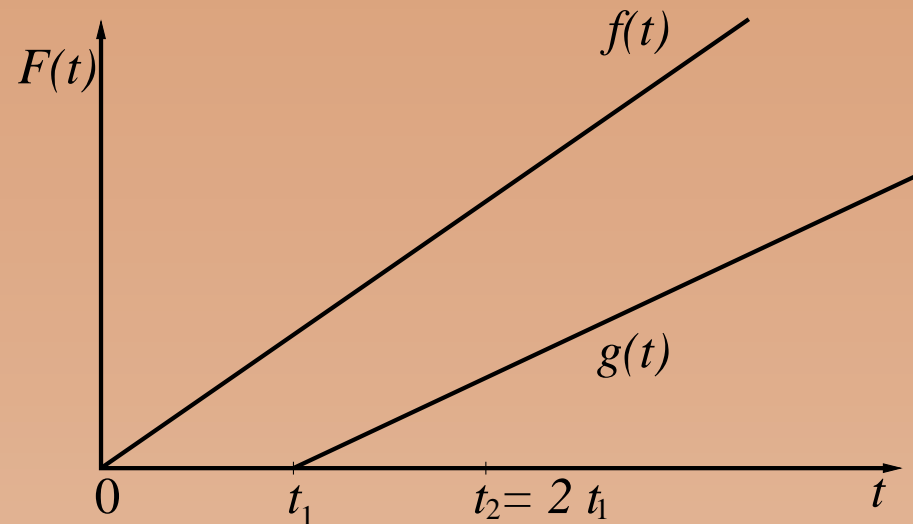
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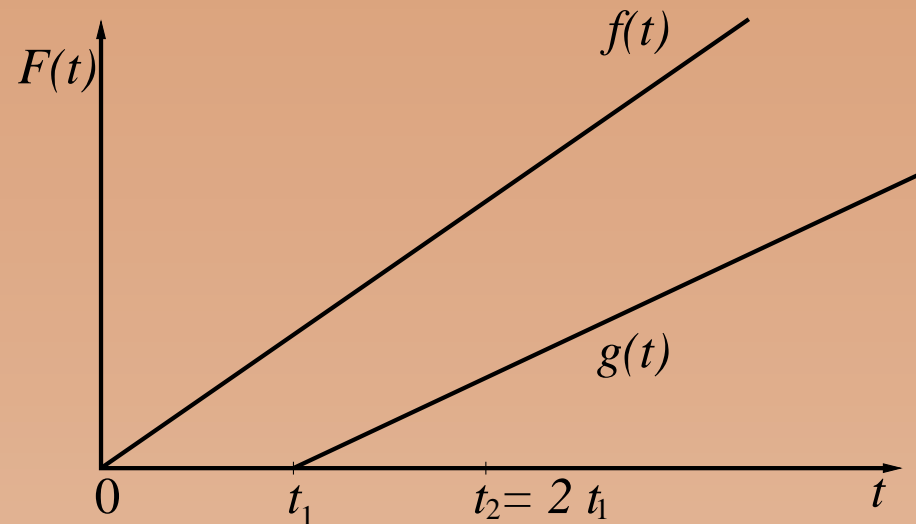
$$t_2 = 2t_1 = 2c_3$$

$$h(0) = \min(f(0) + g(0)) = 0$$

$$h(t_1) = \min(f(t_1) + g(0), f(0) + g(t_1)) = \min(c_1 t_1, 0) = 0$$



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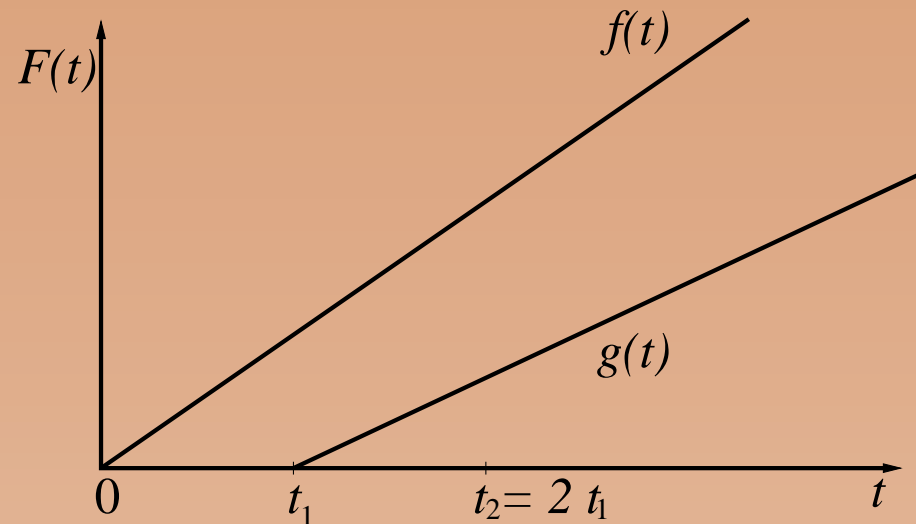
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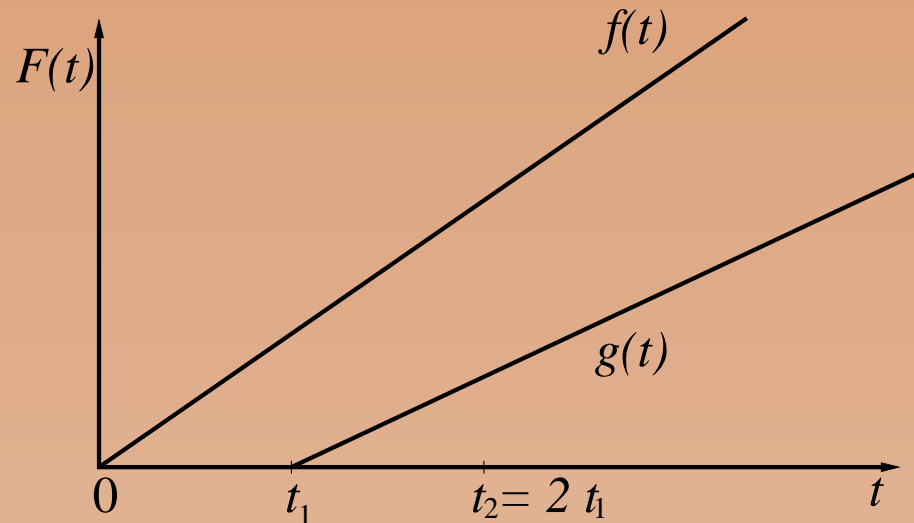
$$h(t_2) = \min(f(t_2) + g(0), f(t_1) + g(t_2 - t_1), f(0) + g(t_2))$$

$$= \min(t_2 c_1, t_1 c_1, c_2(t_2 - c_3)) = \min(2c_3 c_1, c_3 c_1, c_2 c_3) = c_2 c_3 = g(t_2)$$





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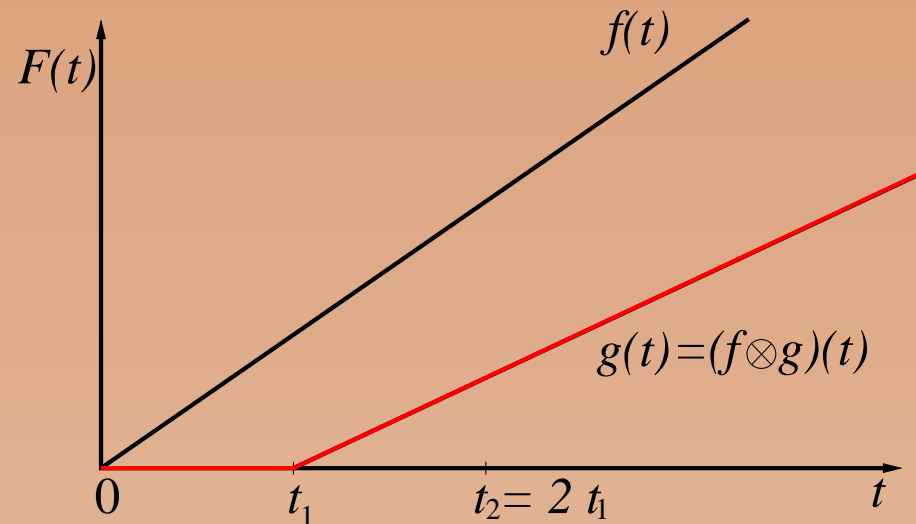
$$h(t_1) = \min(f(t_1) + g(0), f(0) + g(t_1)) = \min(c_1 t_1, 0) = 0$$

$$\begin{aligned} h(t_2) &= \min(f(t_2) + g(0), f(t_1) + g(t_2 - t_1), f(0) + g(t_2)) \\ &= \min(t_2 c_1, t_1 c_1, c_2(t_2 - c_3)) = \min(2c_3 c_1, c_3 c_1, c_2 c_3) = c_2 c_3 = g(t_2) \end{aligned}$$

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## Convolution Example 1



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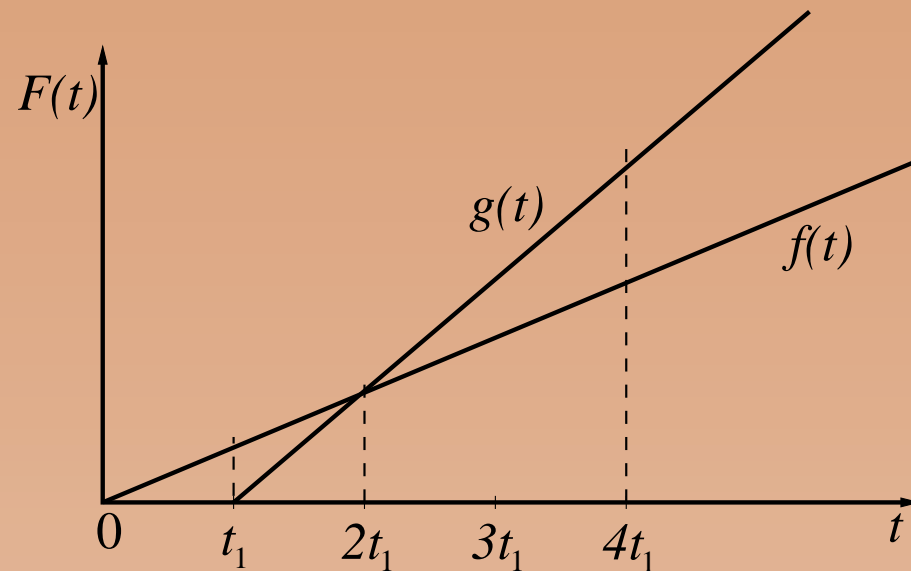
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## Convolution Example 2



$$f(t) = c_1 t$$

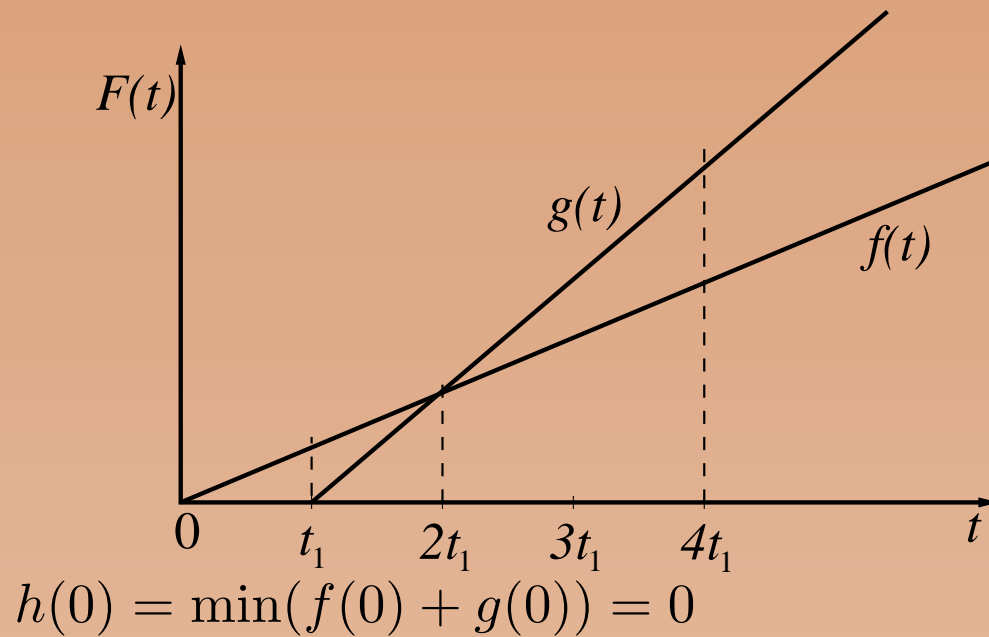
$$g(t) = \begin{cases} c_2(t - c_3) & \text{for } t > c_3 \\ 0 & \text{otherwise} \end{cases}$$

$$h = f \otimes g$$

$$c_2 > c_1$$

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## Convolution Example 2



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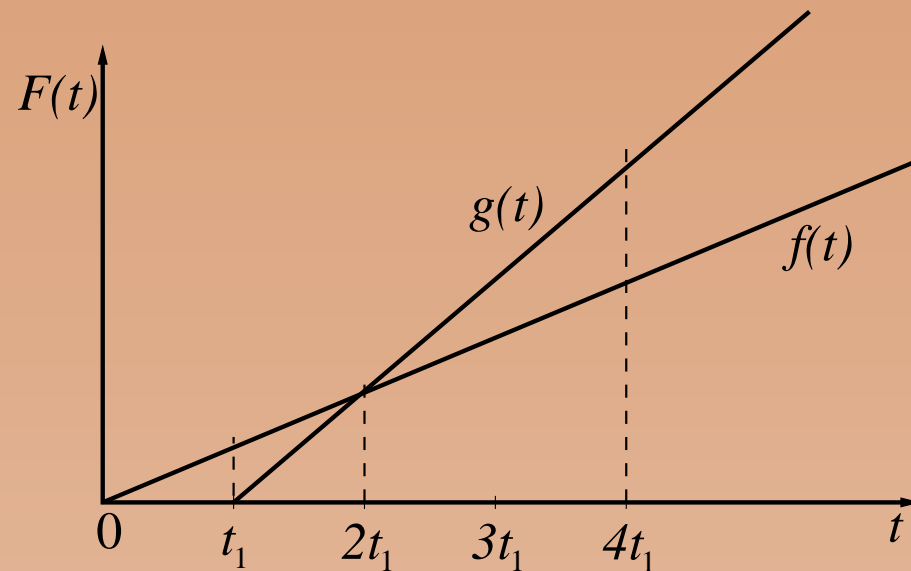
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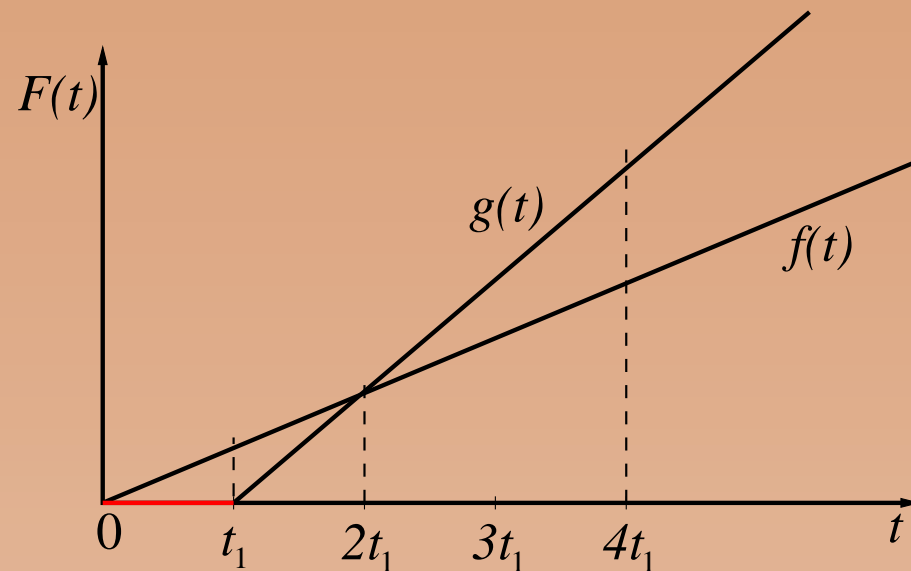
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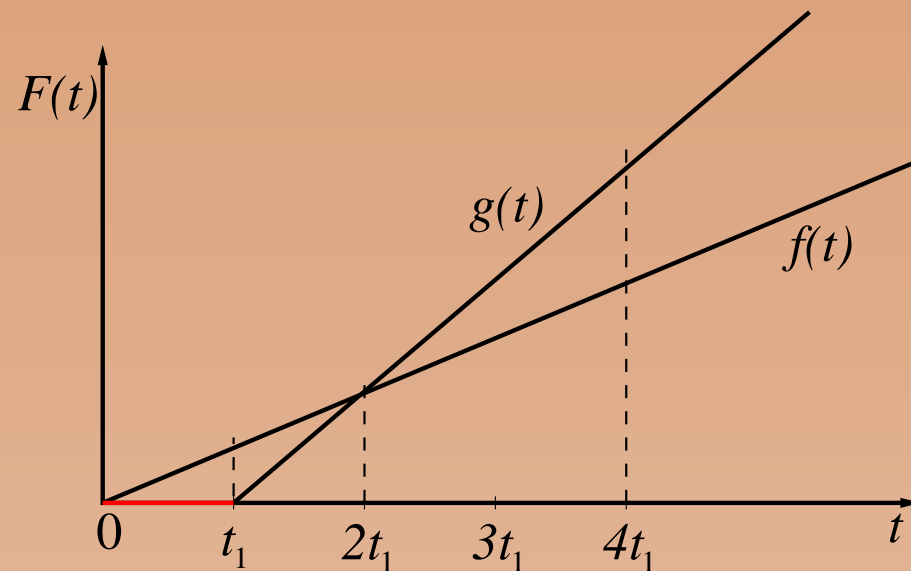
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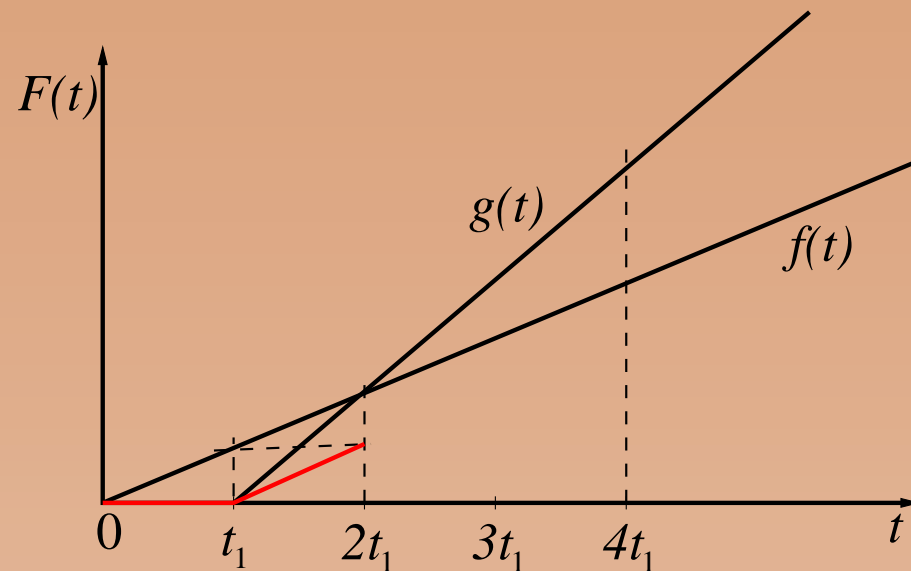
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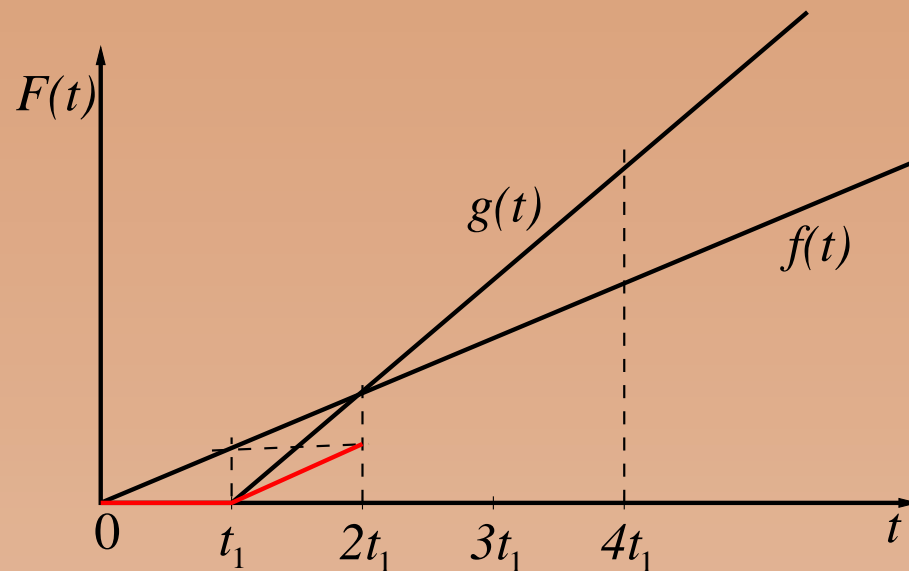
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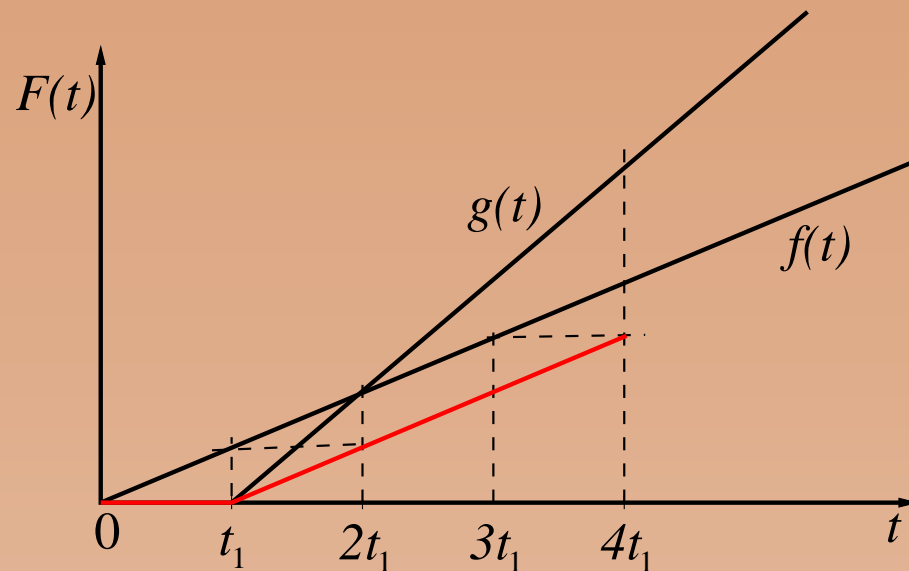
$$h(t_1) = \min(f(t_1) + g(0), f(0) + g(t_1)) = \min(c_1 t_1, 0) = 0$$

$$h(2t_1) = \min(f(2t_1) + g(0), f(t_1) + g(t_1), f(0) + g(2t_1)) = \min(2t_1 c_1, t_1 c_1, c_2 t_1) = t_1 c_1$$

$$\begin{aligned} h(4t_1) &= \min(f(4t_1) + g(0), f(3t_1) + g(t_1), f(2t_1) + g(2t_1), f(t_1) + g(3t_1), f(0) + g(4t_1)) \\ &= \min(4c_1 t_1, 3t_1 c_1, 4c_1 t_1, c_1 t_1 + 2c_2 t_1, 3c_2 t_1) = 3t_1 c_1 \end{aligned}$$



## Convolution Example 2



$$f(t) = c_1 t$$

$$g(t) = \begin{cases} c_2(t - c_3) & \text{for } t > c_3 \\ 0 & \text{otherwise} \end{cases}$$

$$h = f \otimes g$$

$$c_2 > c_1$$

$$t_1 = c_3$$

$$h(0) = \min(f(0) + g(0)) = 0$$

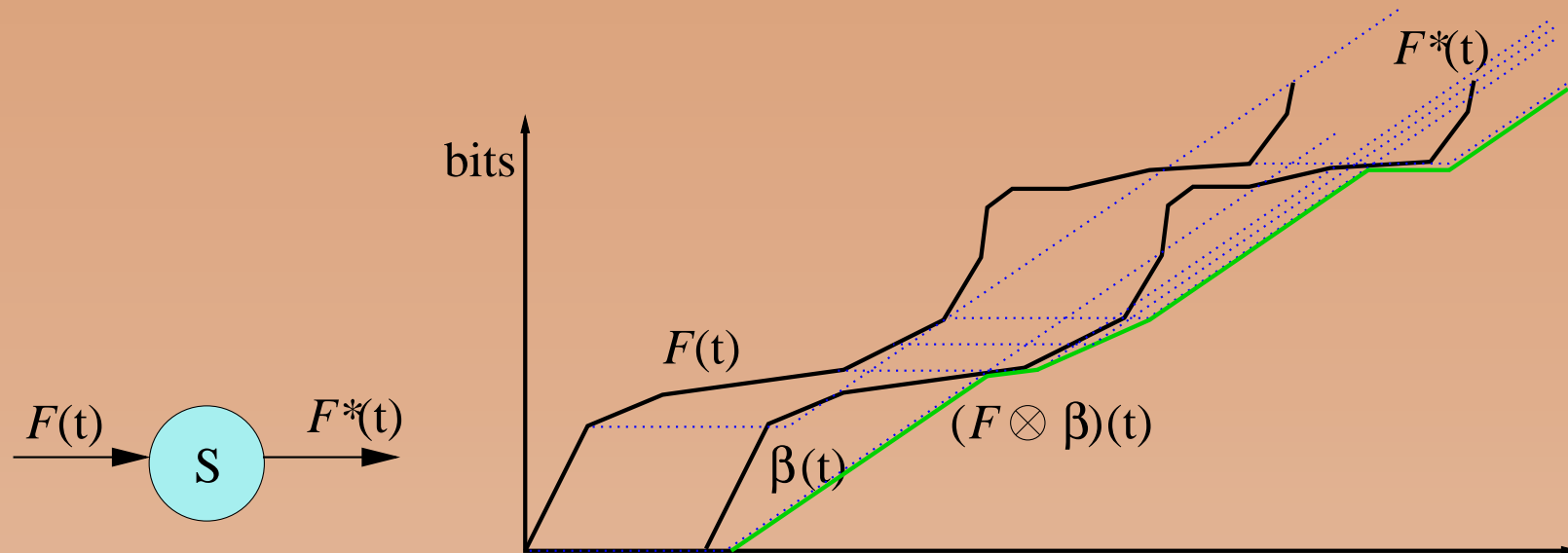
$$h(t_1) = \min(f(t_1) + g(0), f(0) + g(t_1)) = \min(c_1 t_1, 0) = 0$$

$$h(2t_1) = \min(f(2t_1) + g(0), f(t_1) + g(t_1), f(0) + g(2t_1)) = \min(2t_1 c_1, t_1 c_1, c_2 t_1) = t_1 c_1$$

$$\begin{aligned} h(4t_1) &= \min(f(4t_1) + g(0), f(3t_1) + g(t_1), f(2t_1) + g(2t_1), f(t_1) + g(3t_1), f(0) + g(4t_1)) \\ &= \min(4c_1 t_1, 3t_1 c_1, 4c_1 t_1, c_1 t_1 + 2c_2 t_1, 3c_2 t_1) = 3t_1 c_1 \end{aligned}$$



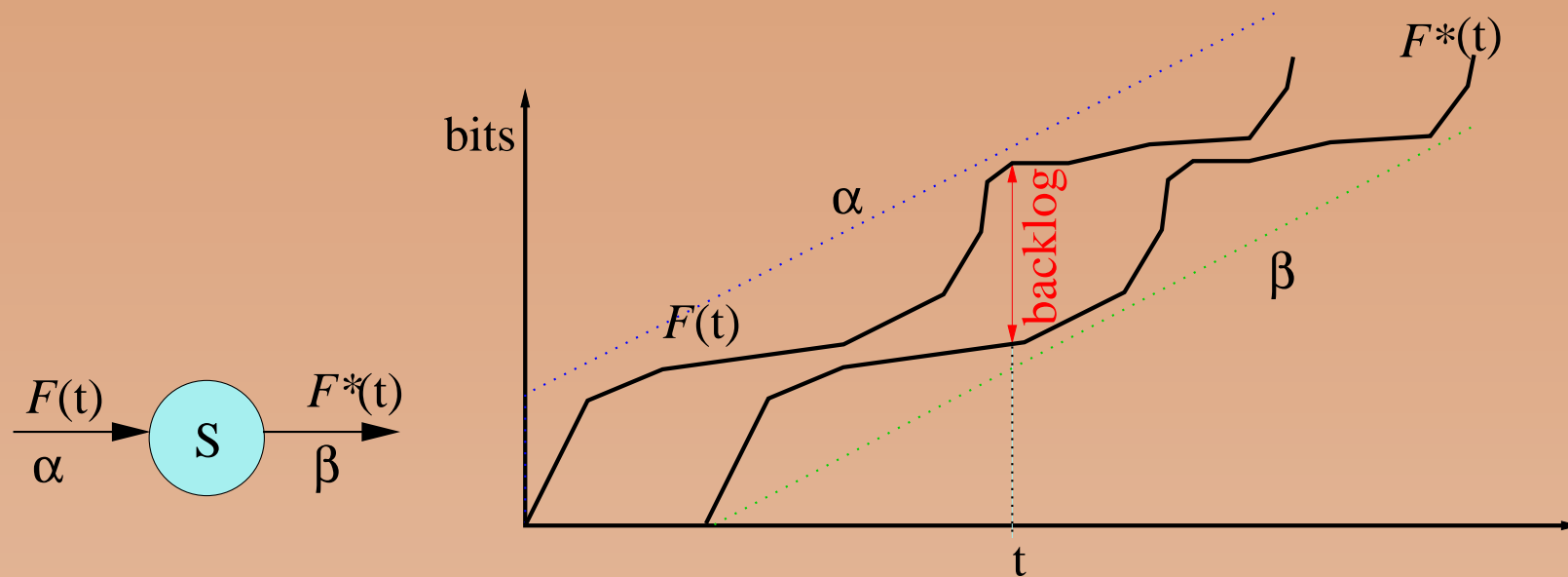
## Network Calculus - Service Curves



Given a system  $S$  with an input flow  $F$  and an output flow  $F^*$ .  $S$  offers the flow a service curve  $\beta$  if and only if  $\beta$  is a monotonically increasing function and  $F^* \geq F \otimes \beta$  which means that

$$F^*(t) \geq \inf_{s \leq t} (F(t) + \beta(t - s))$$

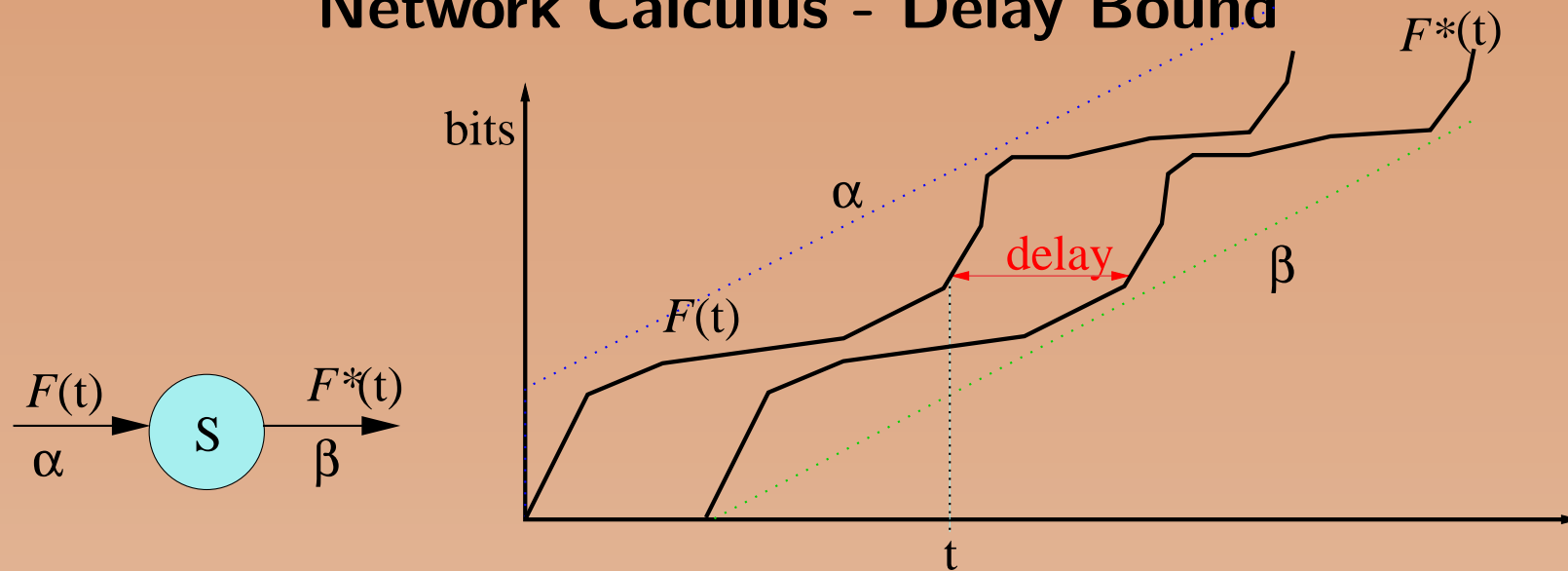
## Network Calculus - Backlog Bound



Given a flow  $F$  constrained by arrival curve  $\alpha$  and a system offering a service curve  $\beta$ , the backlog  $F(t) - F^*(t)$  for all  $t$  satisfies

$$F(t) - F^*(t) \leq \sup_{s \geq 0} (\alpha(s) - \beta(s))$$

## Network Calculus - Delay Bound



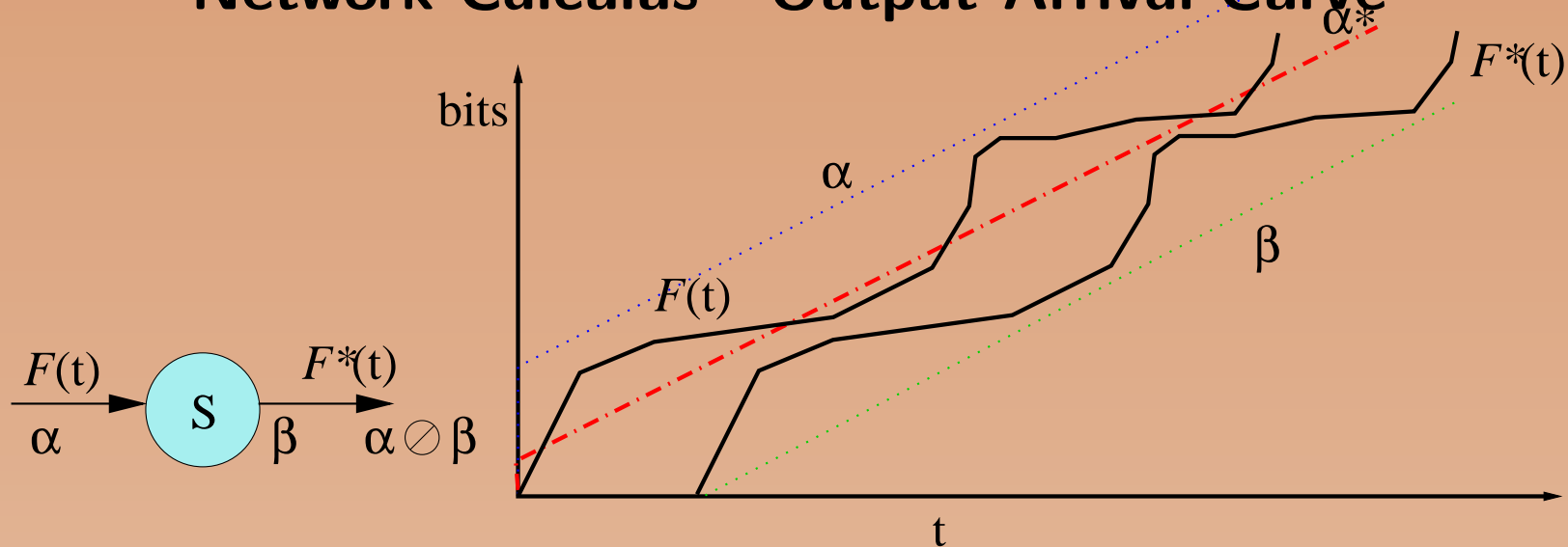
Given a flow  $F$  constrained by arrival curve  $\alpha$  and a system offering a service curve  $\beta$ , the delay  $d(t)$  at time  $t$  is

$$d(t) = \inf(\tau \geq 0 : F(t) \leq F^*(t + \tau)).$$

It satisfies

$$d(t) \leq h(\alpha, \beta) = \sup_{t \geq 0} (\inf(\tau \geq 0 : \alpha(t) \leq \beta(t + \tau)))$$

## Network Calculus - Output Arrival Curve

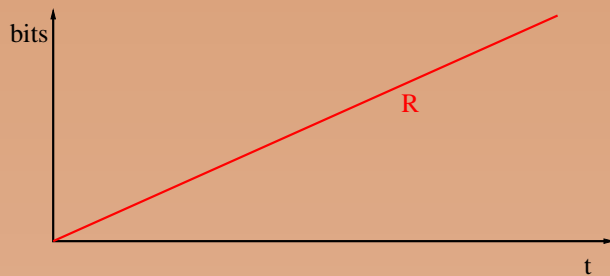


Given a flow  $F$  constrained by arrival curve  $\alpha$  and a system offering a service curve  $\beta$ , the output flow  $F^*$  is constrained by the arrival curve  $\alpha^*$

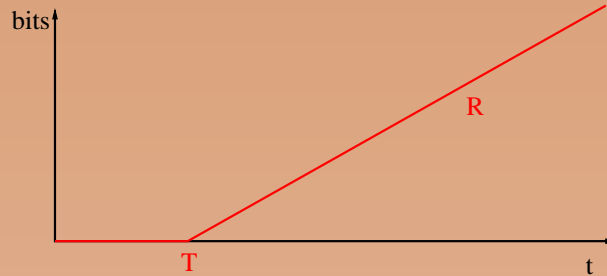
$$\alpha^* = \alpha \circledast \beta.$$

$$(\alpha \circledast \beta)(t) = \sup_{s \geq 0} (\alpha(t + s) - \beta(s))$$

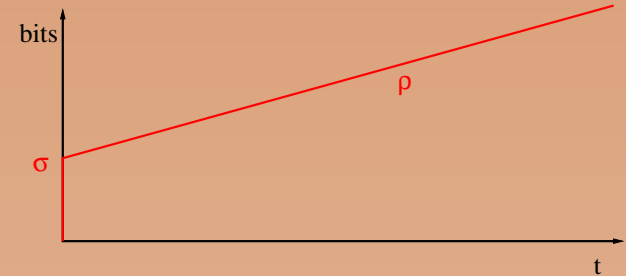
# Network Calculus - Useful Functions



Peak rate function:  
 $\lambda_R(t) = Rt$

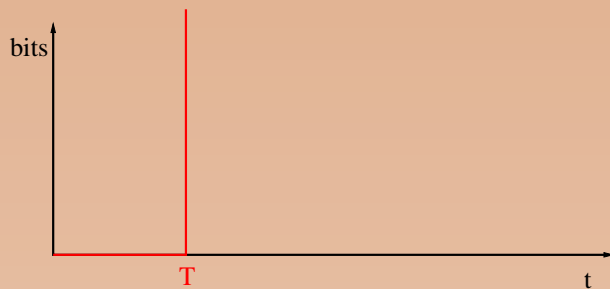


Rate latency function:  
 $\beta_{R,T}(t) = R[t - T]^+$



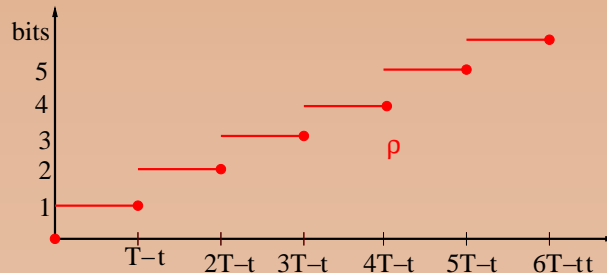
Affine function:  

$$\gamma_{\sigma,\rho}(t) = \begin{cases} 0 & \text{for } t = 0 \\ \sigma + \rho t & \text{for } t > 0 \end{cases}$$



Burst-delay function:  

$$\delta_T(t) = \begin{cases} 0 & \text{for } t \leq T \\ \infty & \text{for } t > T \end{cases}$$



Staircase function:  
 $v_{T,\tau}(t) = \lceil (t + \tau) / T \rceil$

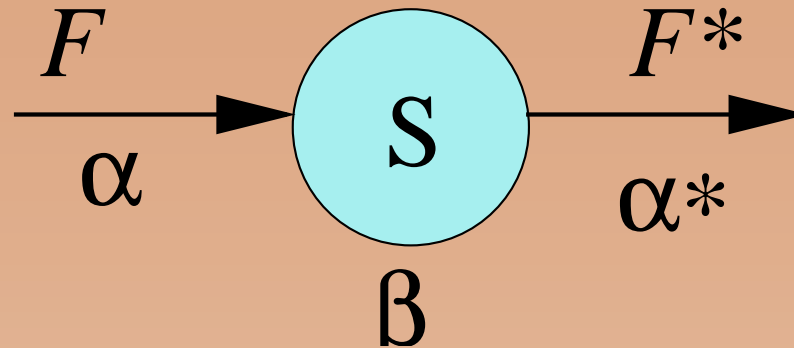


Step function:  

$$u_T(t) = \begin{cases} 0 & \text{for } t \leq T \\ 1 & \text{for } t > T \end{cases}$$



## Network Calculus - Latency Rate Server



$$\beta = \beta_{R,T}$$

$$\alpha = \gamma_{\sigma,\rho}(t)$$

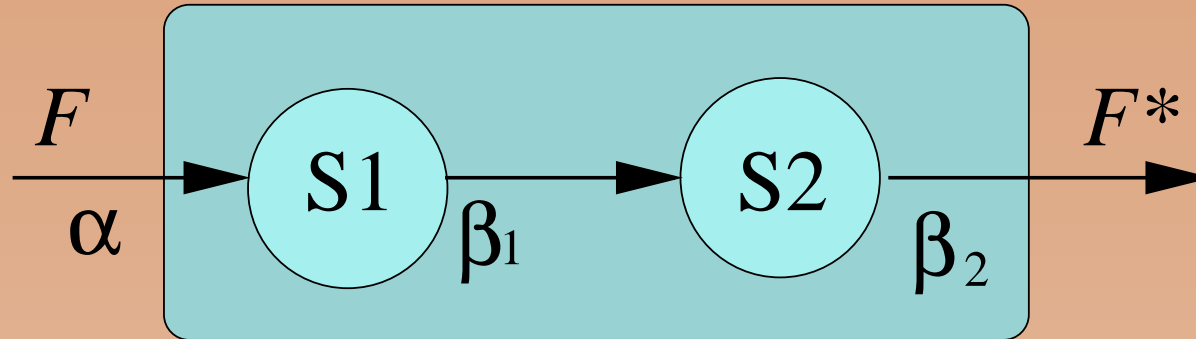
$$D = \frac{\sigma}{R} + T$$

$$\alpha^*(t) = \sigma + \rho(t + T) = \sigma + \rho T + \rho t$$



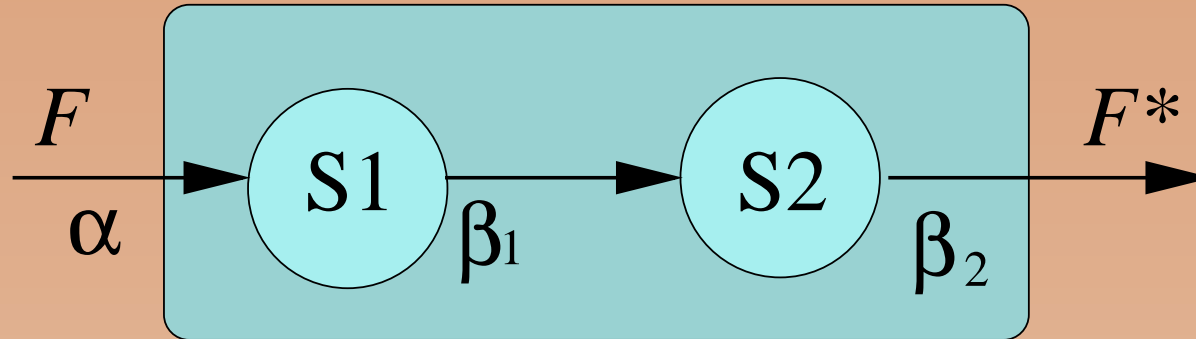
## Network Calculus - Concatenation of Nodes

$$S / \beta_1 \otimes \beta_2$$



## Network Calculus - Concatenation of Nodes

$$S / \beta_1 \otimes \beta_2$$



Example:

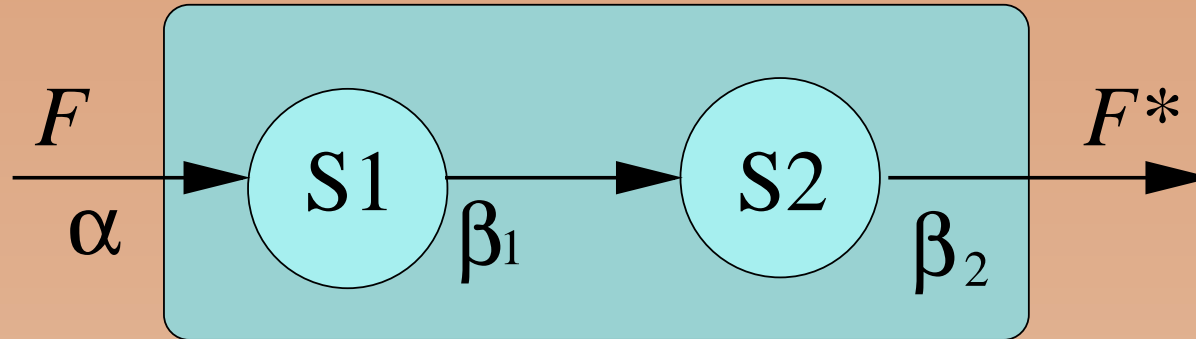
$$\beta_1 = \beta_{R_1, T_1}$$

$$\beta_2 = \beta_{R_2, T_2}$$

$$\beta_{R_1, T_1} \otimes \beta_{R_2, T_2} = \beta_{\min(R_1, R_2), T_1 + T_2}$$

## Network Calculus - Concatenation of Nodes

$$S / \beta_1 \otimes \beta_2$$



Example:

$$\beta_1 = \beta_{R_1, T_1}$$

$$\beta_2 = \beta_{R_2, T_2}$$

$$\beta_{R_1, T_1} \otimes \beta_{R_2, T_2} = \beta_{\min(R_1, R_2), T_1 + T_2}$$

Useful properties:

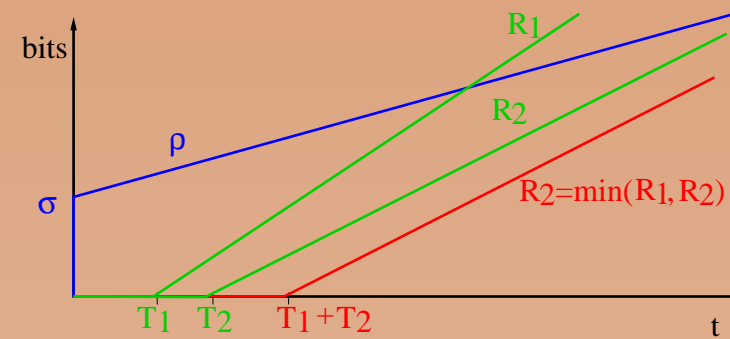
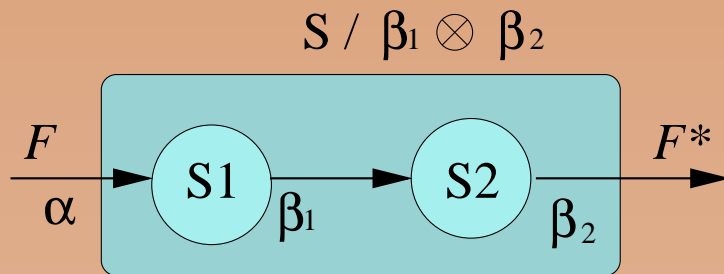
$$f \otimes g = g \otimes f$$

$$(f \otimes g) \otimes h = f \otimes (g \otimes h)$$

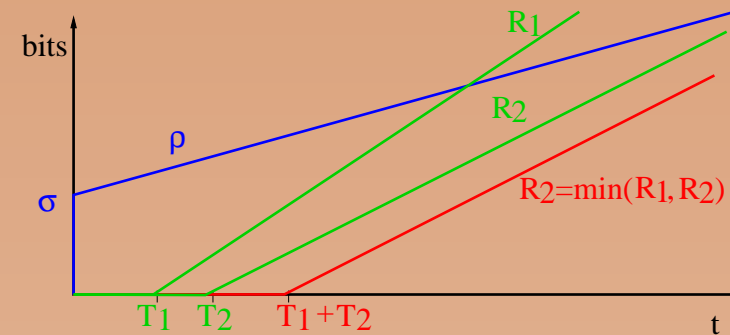
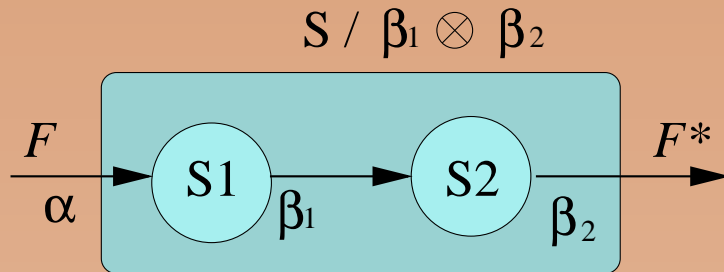
$$(f + c) \otimes g = (f \otimes g) + c \text{ for any constant } c \in \mathbb{R}$$



## Network Calculus - Pay Bursts Only Once



## Network Calculus - Pay Bursts Only Once

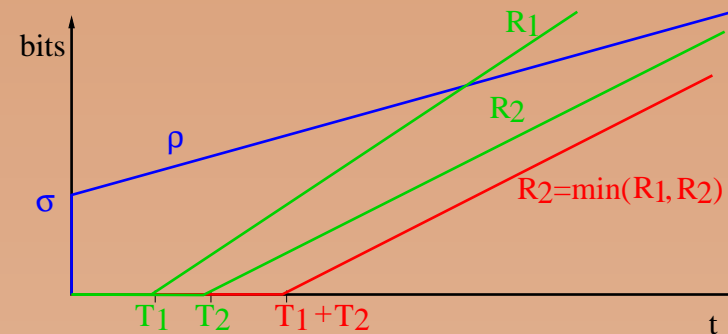
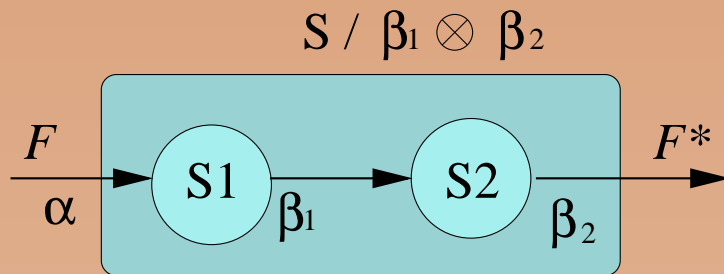


$$\alpha = \gamma_{\rho, \sigma}$$

$$\beta_1 = \beta_{R_1, T_1} = R_1 \max(0, t - T_1)$$

$$\beta_2 = \beta_{R_2, T_2} = R_2 \max(0, t - T_2)$$

## Network Calculus - Pay Bursts Only Once



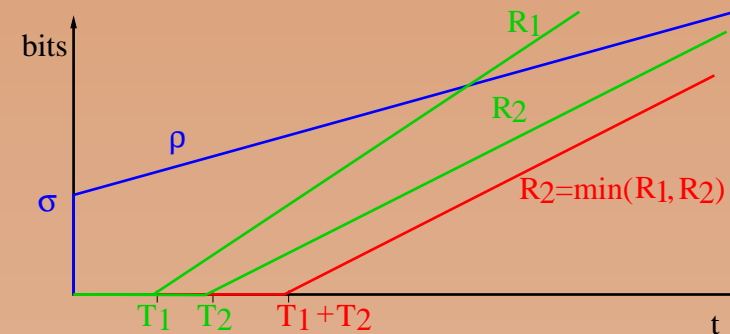
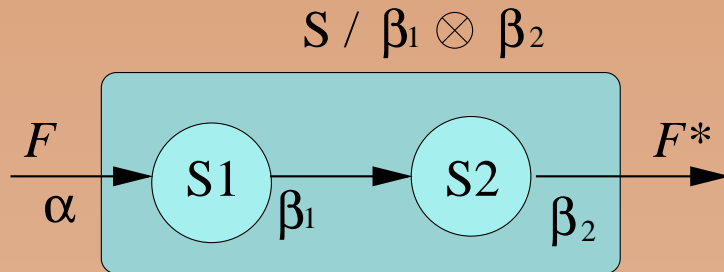
$$\alpha = \gamma_{\rho, \sigma}$$

$$\beta_1 = \beta_{R_1, T_1} = R_1 \max(0, t - T_1)$$

$$\beta_2 = \beta_{R_2, T_2} = R_2 \max(0, t - T_2)$$

$$\beta_{R_1, T_1} \otimes \beta_{R_2, T_2} = \beta_{\min(R_1, R_2), T_1 + T_2} = \min(R_1, R_2) \max(0, t - (T_1 + T_2))$$

## Network Calculus - Pay Bursts Only Once



$$\alpha = \gamma_{\rho, \sigma}$$

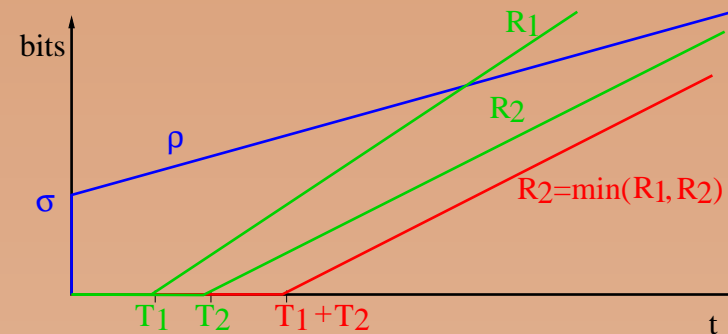
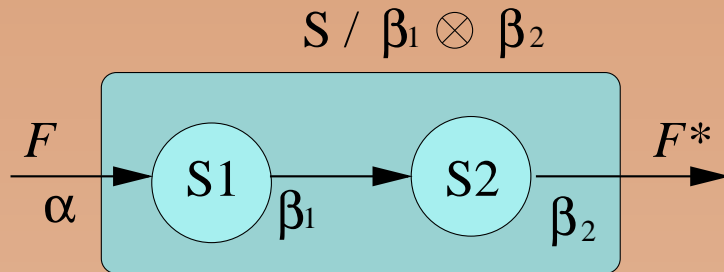
$$\beta_1 = \beta_{R_1, T_1} = R_1 \max(0, t - T_1)$$

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$$\beta_{R_1, T_1} \otimes \beta_{R_2, T_2} = \beta_{\min(R_1, R_2), T_1 + T_2} = \min(R_1, R_2) \max(0, t - (T_1 + T_2))$$

$$D_1 + D_2 = \frac{\sigma}{R_1} + \frac{\sigma}{R_2} + \frac{\rho T_1}{R_2} + T_1 + T_2$$

## Network Calculus - Pay Bursts Only Once



$$\alpha = \gamma_{\rho, \sigma}$$

$$\beta_1 = \beta_{R_1, T_1} = R_1 \max(0, t - T_1)$$

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$$\beta_{R_1, T_1} \otimes \beta_{R_2, T_2} = \beta_{\min(R_1, R_2), T_1 + T_2} = \min(R_1, R_2) \max(0, t - (T_1 + T_2))$$

$$D_1 + D_2 = \frac{\sigma}{R_1} + \frac{\sigma}{R_2} + \frac{\rho T_1}{R_2} + T_1 + T_2$$

$$D_S = \frac{\sigma}{\min(R_1, R_2)} + T_1 + T_2$$





# Summary

- Organizational structure: network interface, switch, link
- Communication performance: bandwidth, unloaded latency, loaded latency
- Topologies: wire space and delay domination favors low dimension topologies;
- Quality of Service and flow regulation



## To Probe Further

### Classic papers:

- [Agarwal, 1991] Agarwal, A. (1991). Limit on interconnection performance. *IEEE Transactions on Parallel and Distributed Systems*, 4(6):613–624.
- [Dally, 1990] Dally, W. J. (1990). Performance analysis of k-ary n-cube interconnection networks. *IEEE Transactions on Computers*, 39(6):775–785.

### Text books:

- [Duato et al., 1998] Duato, J., Yalamanchili, S., and Ni, L. (1998). *Interconnection Networks - An Engineering Approach*. Computer Society Press, Los Alamitos, California.
- [Culler et al., 1999] Culler, D. E., Singh, J. P., and Gupta, A. (1999). *Parallel Computer Architecture - A Hardware/Software Approach*. Morgan Kaufman Publishers.
- [Dally and Towels, 2004] Dally, W. J. and Towels, B. (2004). *Principles and Practices of Interconnection Networks*. Morgan Kaufman Publishers.
- [DeMicheli and Benini, 2006] DeMicheli, G. and Benini, L. (2006). *Networks on Chip*. Morgan Kaufmann.
- [Leighton, 1992] Leighton, F. T. (1992). *Introduction to Parallel Algorithms and Architectures*. Morgan Kaufmann, San Francisco.
- [LeBoudec, 2001] Jean-Yves LeBoudec, J-Y. (2001). *Network Calculus*. Springer Verlag, LCNS 2050

